The EUSO-BALLOON instrument and evaluating the performance of PDM

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PHENIICS Day







Introduction

- The TA-EUSO, SPB-EUSO, K-EUSO, mini-EUSO are a serie of telescopes of the family of JEM-EUSO telescope which have the goal to study UHECR.
- This work involve the integration of PDM camera and the flight mission of EUSO-Balloon in Timmins Canada 2014. This is the first phantfinder of JEM-EUSO with the detection chaine whole.
- The second part of this work was the post calibration and evaluation of performance of the electronic systeme.
- The third part was to develop a method for recover information of pixels with poor performance.

Space Missions for Cosmic Rays



Signature of the EAS (extensive air showers)



Project JEM-EUSO (Extreme Universe Space Observatory-Japanese Experiment Module of the International Space Station)



- Field of View (FoV) de 60° (0.75 km par pixel)
- Time resolution 2.5µs.
- Lens of Fresnel : 2,5m of diameter.
- The data acquisition rate~300kb/s

 Statistical detection of more than one order of magnitude greater than Auger.

The Focal surface tu camera (PDM) of JEM-EUSO.



The camera (PDM) of EUSO-Ballon (Panthfinder of JEM-EUSO)



Complete assembly of the camera



Data Processor (DP)

Camera PDM (Photon detection module)

MISSION EUSO-Balloon



S-Curve ?



But there are bad pixels



The red line indicates the threshold of discrimination of the analog signal

There are two problems: 1) a wide Piedestal (electronic noise) 2) a short SCurve

MAPMT deterioration is unavoidable with use. It means that sensitivity is reduced and this is evident with the backward of Scurve.



Result of calibration after flight at 950V

NOW !! Our goal is recover some information of the bad pixels.



Selected pixels:

8

0

- mean PDE of $\sim 19\%$ •
- sigma of ~3% •

16

24

32

calibrated with an accuracy better than 4%•

0.05

48

X position

40

The grounding configuration and the electronic noise

 During the flight the connection of grounding was used the spider wires as the picture.





The reason for having such a wide pedestal was due to the poor CONNECTION between gnda and gndd of ECASICs.

Connecting with low impedance the gndd and gnda electronic noise is reduced.

Trigger Philosophie

UHECR are not the only targets of detection. Also we want to detect meteors, airglow, etc. which they have different intensity and development time.

This involves dramatic changes in detector sensitivity immediately. (Microseconds).

- L0 : signal over background UV. we can adjust the gain of photomultiplier and pre-amplification of analog-signal.
- L1 : Persistence trigger in fonction of correletion between the time and spatile (events in neighboring pixels for short times ~5ms)
- L2 : Persistence trigger in large periods (>50ms).

L1 an L2 have parameters which change the sensibility of the PDM. Homogenization of the sensitivity of the focal surface is needed.

Drawing on the contributions of 2PE per pulse

This is known than there are contributions of two or more photos in a impulse signal-out of PMTs.



Drawing on the contributions of 2PE per pulse



One could in-use this relationship to find the λ of each pixel.

For pixels with weak gains, where it is impossible to see the SC for 1pe, if we know the lambda value, we could estimate counts by SC/1pe.

For this we will try use SC/2pe.

We must confirm this hypothesis with good pixels with enough data.

Post flight tests in black box with light to indentify the 2pe contribution with a complete PDM





We can observe the second 2 pe contribution.

These measurements allowed to have the relation ⁸ between 1 pe and 2 pe contributions that will be used to recover the 1 pe position (see slide 5)

The efficiency increases when the PDM runs at 1100V. Which is why the contribution of 2PE is more^{10²} evident in this case.



Proposed Fit function for the SCurve

arg (x) =(x - a_1)/ πa_2 Fit₁ (x) = a_0 Erf c (arg))

2 different functions are used : one for the 1pe region (Fit1) and another for the 2 pe region (Fit2). A fit error is calculated and represented on the plots bellow. A chi2 square method is being developped.

Fit₂ (x) = a_5 (a_3 x + a_4)

 $Fit(x) = Fit_1(x) + Fit_2(x)$



Curve linearity counts 1pe/GTU vs counts 2pe/GTU

EC-UNIT7 (asic18, asic19, asic34, asic35) light 289,729,1525, 2356, 3100 nW



count 10^3 X 2pe/GTU

Testing the complete method to recover data



We installed a mask with different transparencies in order to observe the sensitivity in different regions on MAPMT.

We illuminated the PDM uniformly

We can see that there is an improvement in image resolution.

In the bottom-center ECUNIT, the red area corresponding to a triangular free area is recovered.

Homogeneity of the other triangular regions is improved



Conclusion

- The mission of EUSO Balloon achieved its main objective, achieving sensitivity to detect background UV and simulation of EAS with laser beam.
- One of the big problems was to reduce electronic noise by integrating all components. The sujestion to change the internal settings gnd in ASIC-boards was considered, now the new PDM for the next balloon takes this configuration.
- It is possible to use the signal of 2PE for pixels with low sensitivity. This allow homogenize FS and keep operating algorithms trigger.



Electronic eficiency $\boldsymbol{\epsilon}_{e}$

-f is the fit-model function propose.

-The count estimate is $f > f(x_0)$, this mean the function evaluate in the pieestal. - θ_i are parameters of the fit function, its characterized each pixel.



Determining ϵ_{G} , we can given an estimated value of counts/GTU of an error σ . Later this would apply over the flight data.

detection of 1photon UV



Electronics workload ASIC



