

Tests expérimentaux de la Relativité Générale : sur Terre, dans notre Système Solaire et même plus loin si nécessaire

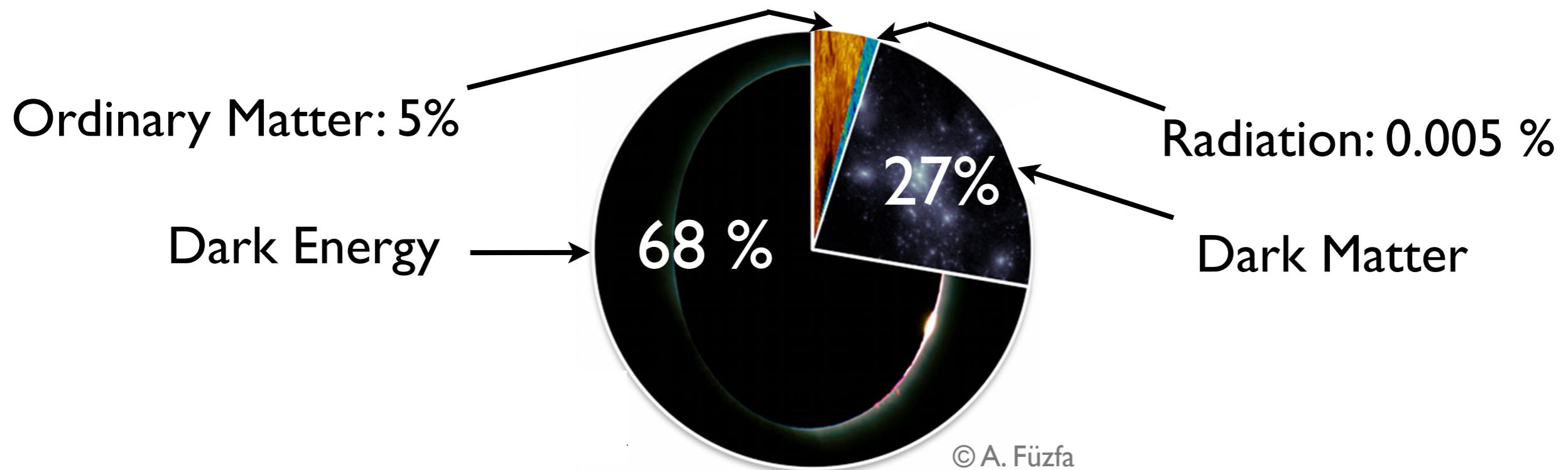
C. Le Poncin-Lafitte

SYRTE, Observatoire de Paris, PSL Research University, Sorbonne Universités,
CNRS, UPMC Univ. 06, LNE



Motivations to test GR

- **Quantum theory of gravity:**
 - GR: classic theory (not a quantum theory)
 - at high energy: quantum effects should appear
 - useful to study black holes and the Planck Era
- **Unification** of all fundamental interactions: unify Standard model of particles with gravitation
- Cosmological and galactic observations required **Dark Matter** and **Dark Energy**: not directly observed so far \Rightarrow hints of a deviation from GR ?



Where to test gravity ?

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Since Galileo Galilei, here...

Where to test gravity ?



Since Galileo Galilei, here...

and with the beginning of Deep Space
exploration in the 60th

weak field tests



Where to test gravity ?



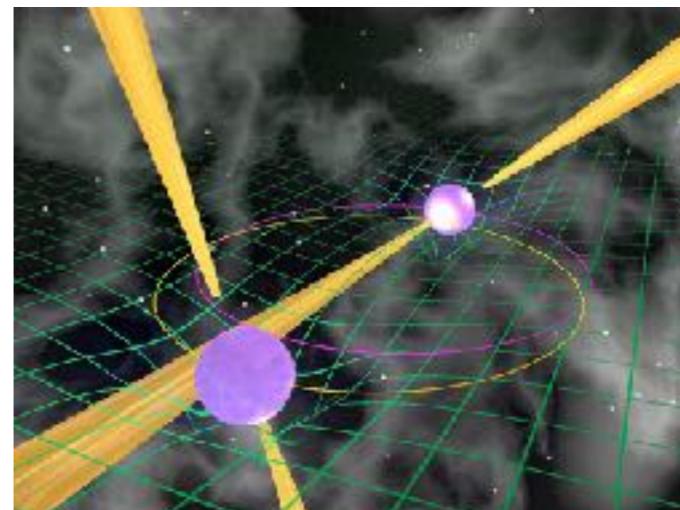
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1967 : discovery of pulsar.
=> first strong field tests



Where to test gravity ?



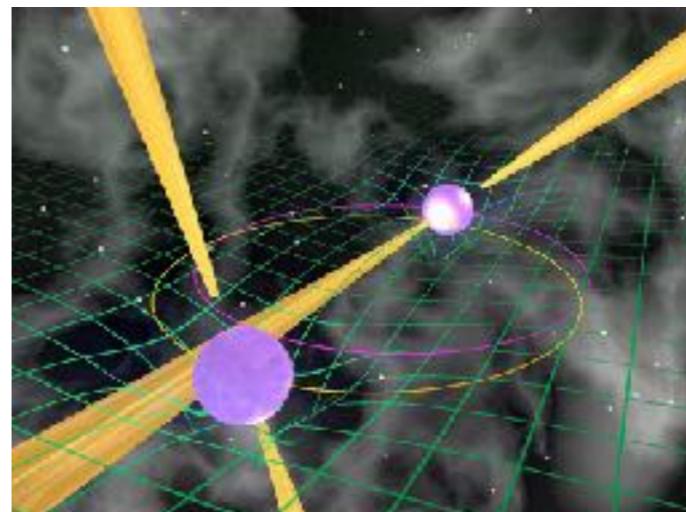
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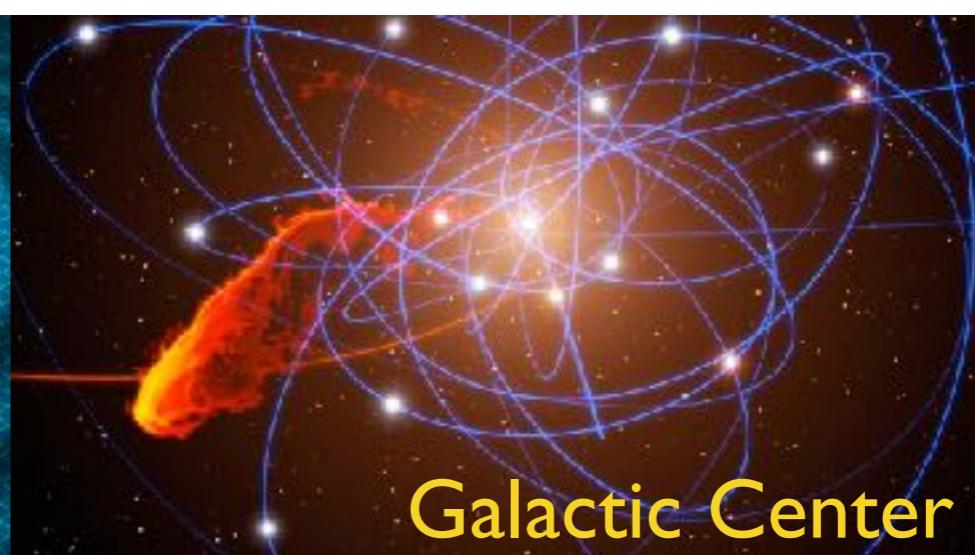
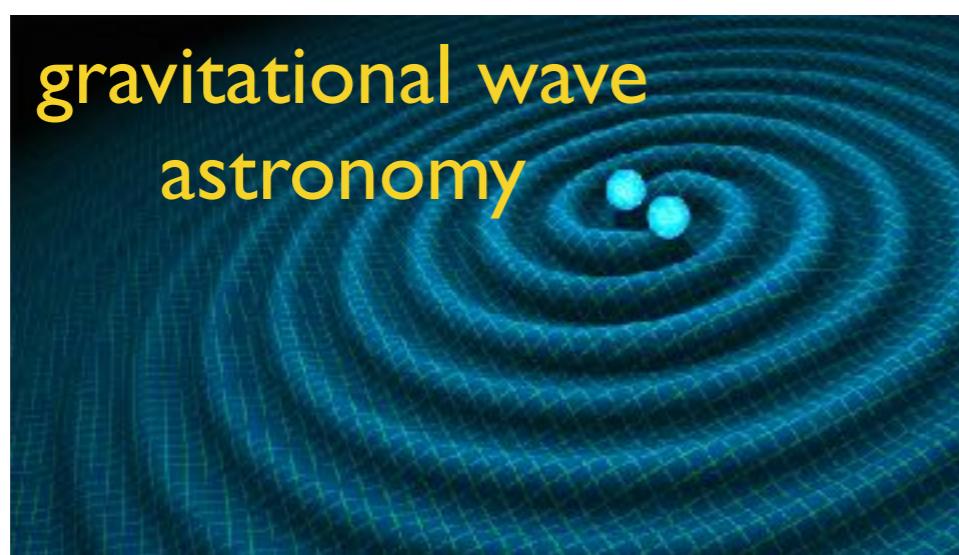
weak field tests



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and tomorrow (even already today) :



Galactic Center

Basic principles of GR

I) Equivalence Principle:

- 3 facets: Universality of free fall, Local Position/Lorentz Invariance
- very well tested (10^{-13} with Eöt-wash experiments and Lunar Laser Ranging ; 10^{-4} with grav. redshift ; no variation of constants)¹
- more accurate measurement needed: alternative (string) theories predict violation smaller² → MICROSCOPE accuracy 10^{-15}
- **Gravitation \Leftrightarrow space-time curvature** (described by a metric $g_{\mu\nu}$)
- free-falling masses follow **geodesics** of this metric and ideal clocks measure proper time

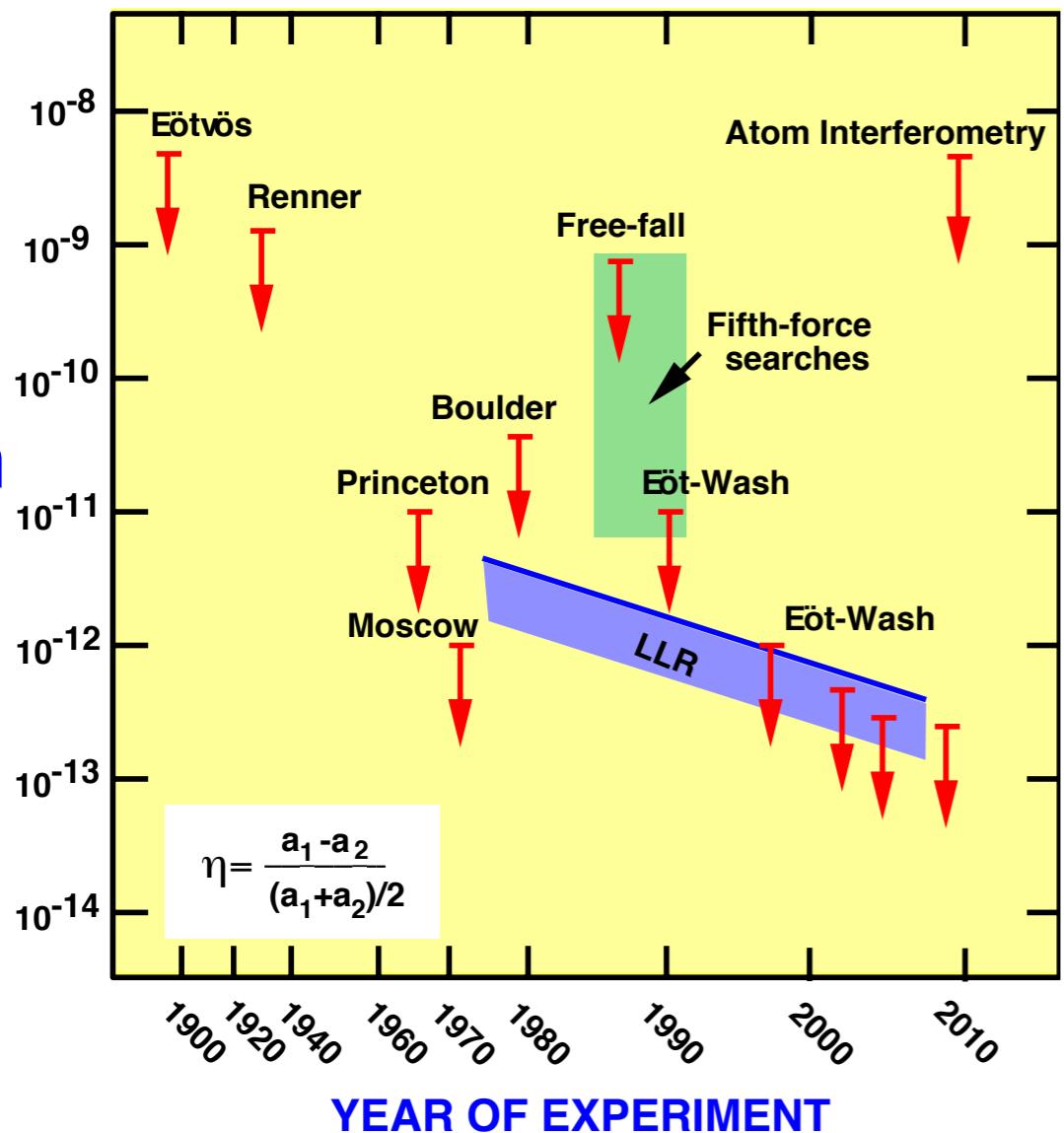
$$ds^2 = g_{\mu\nu} dx^\mu dx^\nu$$

¹ C. Will, LRR, 9, 2006

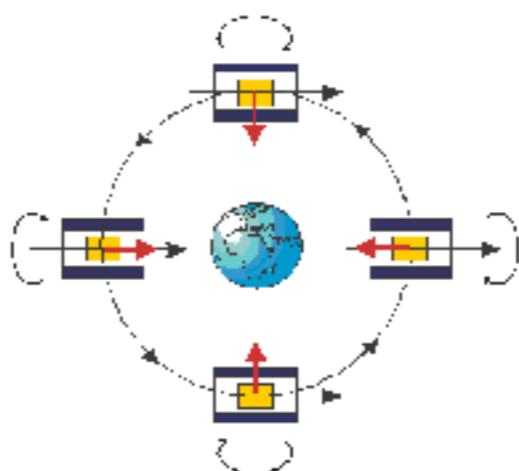
² T. Damour, CQG, 29-184001, 2012

Free Fall Experiments

TESTS OF THE WEAK EQUIVALENCE PRINCIPLE



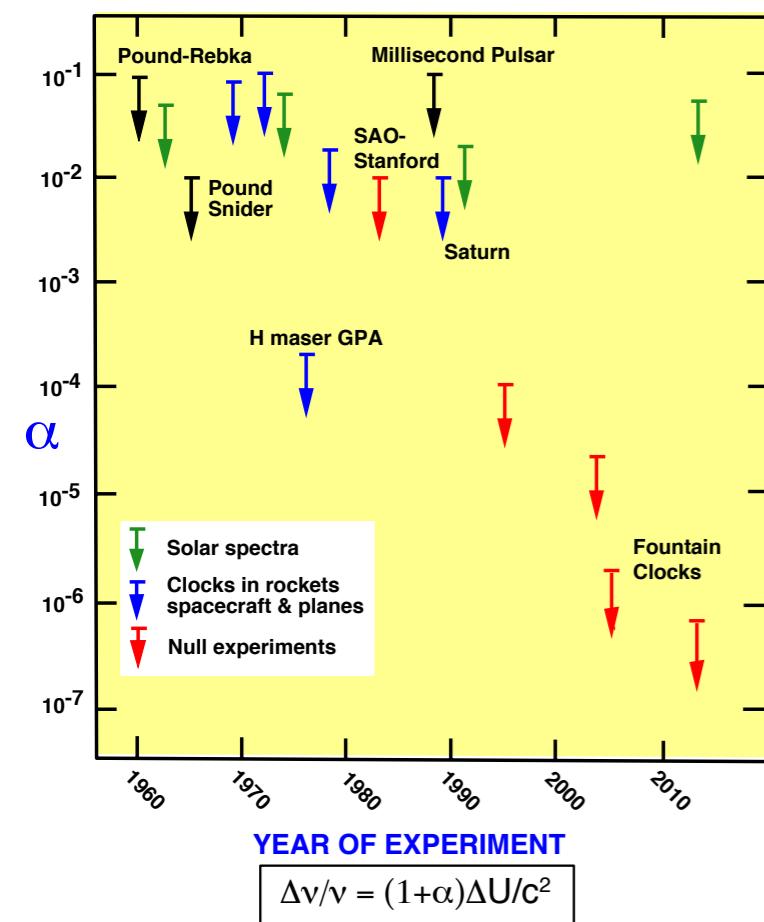
- 400 CE Ioannes Philponus: "...let fall from the same height two weights of which one is many times as heavy as the other the difference in time is a very small one"
- 1553 Giambattista Benedetti proposed equality
- 1586 Simon Stevin experiments
- 1589-92 Galileo Galilei Leaning Tower of Pisa?
- 1670-87 Newton pendulum experiments
- 1889, 1908 Baron R. von Eötvös torsion balance experiments (10^{-9})
- 1990s UW (Eöt-Wash) 10^{-13}



CNES Microscope Mission : 10^{-15}

Local Position Invariance : redshift

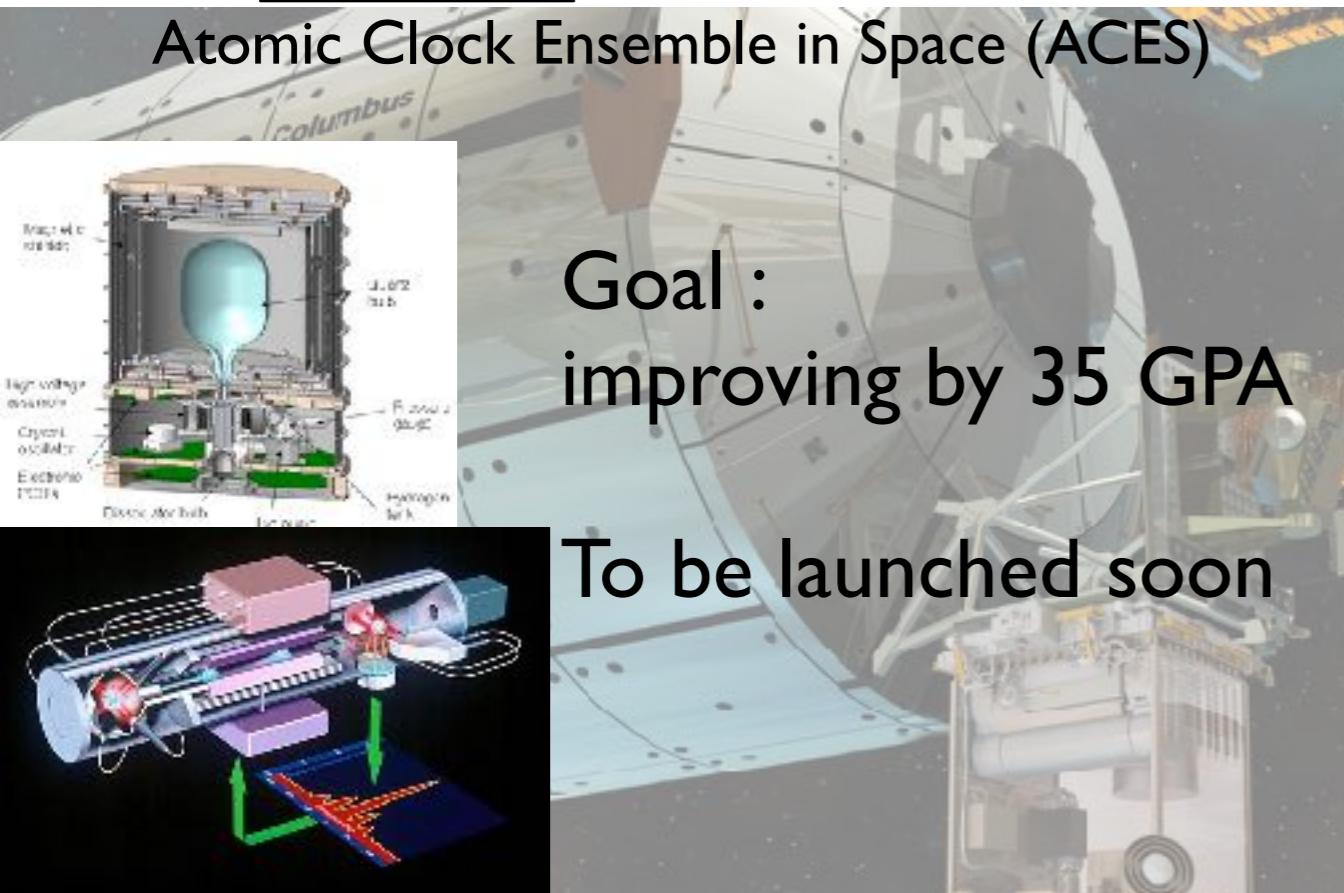
TESTS OF
LOCAL POSITION INVARIANCE



1959 : Pound & Rebka (10%)



1980 : Gravity Probe A
Vessot (0.01%)

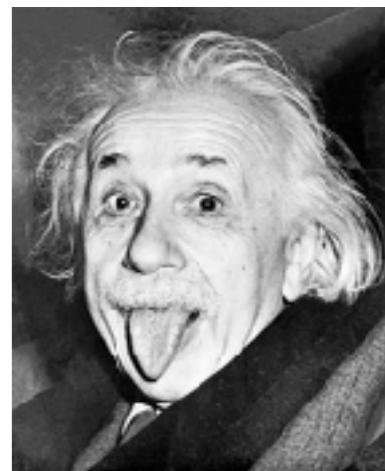


Goal :
improving by 35 GPA

To be launched soon

Launch : 1976 with Scout rocket
duration : 1h55mn
where : Wallops Island

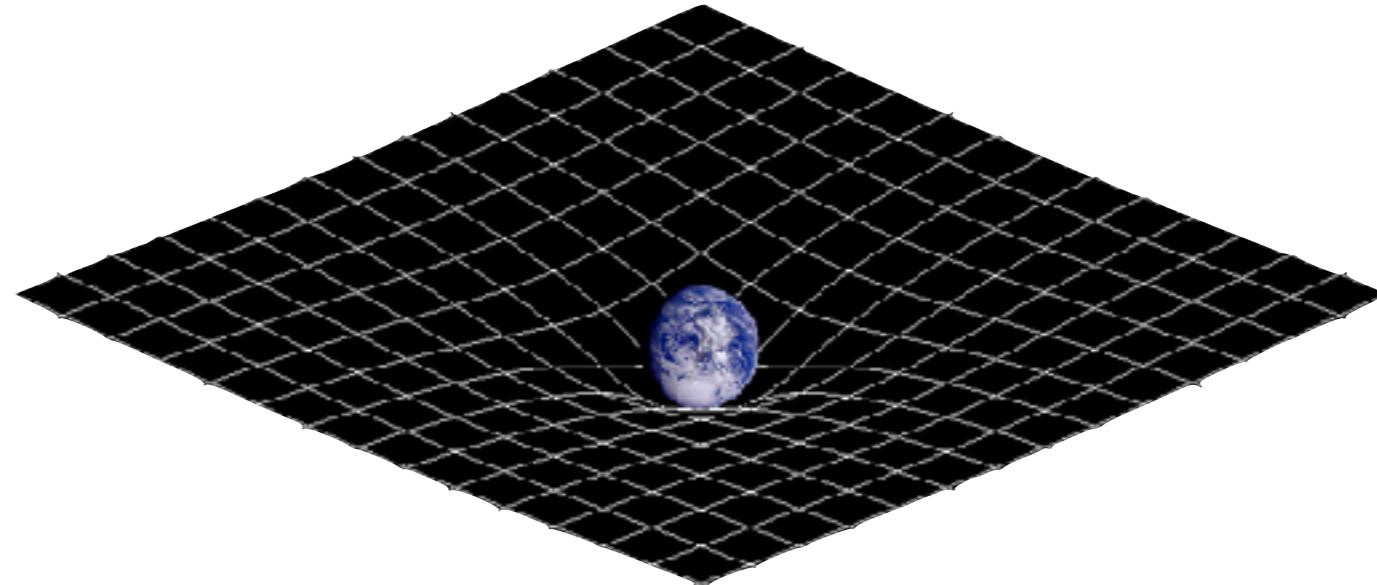
Basic principles of GR



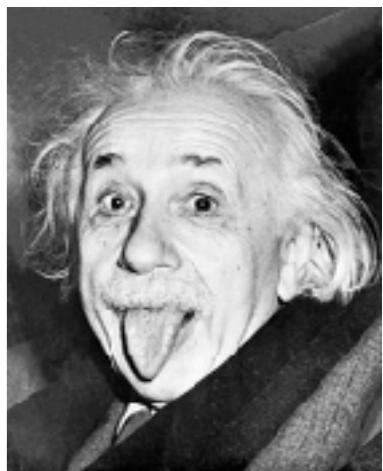
II) Field equations (determination of the metric):

- Einstein Equations:
$$R_{\mu\nu} - \frac{1}{2}Rg_{\mu\nu} = \frac{8\pi G}{c^4}T_{\mu\nu}$$

space-time curvature (metric) \Leftrightarrow matter-energy content



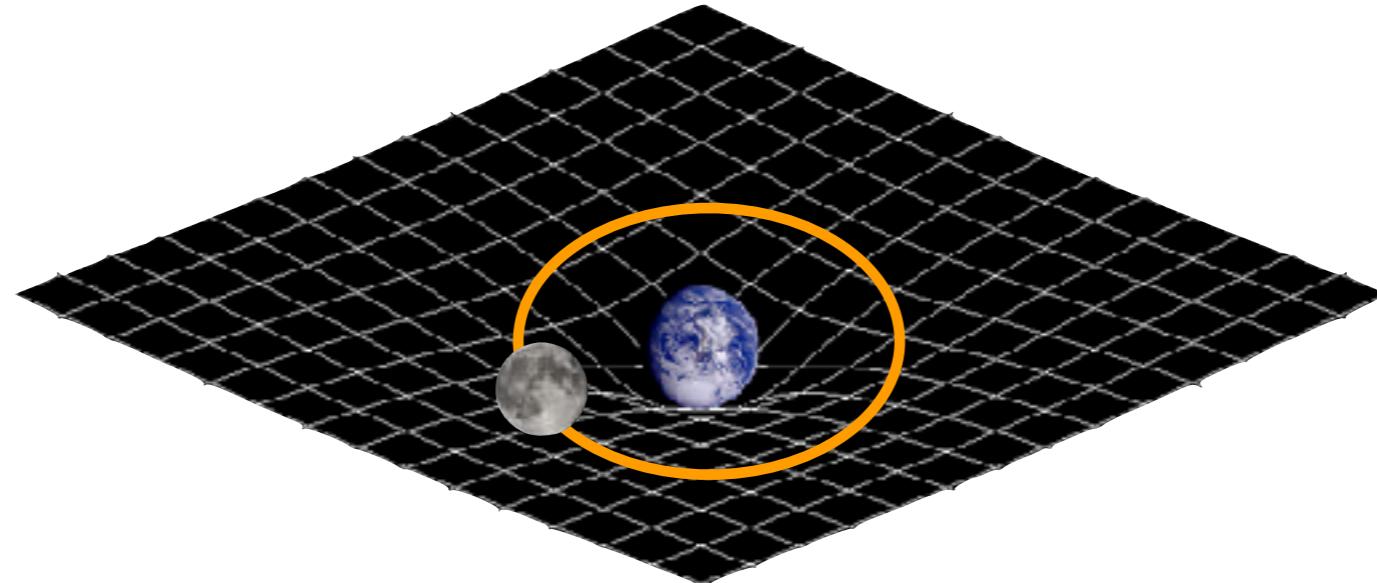
Basic principles of GR



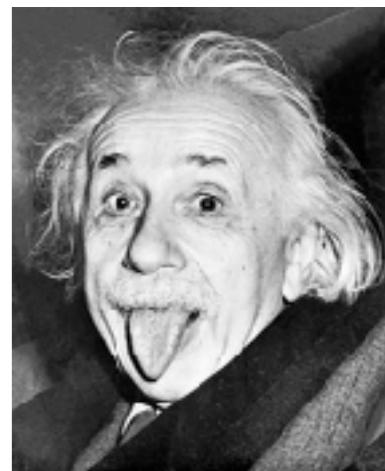
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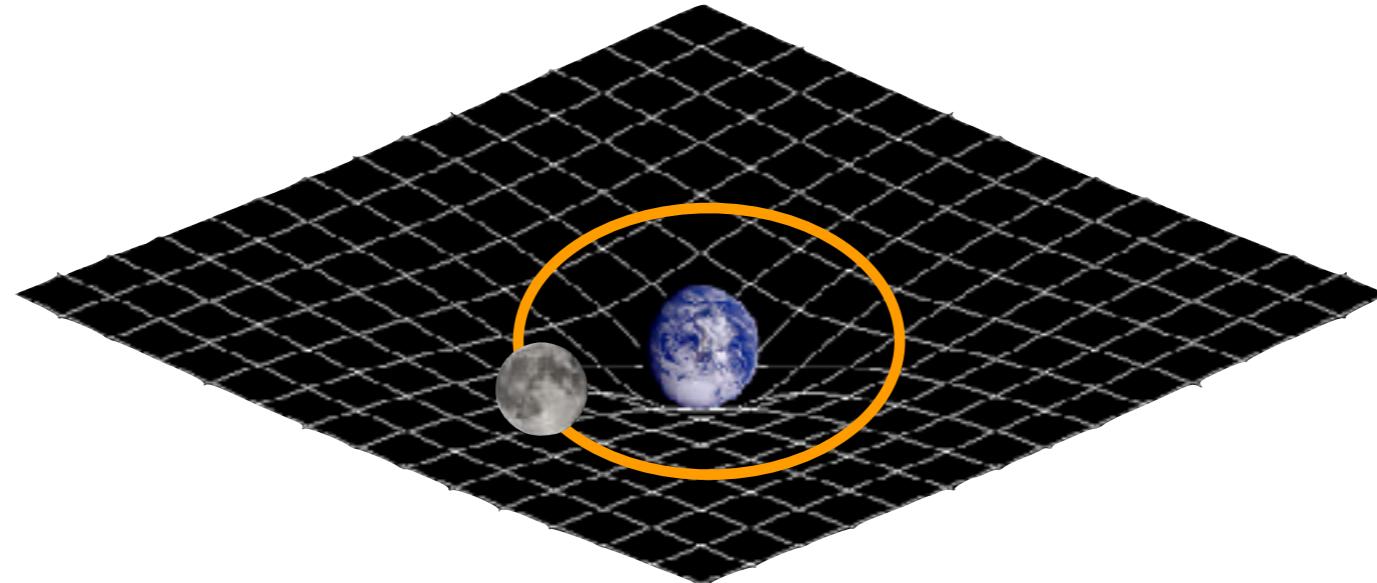
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space-time curvature (metric) \Leftrightarrow matter-energy content



- important effects for space-mission:
 - dynamics \neq from Newton (ex.: advance of the perihelion)
 - proper time (measured by ideal clocks) \neq coordinate time
 - coordinate time delay for light propagation (Range/Doppler)
 - light deflection (VLBI, astrometry)

Solar System observations

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Ground & space geodesy accuracy is increasing:

Solar System observations

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LLR & SLR → From cm to mm

GALILEO

Solar System observations

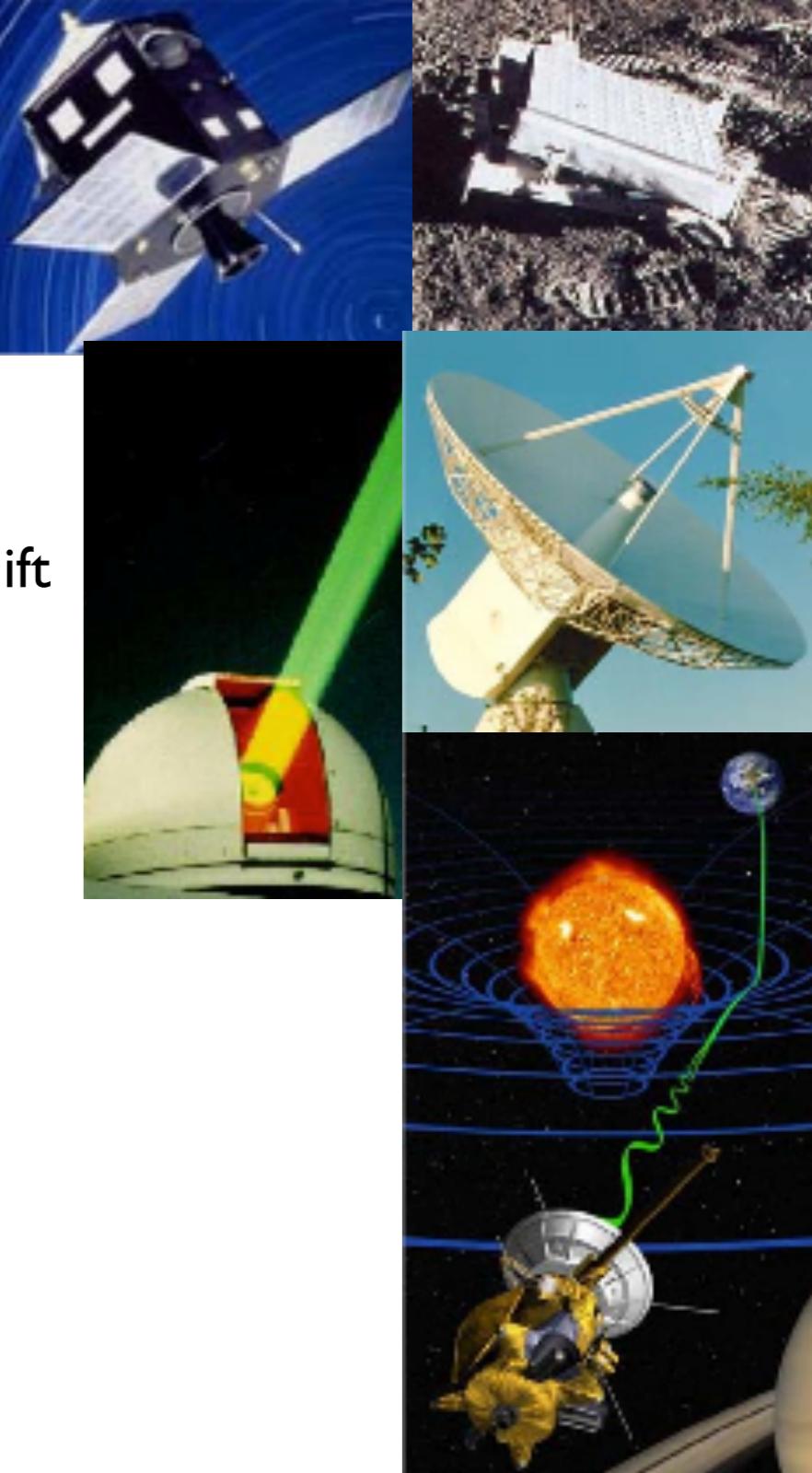
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Gravity Probe A to ACES/Pharao → factor 80 on Grav. Redshift

Solar System observations



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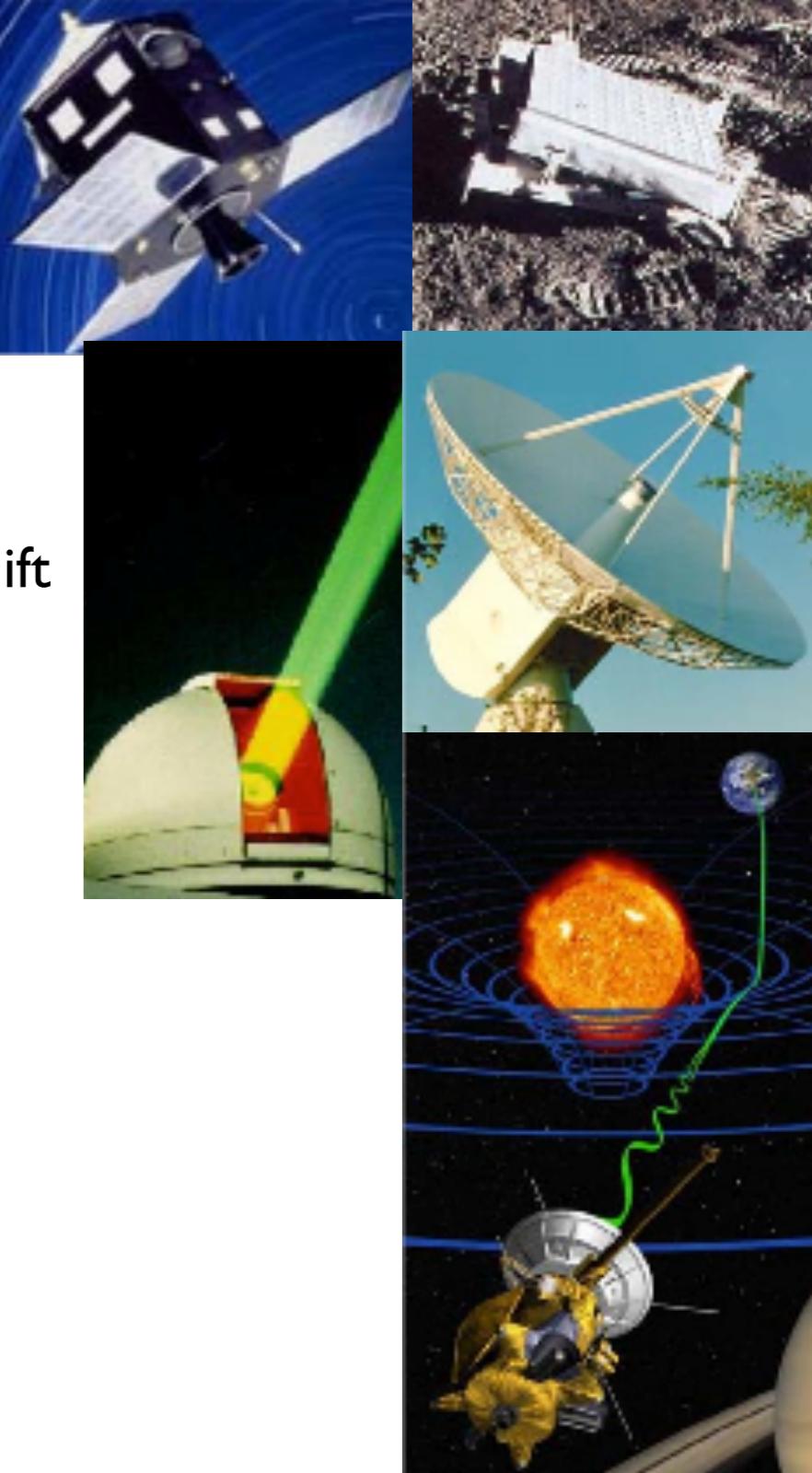
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Ground & space astrometry:

Gaia, Gravity → from milli to micro-arcsecond

Solar System observations



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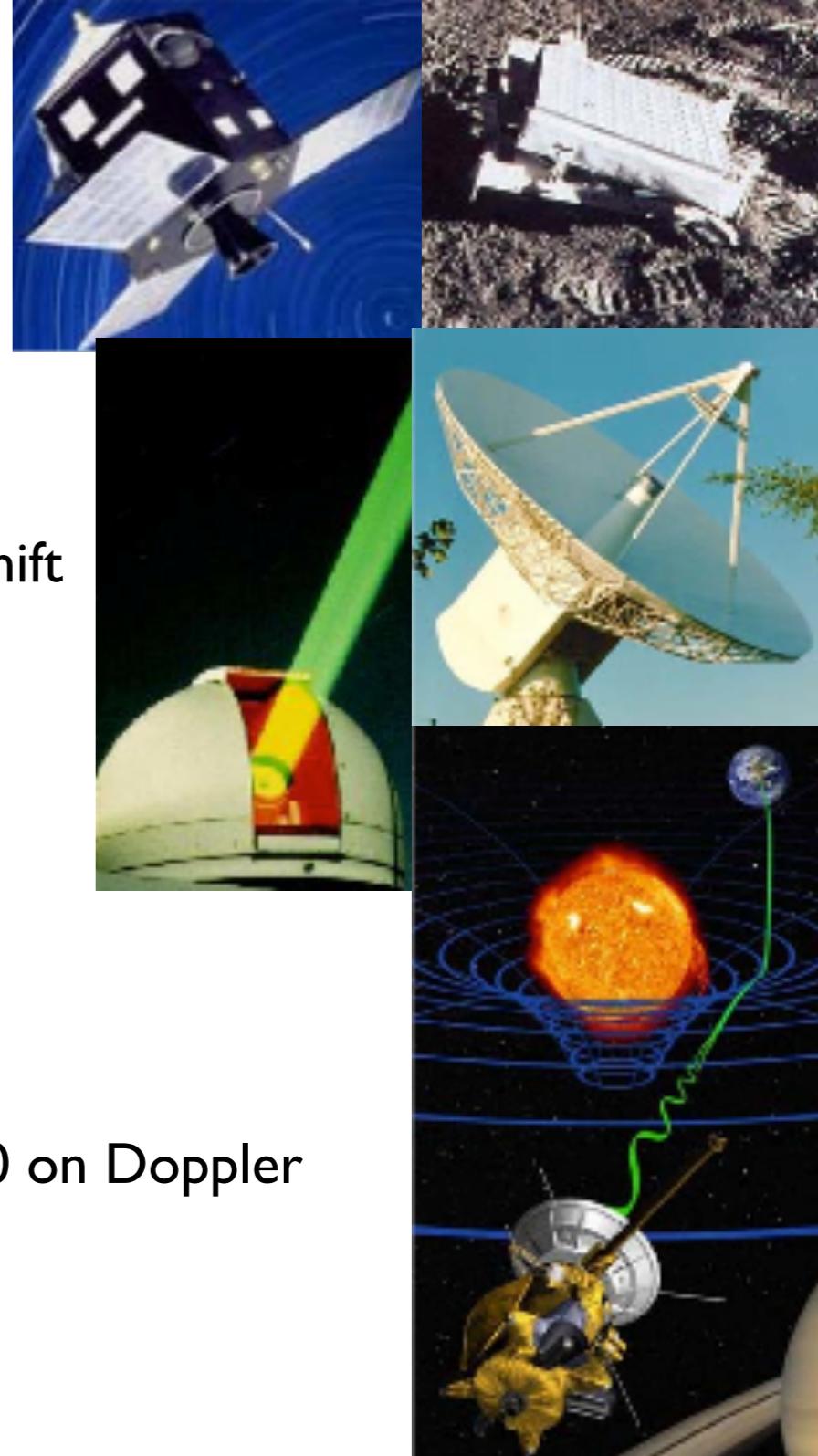
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Navigation of interplanetary probes :

Solar System observations



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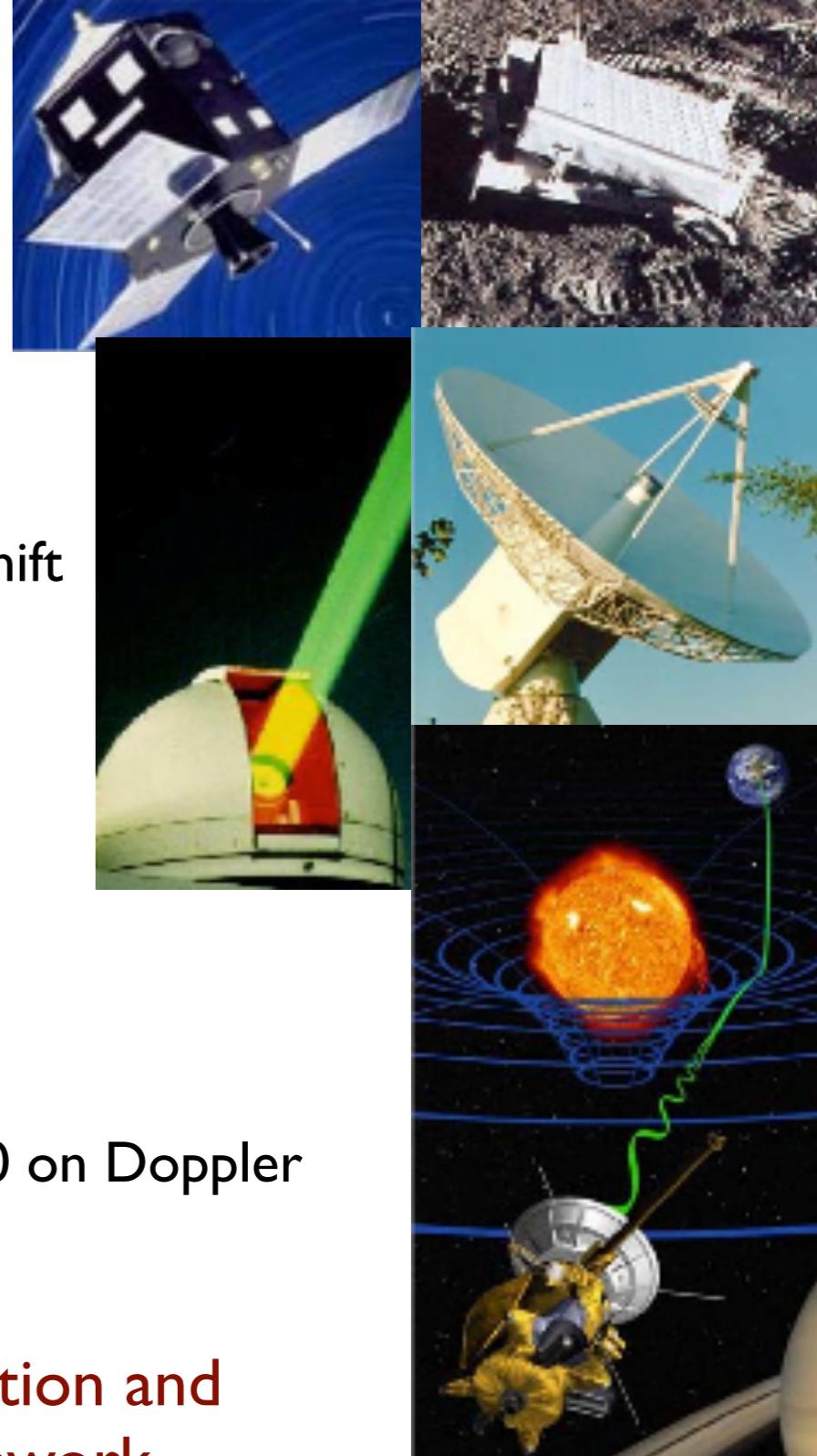
Cassini Experiment, use of Ka Band

MORE Experiment on BepiColombo

JUNO Experiment 2016, JUICE towards 2030



Solar System observations



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Need to describe light propagation and dynamics in relativistic framework



Solar System observations



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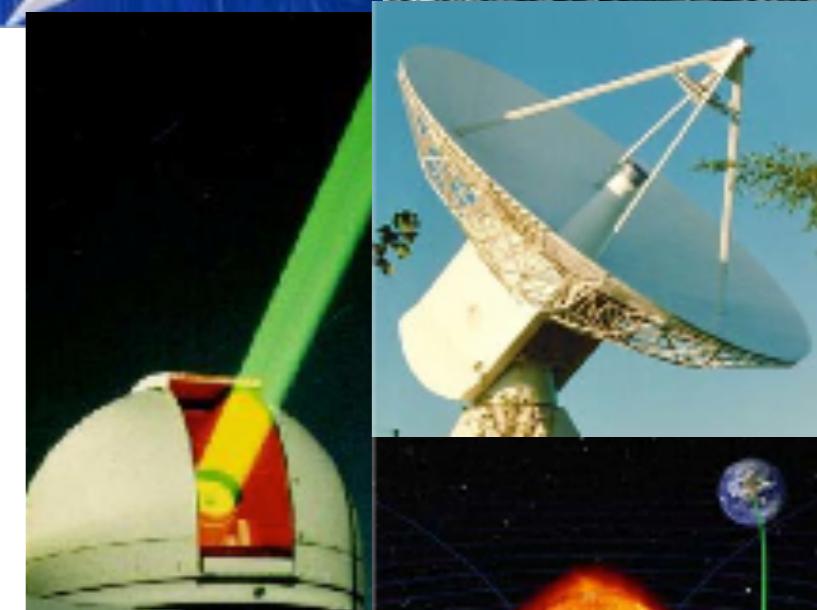
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→ factor 10 on Doppler

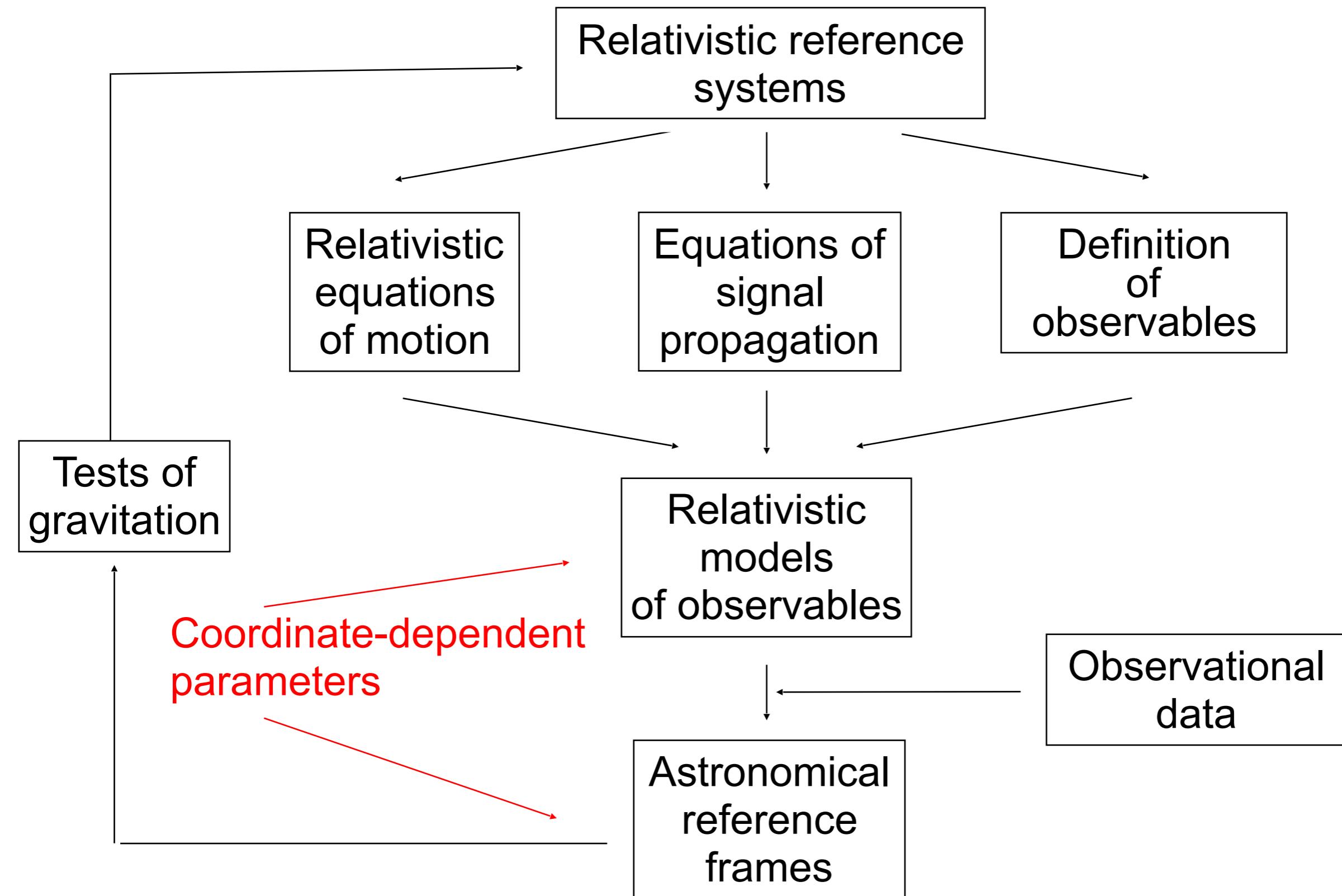


Need to describe light propagation and dynamics in relativistic framework

- one can solve geodesic
- one can introduce new tools and define properly the observables !



Relativistic Astronomy : some basics



IAU Reference Systems and relativity

THE IAU 2000 RESOLUTIONS FOR ASTROMETRY, CELESTIAL MECHANICS, AND METROLOGY IN THE RELATIVISTIC FRAMEWORK: EXPLANATORY SUPPLEMENT

M. SOFFEL,¹ S. A. KLIONER,¹ G. PETIT,² P. WOLF,² S. M. KOPEIKIN,³ P. BRETAGNON,⁴ V. A. BRUMBERG,⁵ N. CAPITAINE,⁶ T. DAMOUR,⁷ T. FUKUSHIMA,⁸ B. GUINOT,⁶ T.-Y. HUANG,⁹ L. LINDEGREN,¹⁰ C. MA,¹¹ K. NORDTVEDT,¹² J. C. RIES,¹³ P. K. SEIDELMANN,¹⁴ D. VOKROUHlický,¹⁵ C. M. WILL,¹⁶ AND C. XU¹⁷

Received 2002 August 9; accepted 2003 July 2

ABSTRACT

- First attempt : IAU 1976
- IAU 2000:
 - Fully relativistic (General Relativity, not PPN)
 - BCRS: time scale TCB
 - GCRS: time scale TCG
- IAU 2006: redefinition of time scale TDB

I. INTRODUCTION

lunar laser ranging measures the distance to the Moon with a precision of a few centimeters, thereby operating at the millimeter level. At this level, solar relativistic effects are significant and observable. Relativistic effects related to the motion of the Earth-Moon system about the Sun are of order 10^{-10} to 10^{-8} . The Lense-Thirring contraction of the Earth's oblateness that appears in barycentric coordinates has an amplitude of about 100 cm, whereas in some suitably chosen (local) coordinate system that moves with the Earth-Moon barycenter, the dominant relativistic range oscillation reduces to only a few centimeters (Mashhoon 1985; Soffel, Ruder, & Schneider 1986).

The situation is even more critical in the field of astrometry. It is well known that the gravitational light deflection at the limb of the Sun amounts to $1.75''$ and decreases only as $1/r$ with increasing impact parameter r of a light ray to the solar center. Thus, for light rays incident at about 90° from the Sun the angle of light deflection still amounts to 4 mas. To describe the accuracy of astrometric

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³ Department of Physics and Astronomy, 322 Physics Building, University of Missouri-Columbia, Columbia, MO 65211.

⁴ Bureau des Longitudes, 77 Avenue Denfert-Rechereau, F-75014 Paris, France.

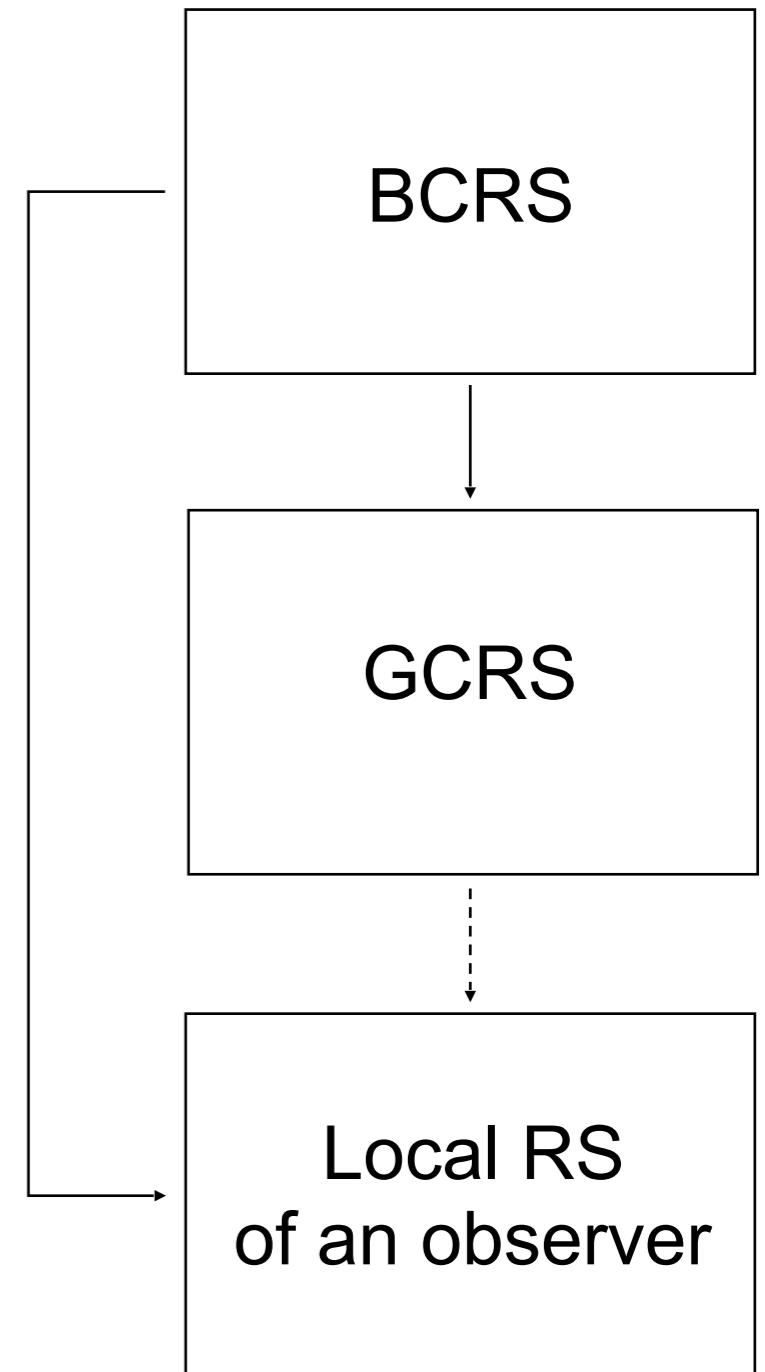
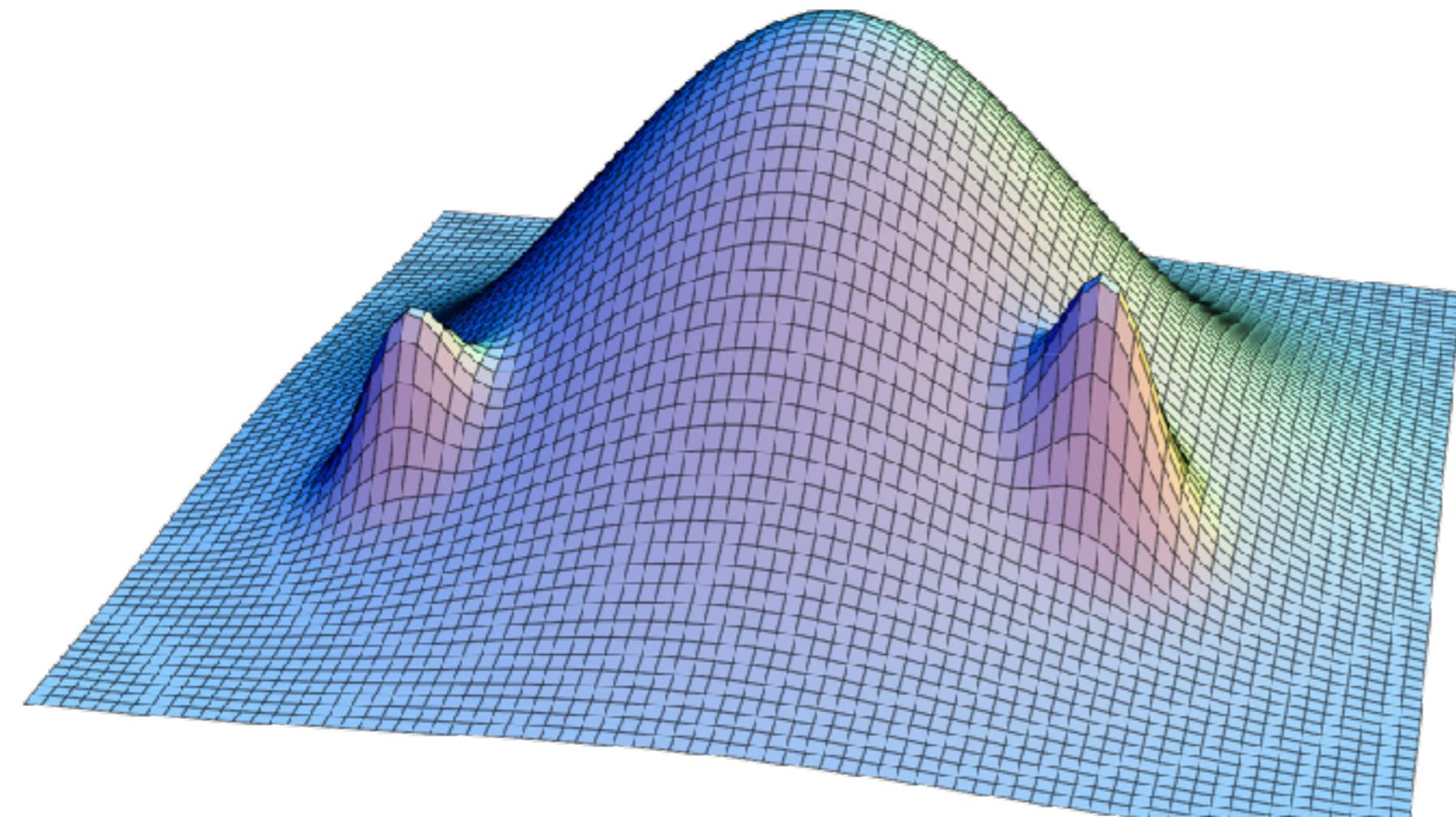
⁵ Institute of Applied Astronomy, Russian Academy of Sciences, Naberezhnaya Kutuzova 10, St. Petersburg 191187, Russia.

⁶ Observatoire de Paris, 61 Avenue de l'Observatoire, F-75014 Paris, France.

⁷ Institut des Hautes Etudes Scientifiques, 35 Route de Chartres,

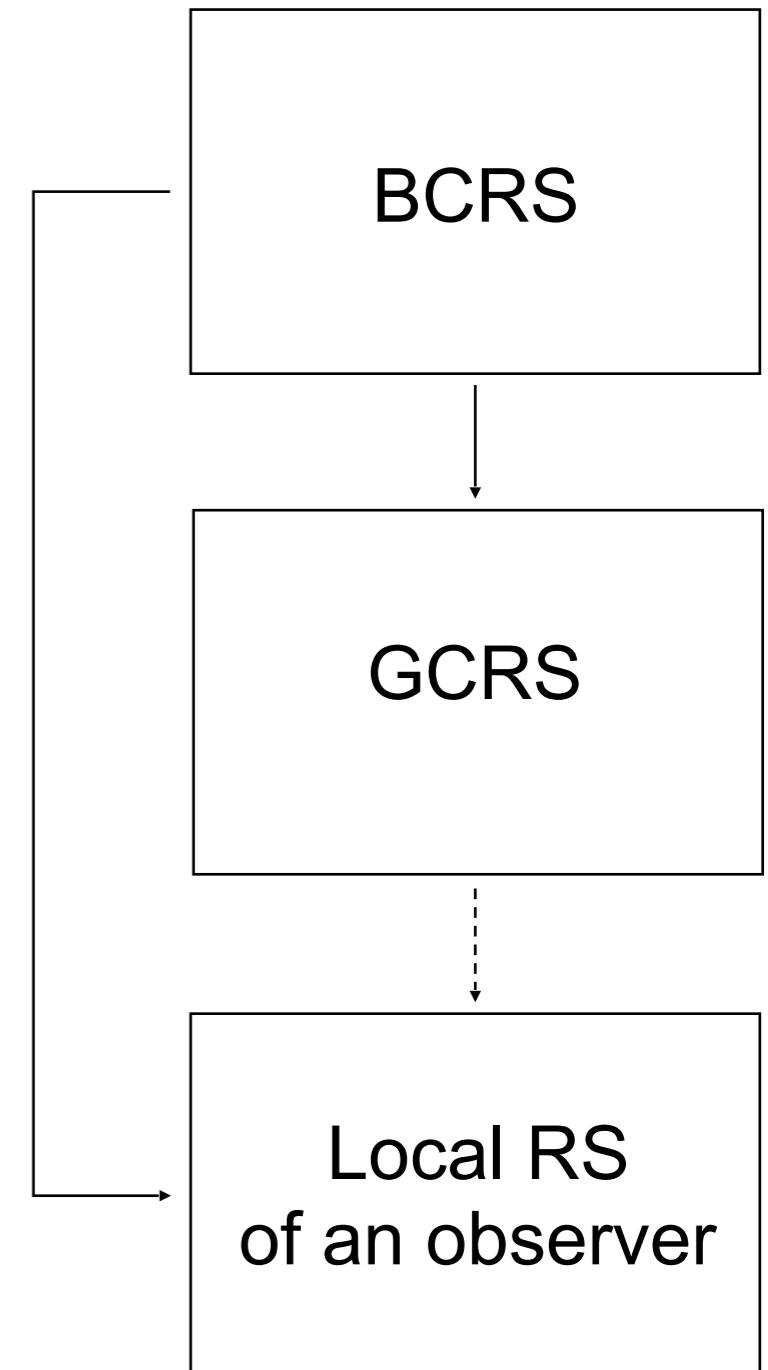
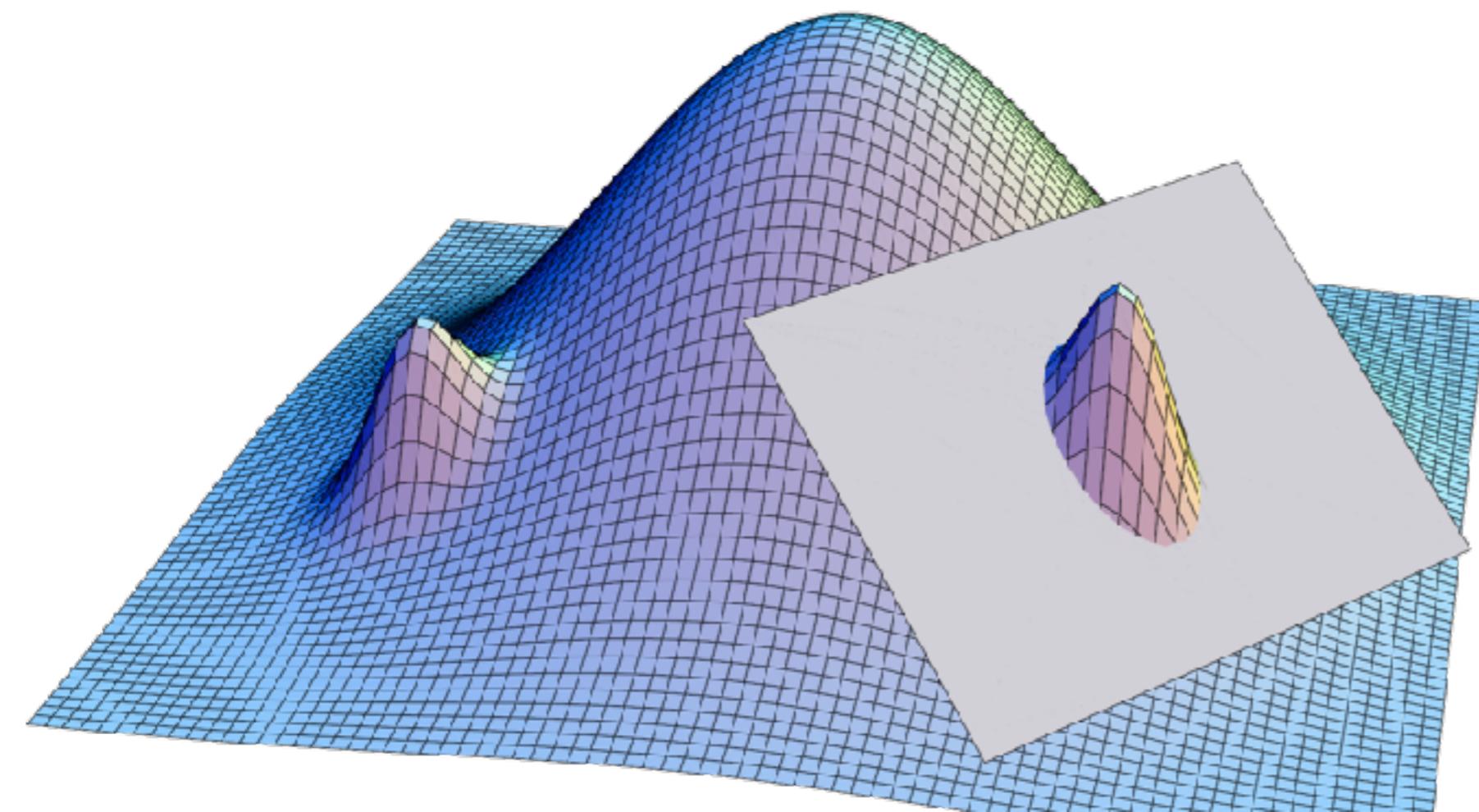
Reference systems theory

- In relativistic astronomy the
 - BCRS (Barycentric Celestial Reference System)
 - GCRS (Geocentric Celestial Reference System)
 - Local reference system of an observer
- play an important role.
- All these reference systems are defined by the form of the corresponding metric tensor.



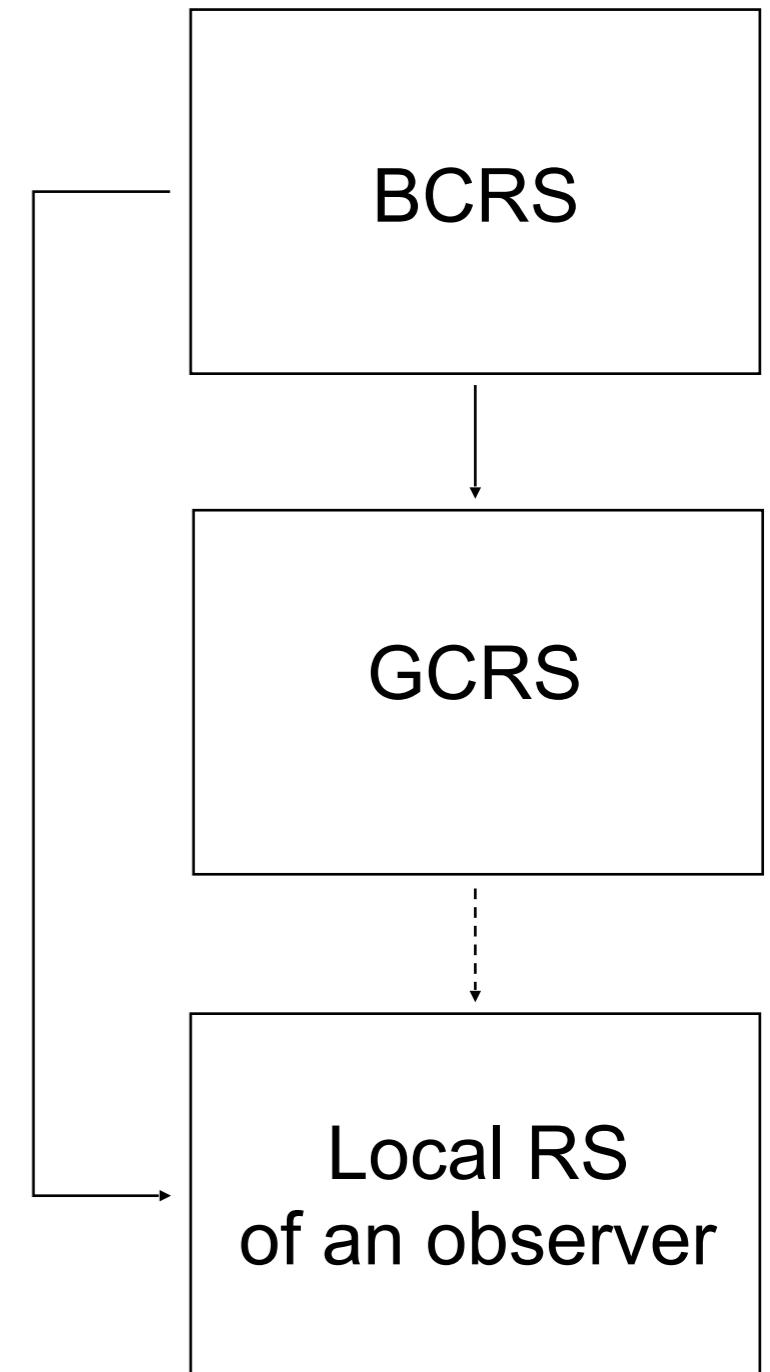
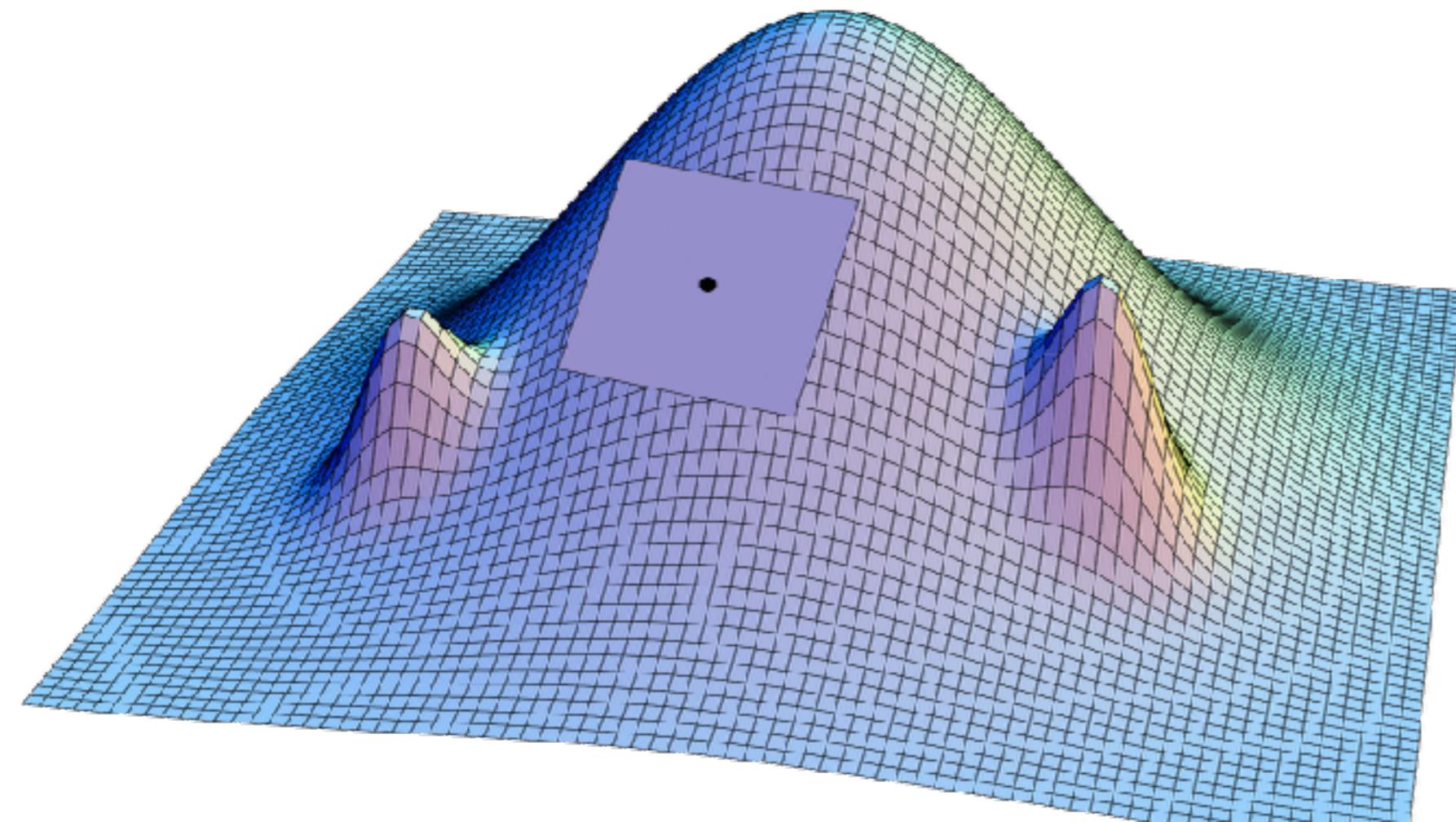
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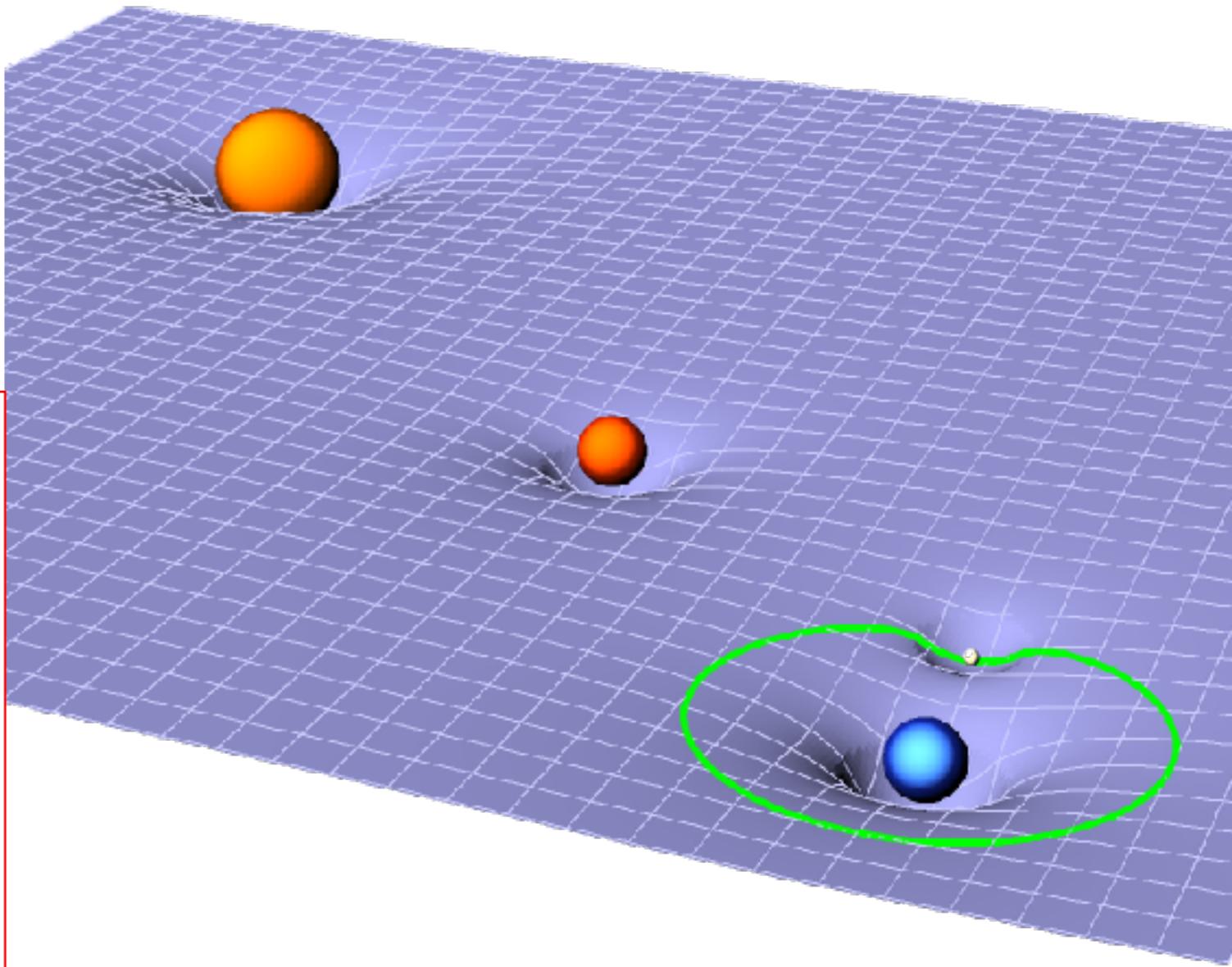
Barycentric Celestial Reference System

The BCRS is a particular reference system in the curved space-time of the Solar system

- One can use any
- but one should fix one :

ICRF by VLBI

$$\begin{aligned}g_{00} &= -1 + \frac{2}{c^2} w(t, \mathbf{x}) - \frac{2}{c^4} w^2(t, \mathbf{x}), \\g_{0i} &= -\frac{4}{c^3} w^i(t, \mathbf{x}), \\g_{ij} &= \delta_{ij} \left(1 + \frac{2}{c^2} w(t, \mathbf{x}) \right).\end{aligned}$$



Used to describe motion of celestial body and description of light propagation
Ephemeride Astrometry

Tests of the gravitational dynamics

- How to test the form of the metric/the Einstein field equations ? Two frameworks widely used so far:

Tests of the gravitational dynamics

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I) Parametrized Post-Newtonian Formalism¹

- powerful phenomenology making an interface between theoretical development and experiments
- metric parametrized by 10 dimensionless coefficients
- γ and β whose values are 1 in GR

$$ds^2 = (1 + 2\phi_N + 2\beta\phi_N^2 + \dots)dt^2 - (1 - 2\gamma\phi_N + \dots)d\vec{x}^2$$

¹ C. Will, LRR, 9, 2006

“Theory and Experiment in Grav. Physics”, C. Will, 1993

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II) Fifth force formalism²

- modification of Newton potential of the form of a Yukawa potential

$$\phi(r) = \frac{GM}{c^2 r} \left(1 + \alpha e^{-r/\lambda}\right)$$

¹ C. Will, LRR, 9, 2006

“Theory and Experiment in Grav. Physics”, C. Will, 1993

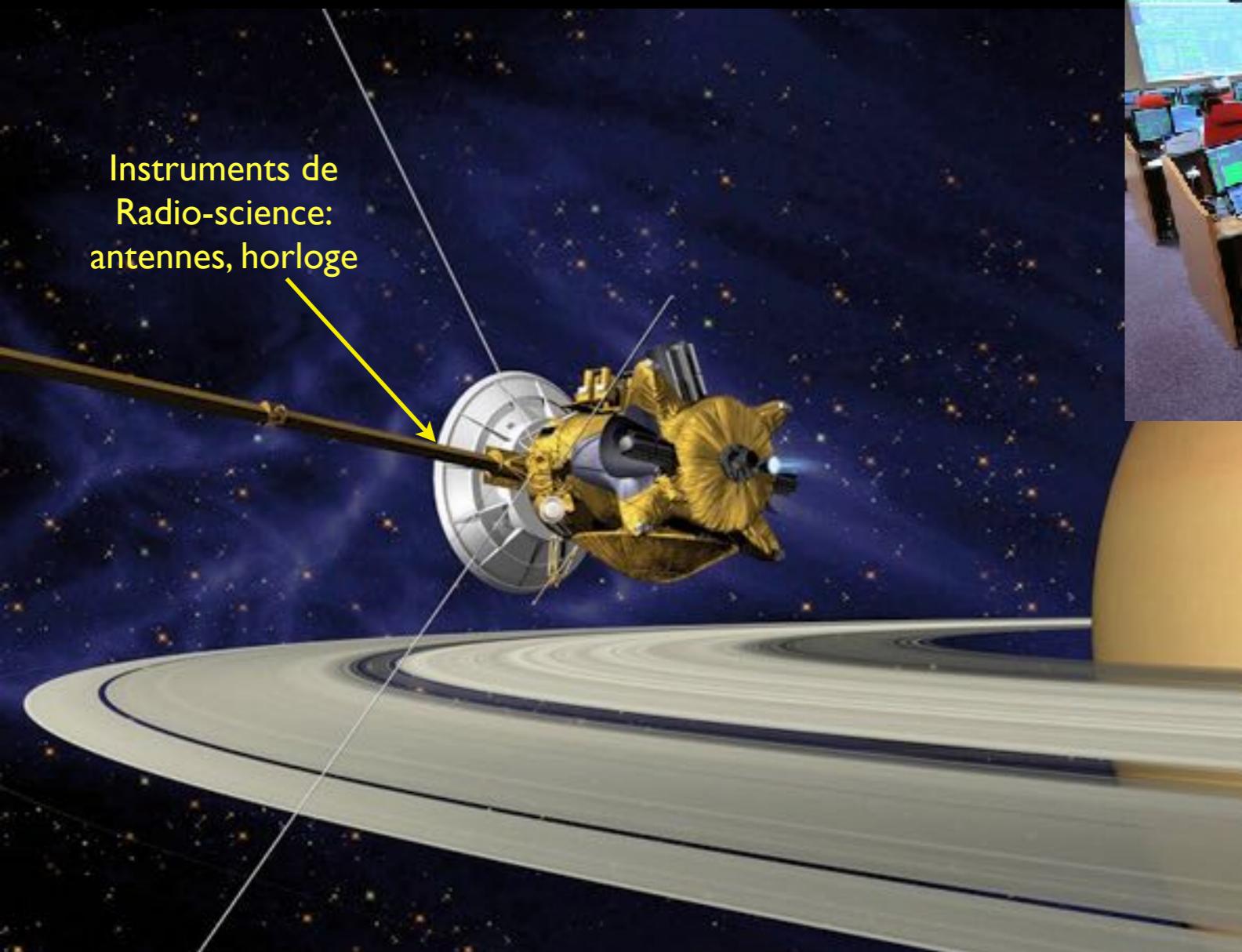
² E.G. Adelberger, Progress in Part. and Nucl. Phys., 62/102, 2009

“The Search for Non-Newtonian gravity”, E. Fischbach, C. Talmadge, 1998

PPN parameters and their significance

Parameter	What it measures, relative to general relativity	Value in GR	Value in scalar tensor theory	Value in semi-conservative theories
γ	How much space curvature produced by unit mass?	1	$(1+\omega)/(2+\omega)$	γ
β	How "nonlinear" is gravity?	1	$1 + \Lambda$	β
ξ	Preferred-location effects?	0	0	ξ
a1	Preferred-frame effects?	0	0	a1
a2		0	0	a2
a3		0	0	0
ζ_1	Is momentum conserved?	0	0	0
ζ_2		0	0	0
ζ_3		0	0	0
ζ_4		0	0	0

Expériences de Radio-Science

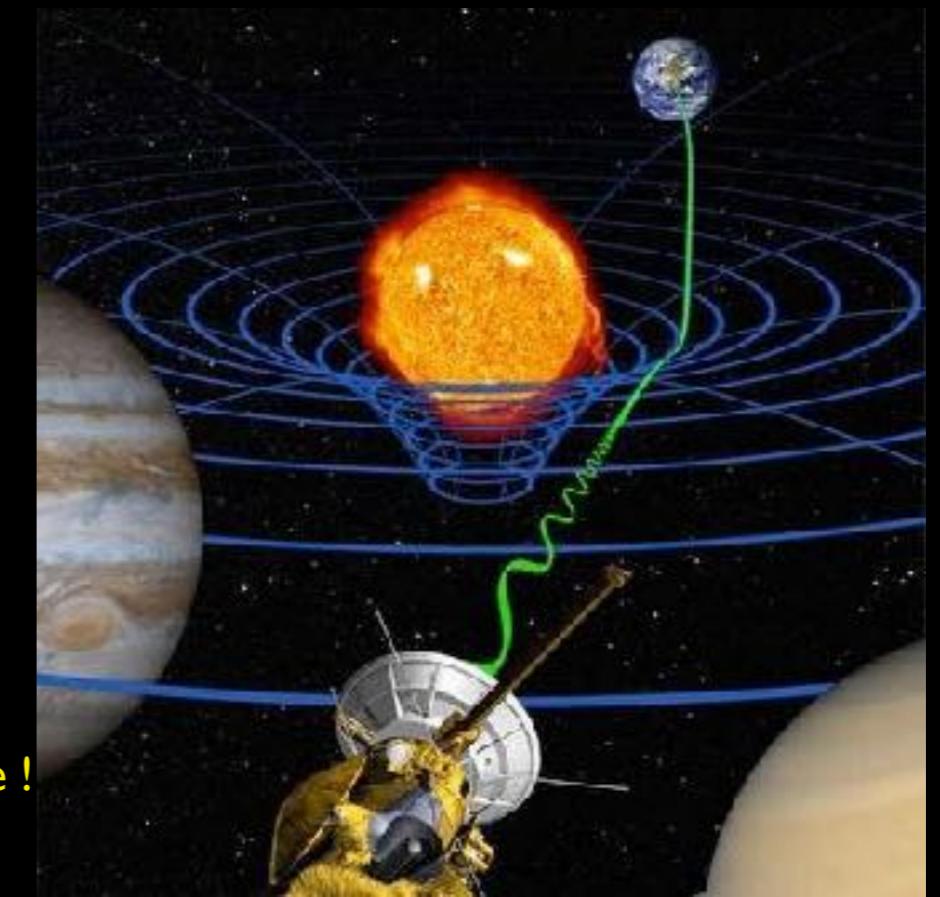


Conjonction entre la Terre et Cassini en Septembre 2003



Maximum de déflexion relativiste !

Une équipe italienne mesure le changement de la fréquence du signal avec une précision de quelques 10^{-14} de fraction de fréquence.



La Relativité serait correcte à 0.002% près
Bertotti *et al.* 2003, *Nature*, 425, 374

Shapiro effect with Viking Probe

$$\Delta t \approx \frac{2GM(1+\gamma)}{c^3} \left[\ln\left(\frac{4r_A r_B}{r_0^2}\right) + 1 \right]$$

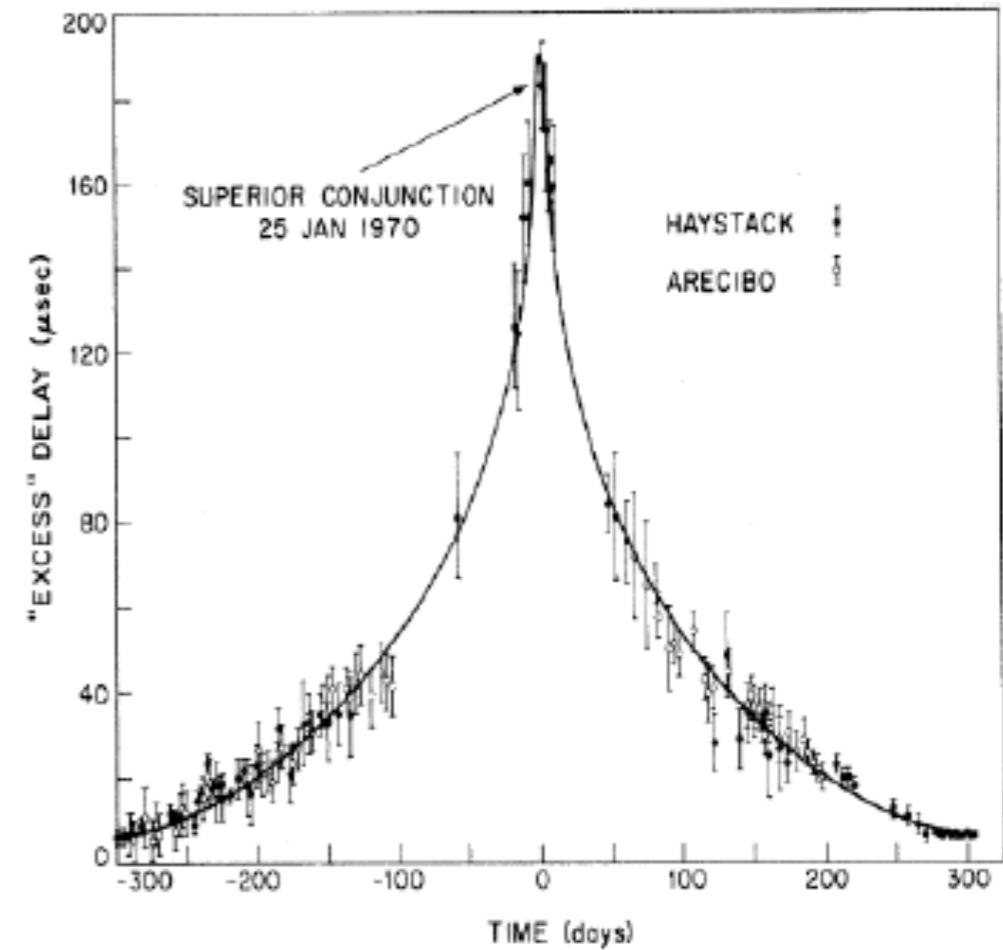
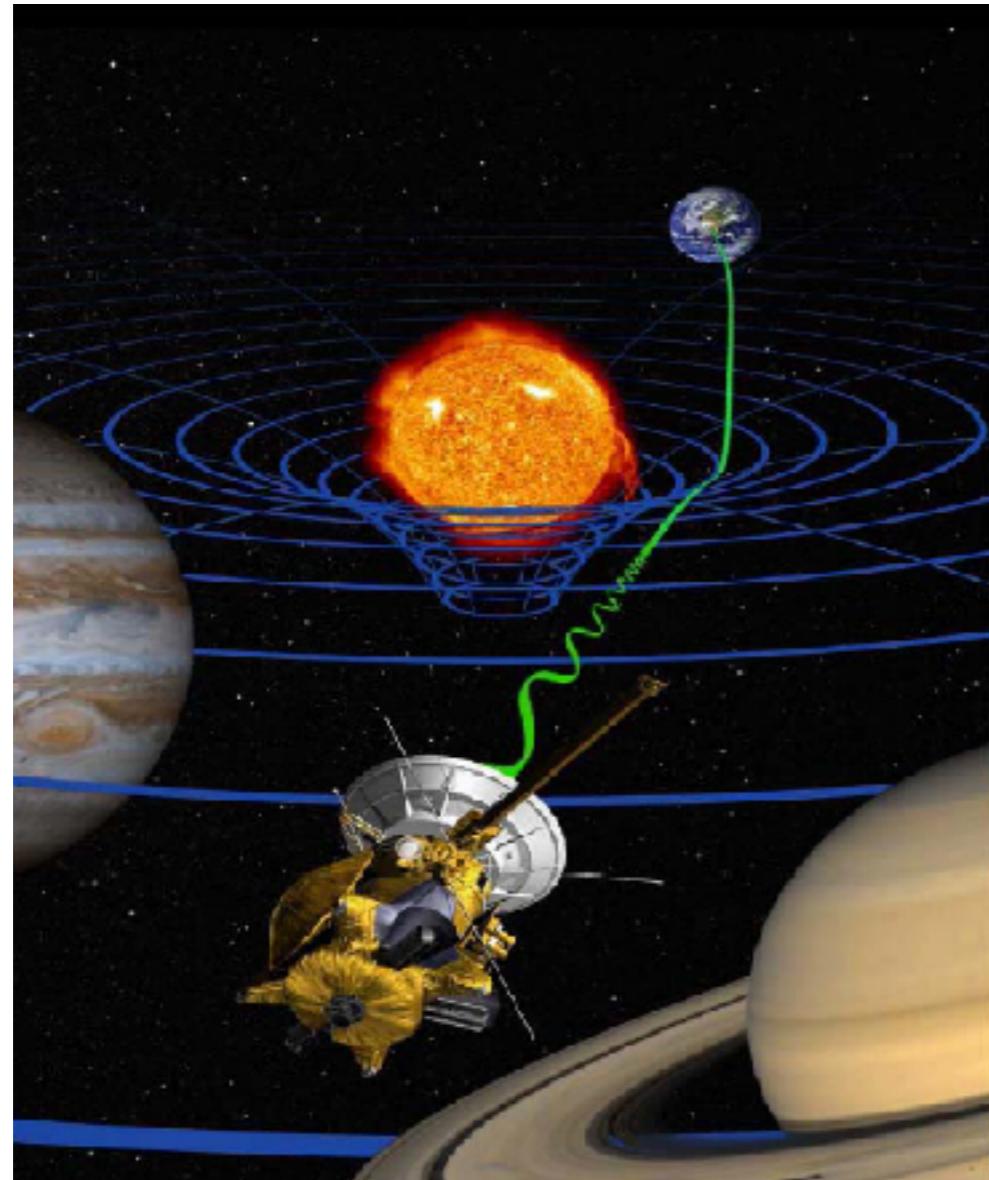
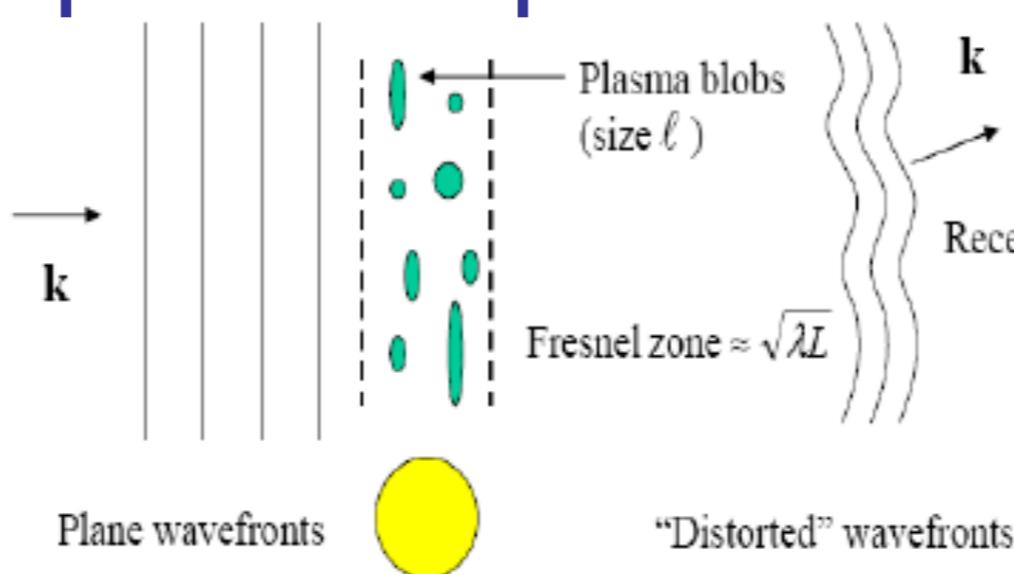
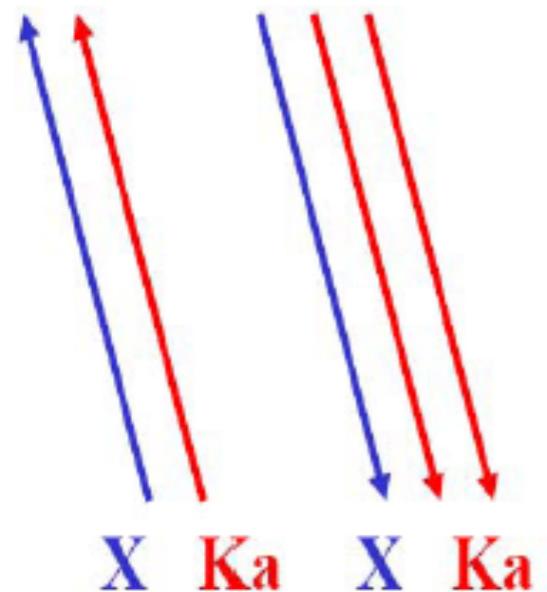


FIG. 1. Typical sample of post-fit residuals for Earth-Venus time-delay measurements, displayed relative to the “excess” delays predicted by general relativity. Corrections were made for known topographic trends on Venus. The bars represent the original estimates of the measurement standard errors. Note the dramatic increase in accuracy that was obtained with the radar-system improvements incorporated at Haystack just prior to the inferior conjunction of November 1970.

Shapiro, I.I. et al, Phys.Rev.Lett, 26, 1132 (1971)



Cassini probe experiment



Critical blob size:
 $\ell_c = \sqrt{\lambda L}$

$L = 1 \text{ AU}$
 $X: 80 \text{ km}$
 $Ka: 40 \text{ km}$

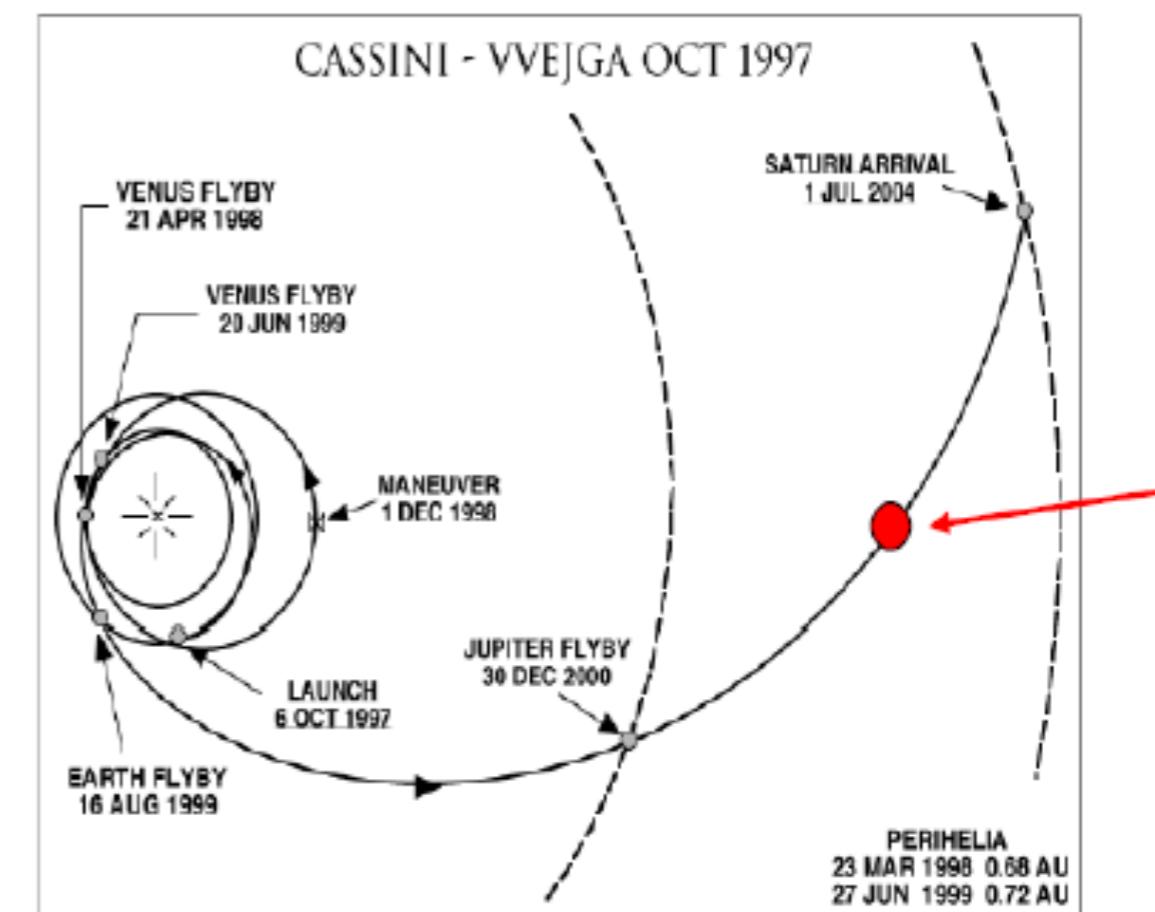


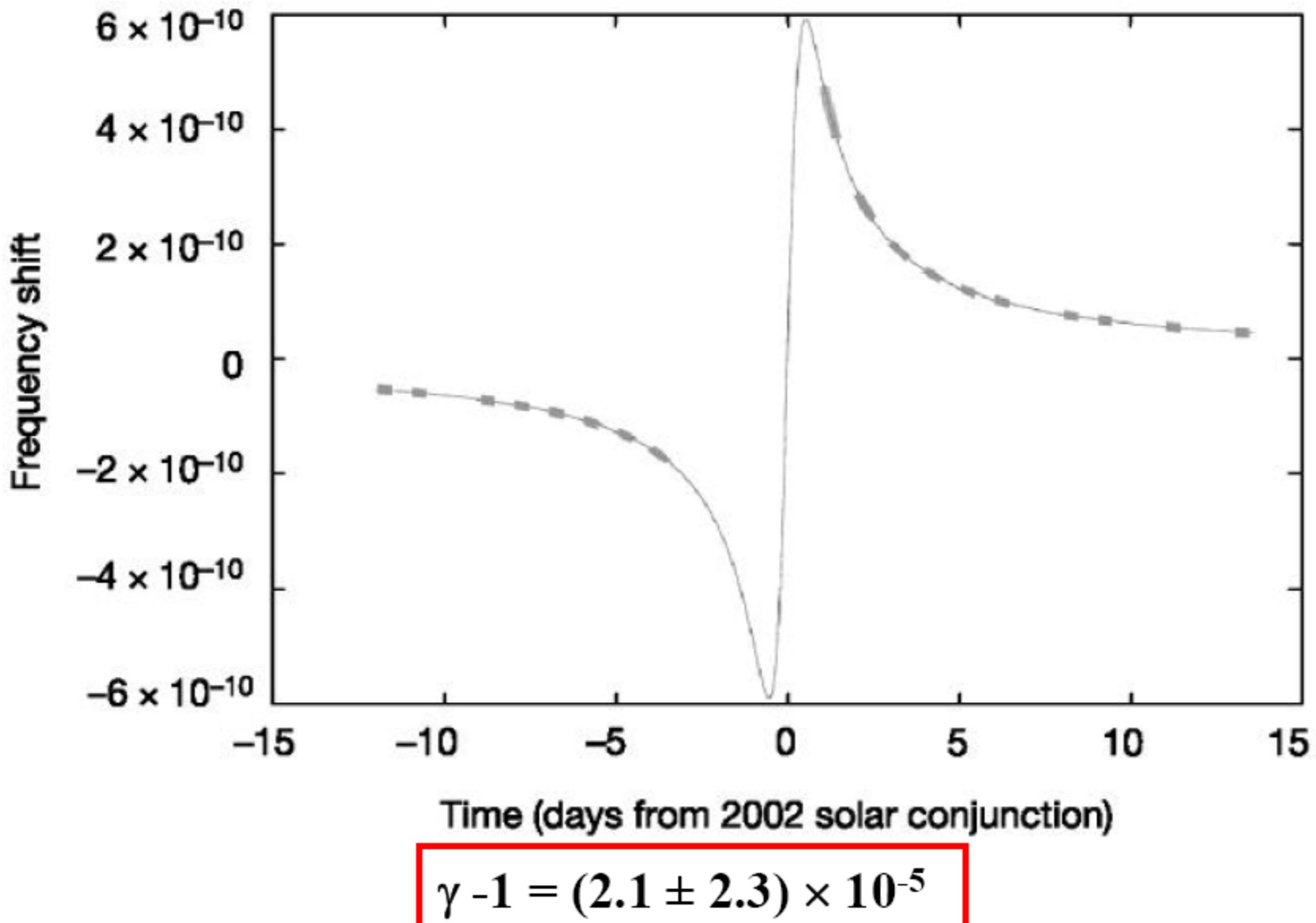
Doppler effect

DSS 25 -
Goldstone

$$\frac{\Delta \nu}{\nu} \approx 4(1 + \gamma) \frac{M_{Sol}}{b} \frac{db}{dt}$$

$$\delta \left(\frac{f_r - f_e}{f_0} \right) \approx \frac{d}{dt} \left[2(1 + \gamma) \frac{GM}{c^3} \ln \left(\frac{4r_S r_G}{b^2} \right) \right] \approx -4(1 + \gamma) \frac{GM}{c^3 b} \frac{db}{dt}$$





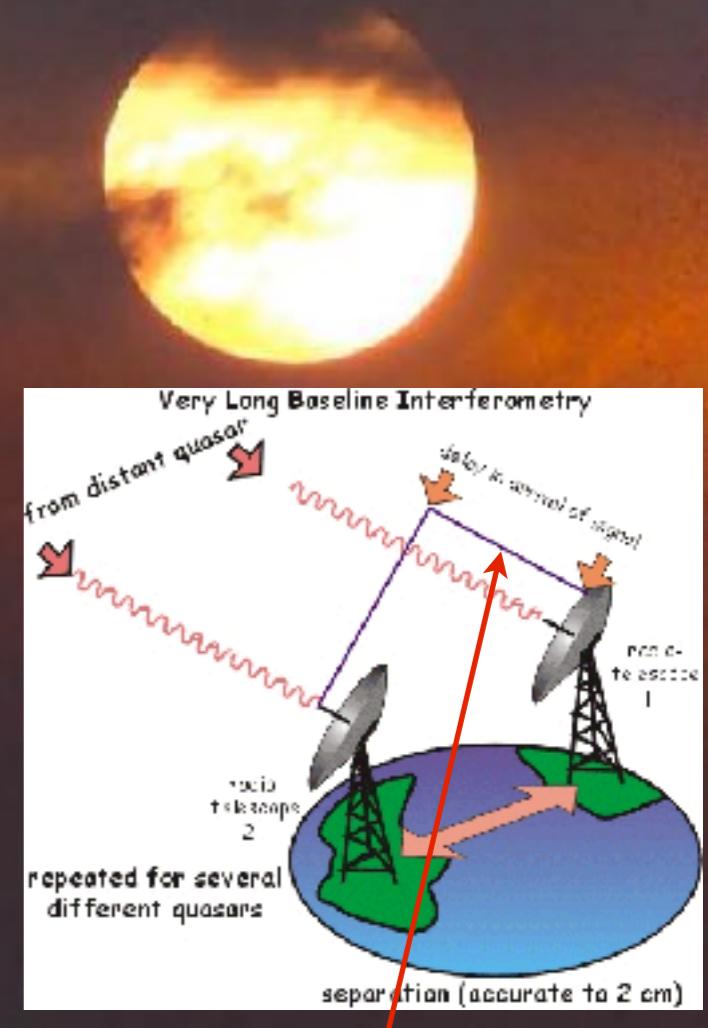
Bertotti, B. et al, *Nature*, 425, 374 (2003)

Interférométrie à Très Longue Base: le VLBI

On observe les objets les plus lointains:

1. Ne bougent pas, en première approximation,
2. Avec 2 radio-télescopes, on réalise donc une triangulation !

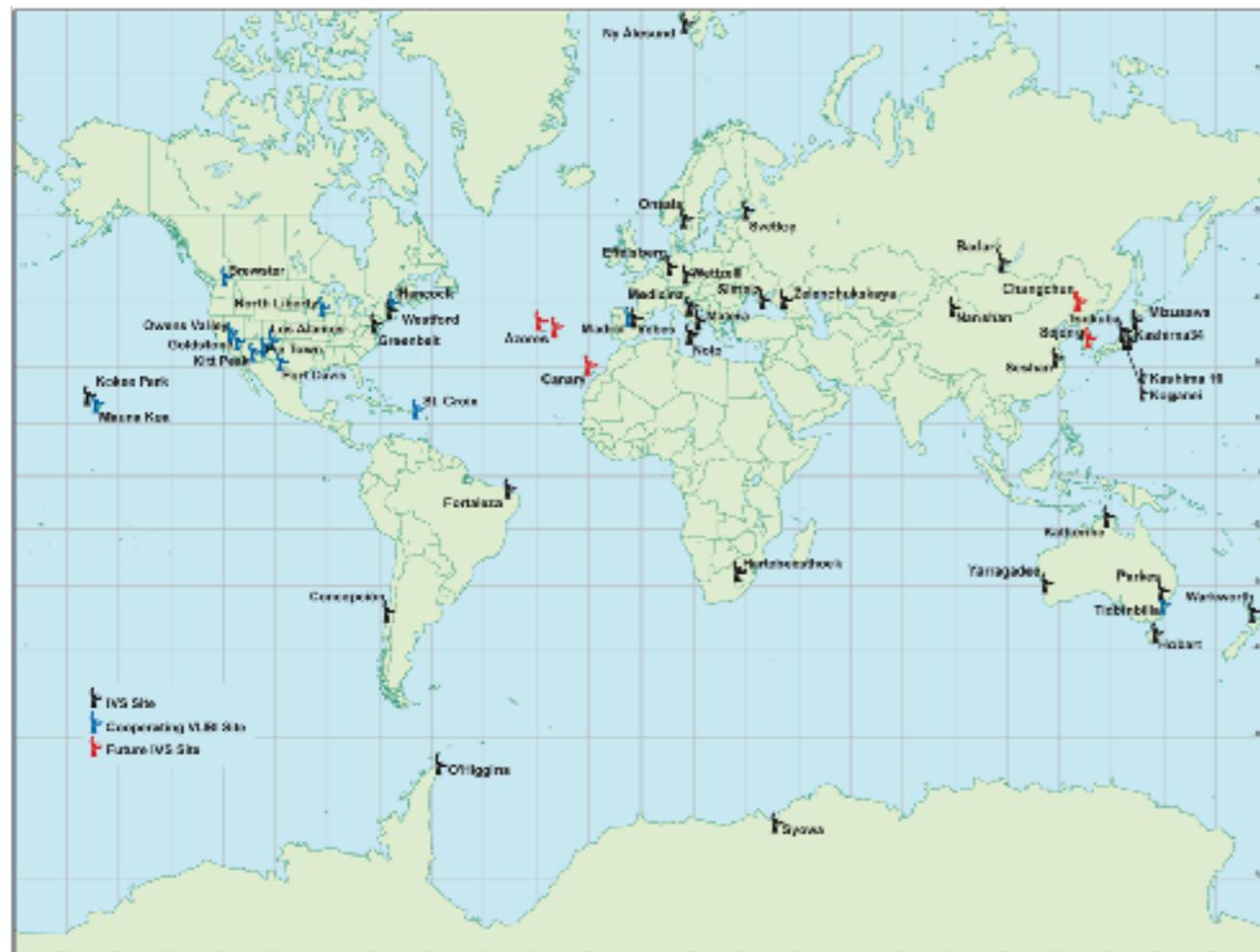
Position cinématique
de la Terre
dans l'espace



Délai temporel entre les réceptions des signaux:
mesure temporelle !

Qui dit un laps de temps...
dit une distance !

International VLBI service (IVS)



primary goals :

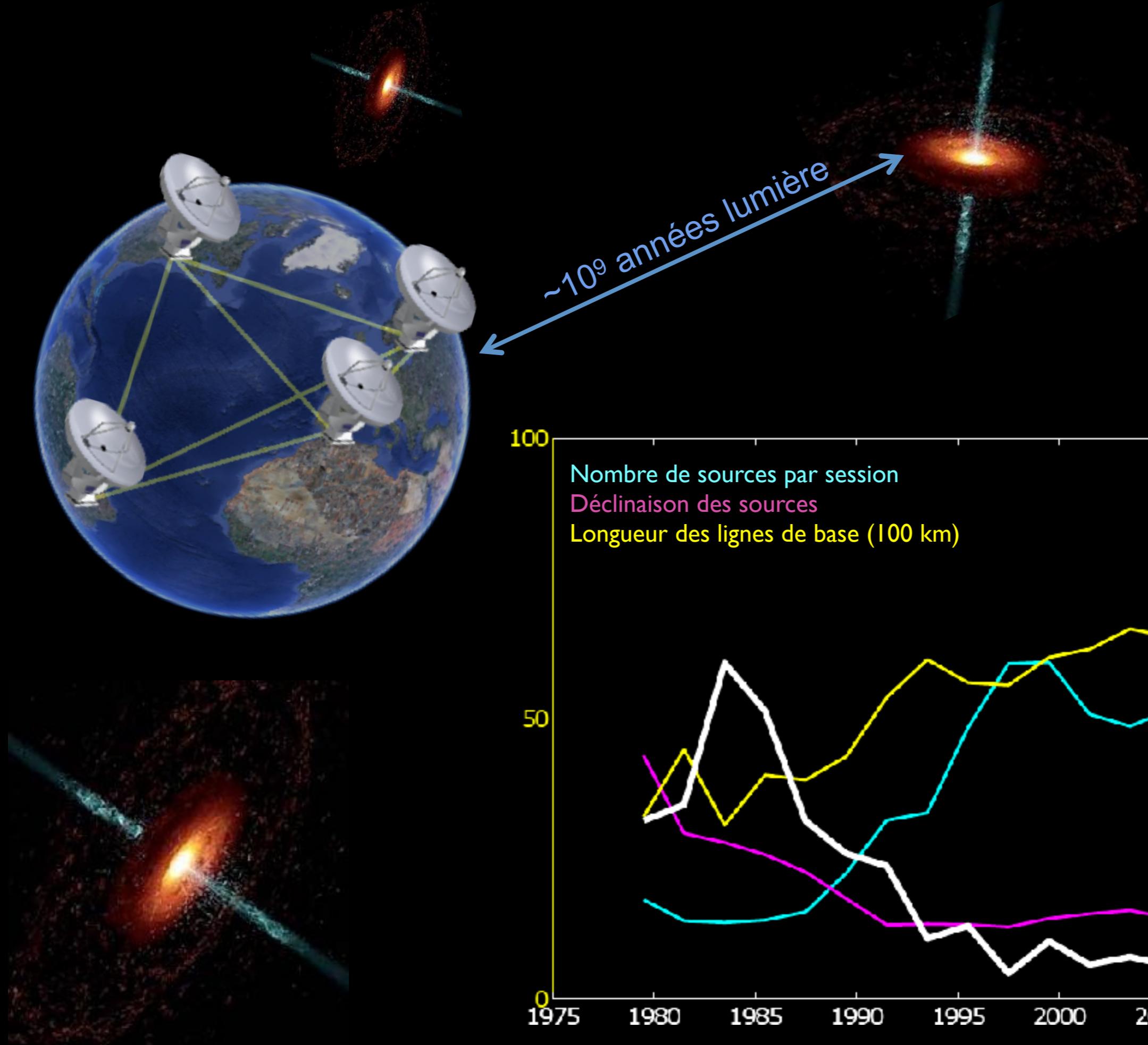
- monitoring the Earth's rotation
- determining reference frames

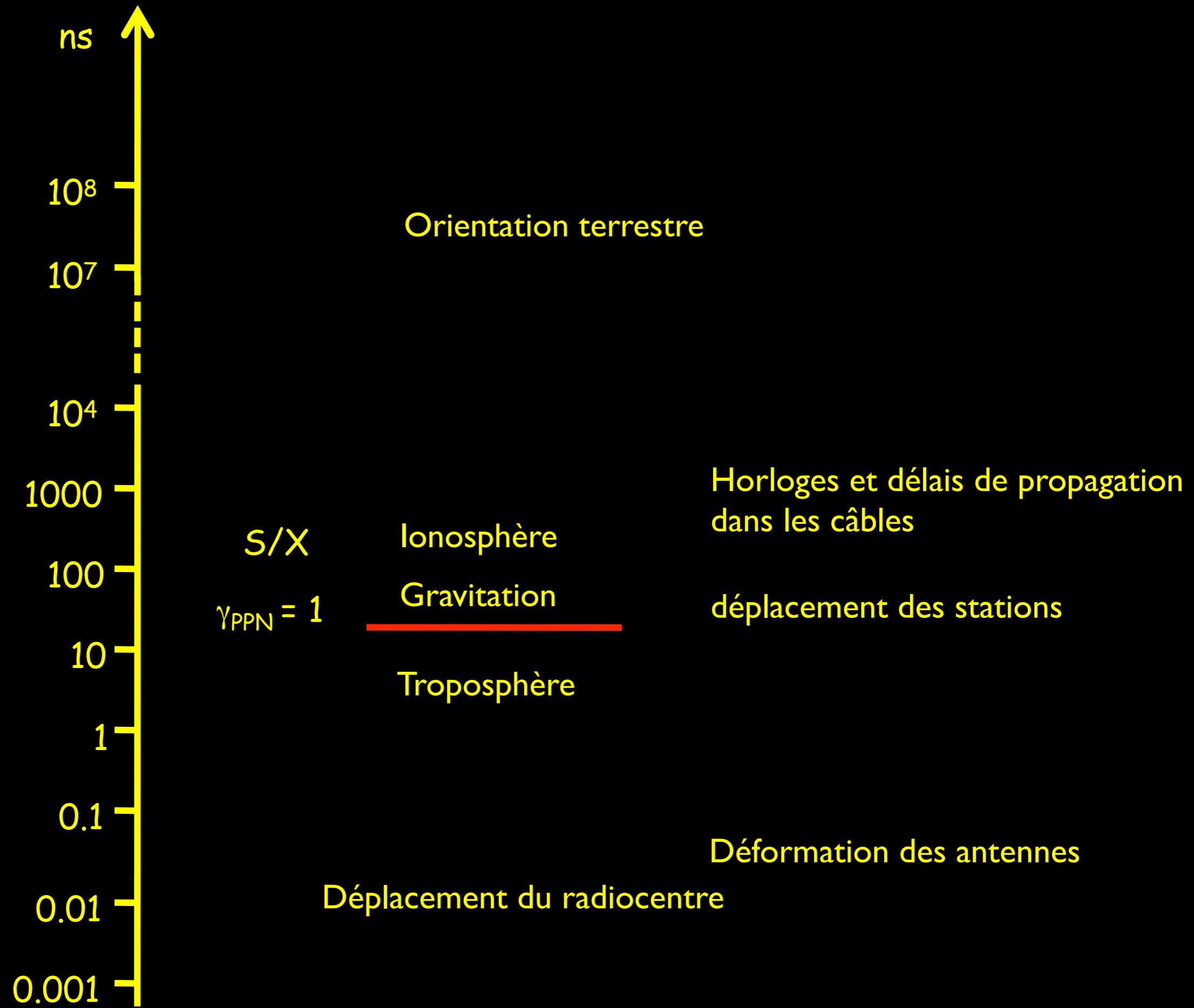
5 data centers and 29 analysis centers

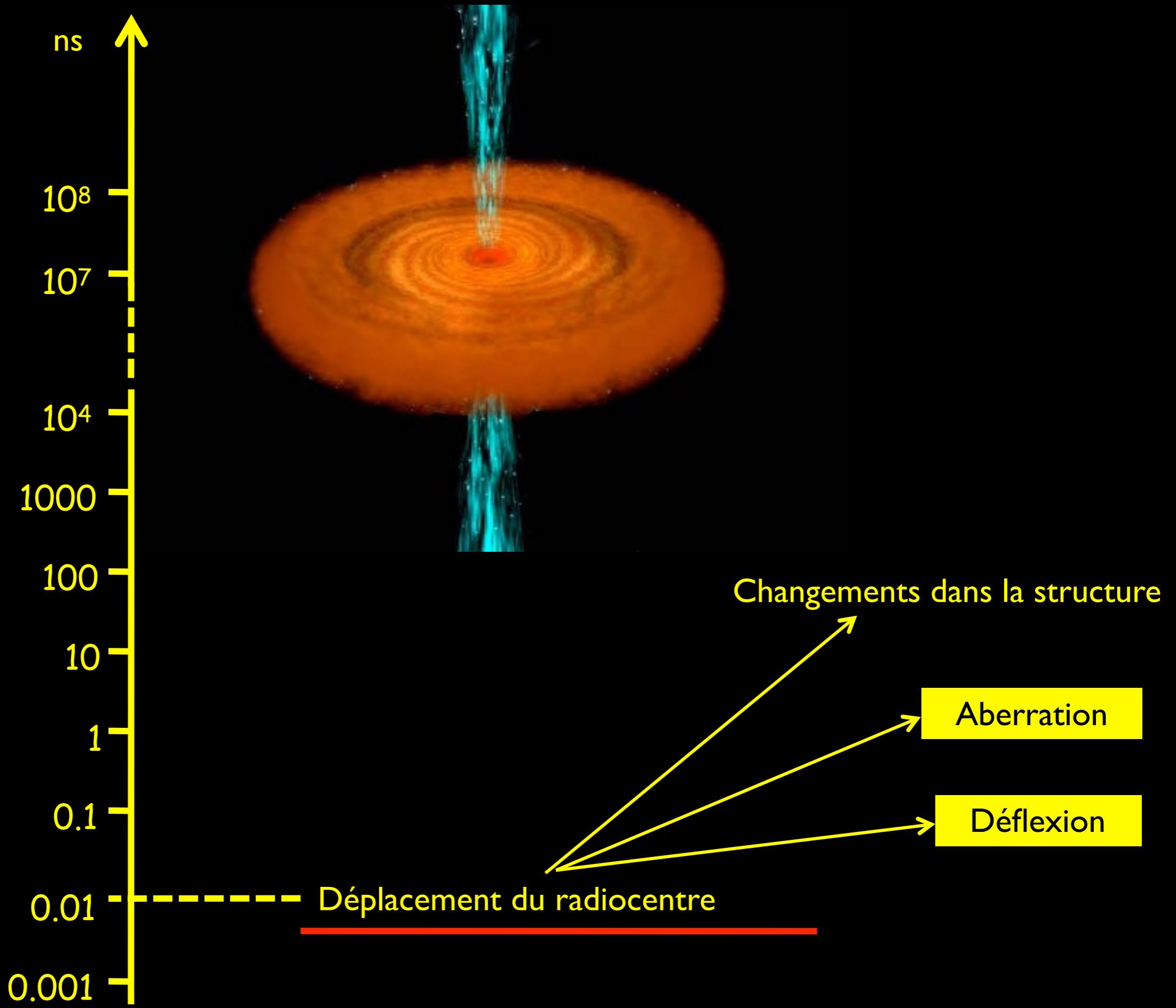
IVS-OPAR @ SYRTE/Obs.
Paris
lead : S. Lambert

Use Mark-5 VLBI Analysis Software
Calc/Solve.
109 programs, 3680 modules
1.02 million lines of source code
written mainly in Fortran-95

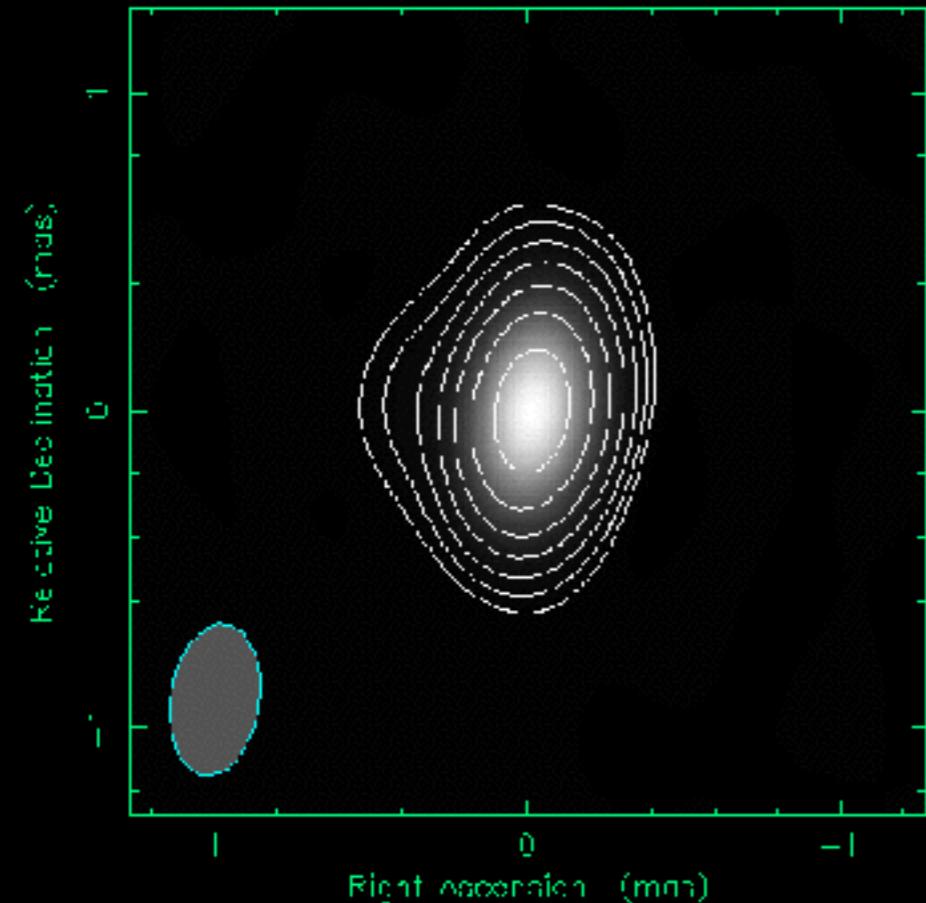
Observation time span : From August 1979 to mid-2016
almost 6000 VLBI 24-hr sessions
(correspondingly 10 million delays)



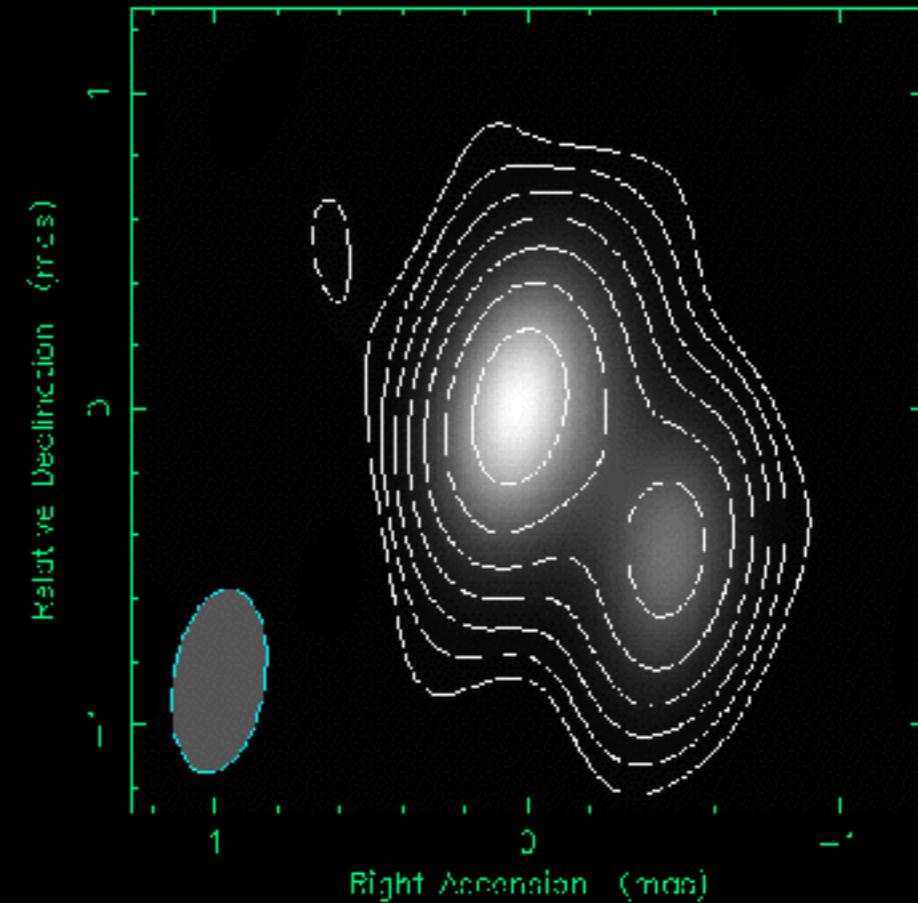




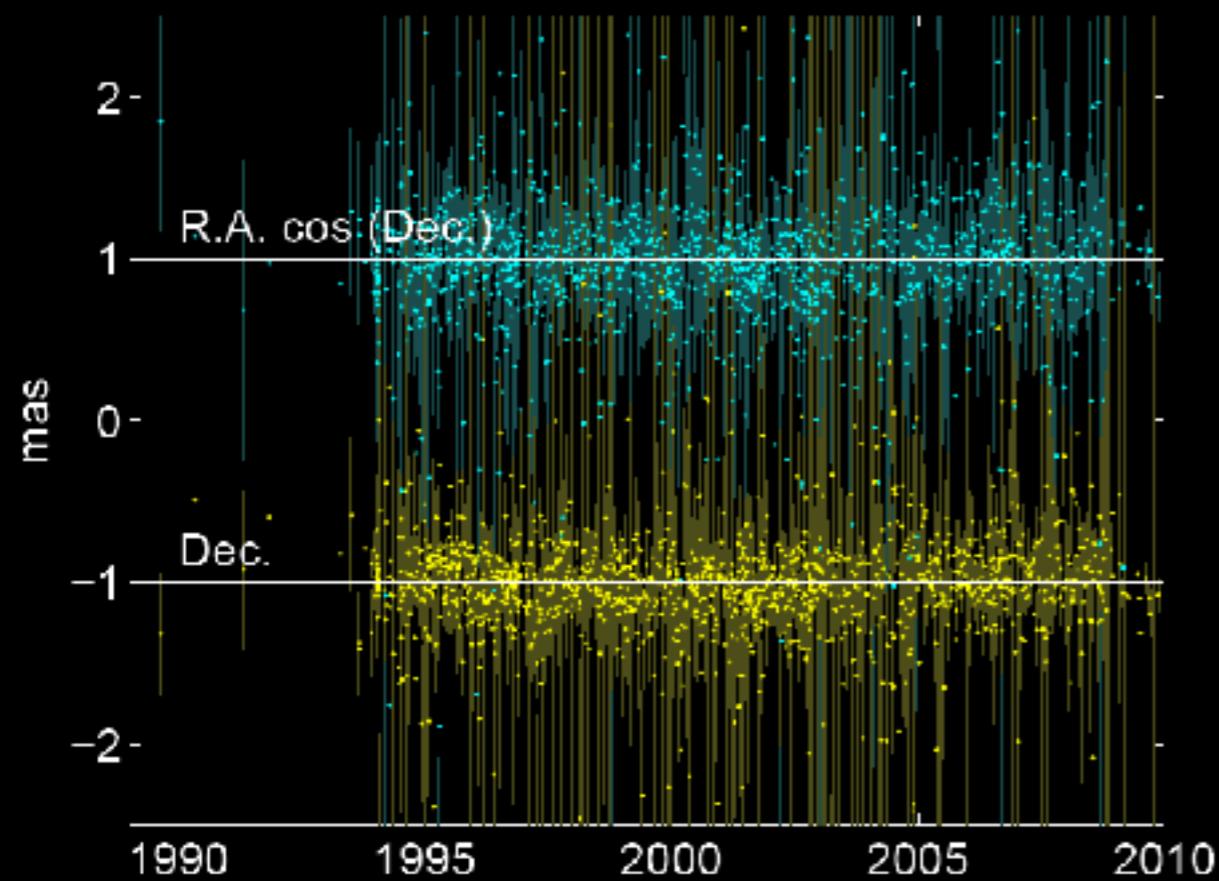
J0808+4950 at 15.350 GHz 2002 Oct 02



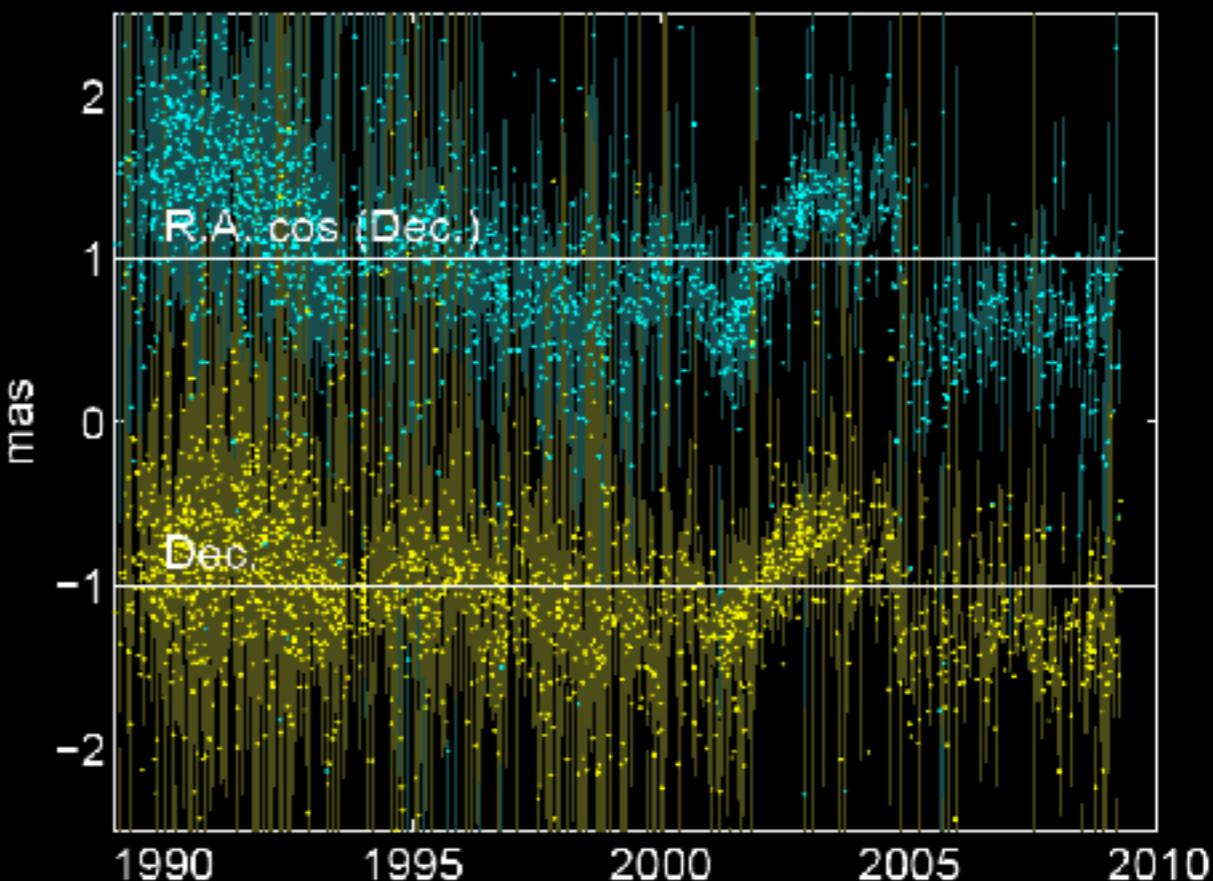
J2236+2828 at 15.350 GHz 2002 Oct 20



J0808+4950



J2236+2828



Configuration d'analyse VLBI

Modélisation du retard imparfait

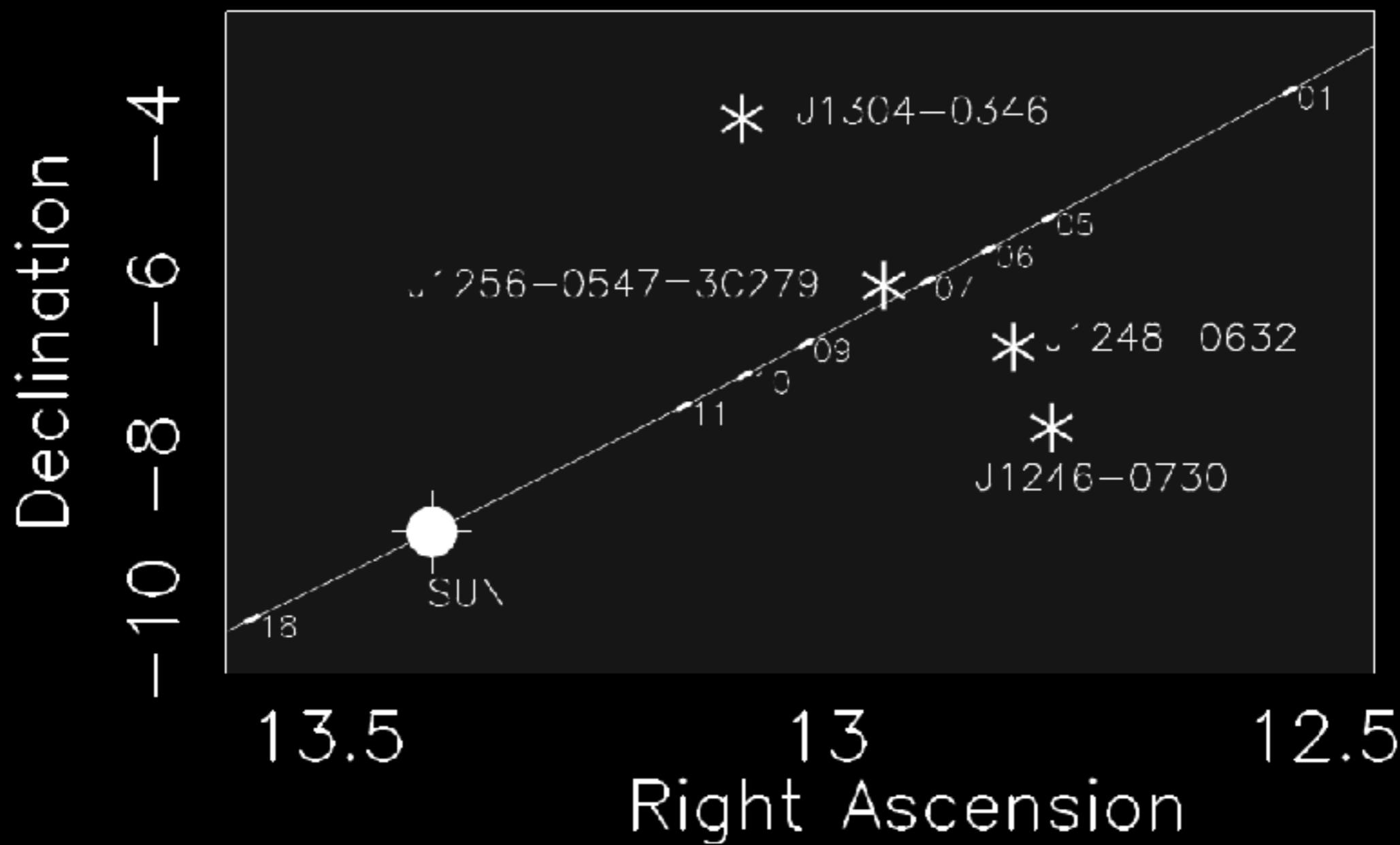
→ Estimer les écarts aux modèles

- EOP
- Déplacements des sources et stations
- ZTD et allongement troposphérique
- ...

→ Contraindre

- Rattachement aux RF
- Risque de contamination entre paramètres (ex : quasars / nutations)

Fomalont et al. 2009



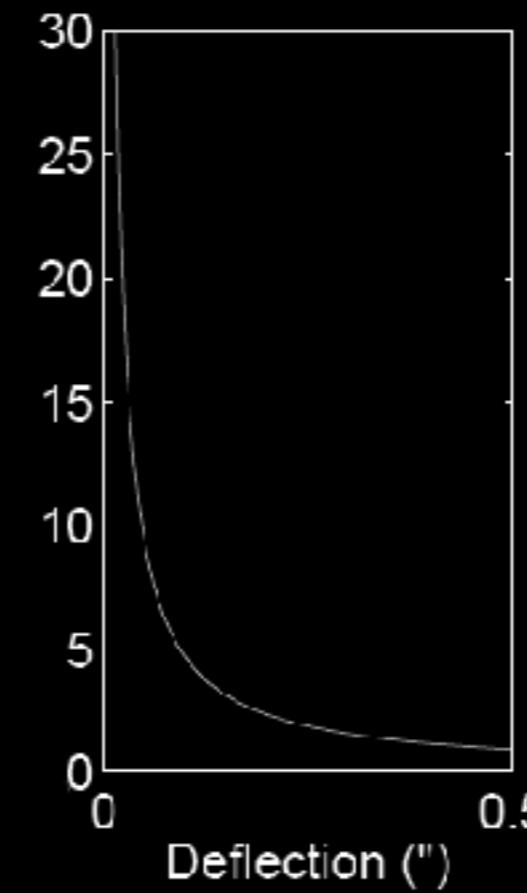
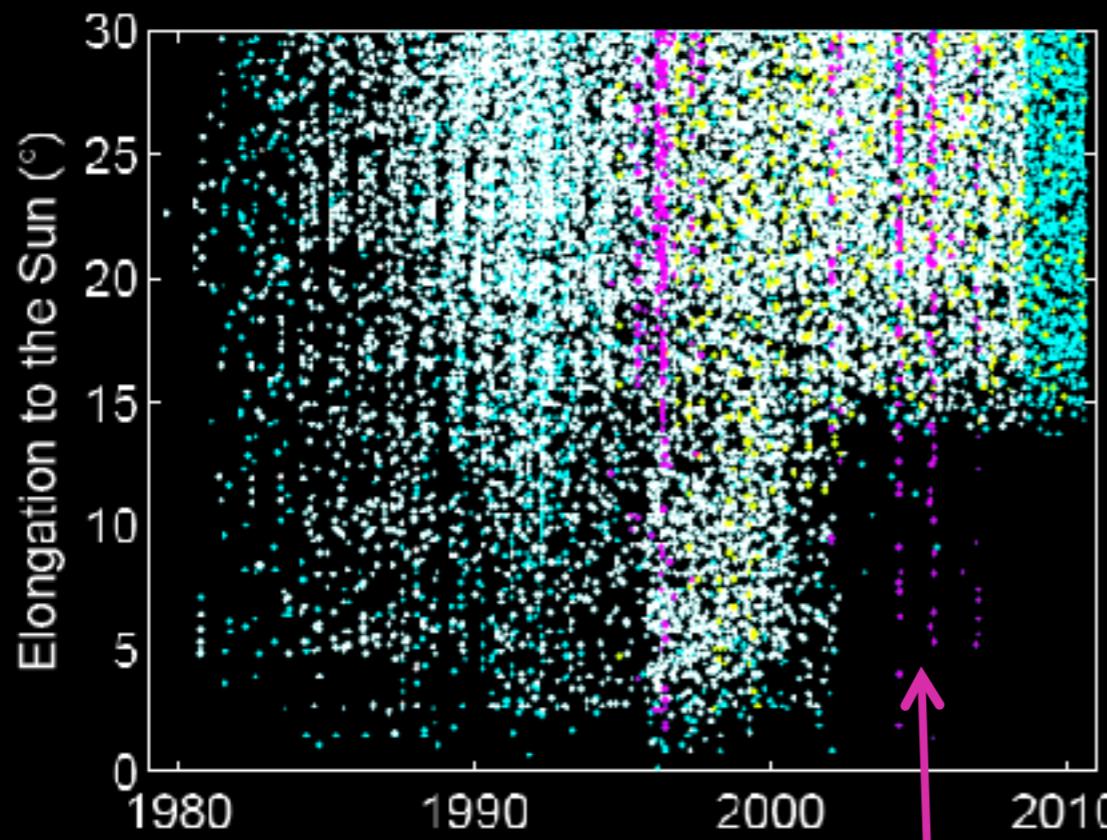
$$\gamma - 1 = 2 \pm 3 \times 10^{-4}$$

Lambert & Le Poncin-Lafitte 2009, 2010 : utilisation de la base de données VLBI complète



Activité solaire = déflexion plus forte
(Lebach et al. 1995)
~ I—10 ps

γ = coef. de « déflexion »



Sans le VLBA :
 $\gamma - I = 0.4 \pm 1.4 \times 10^{-4}$

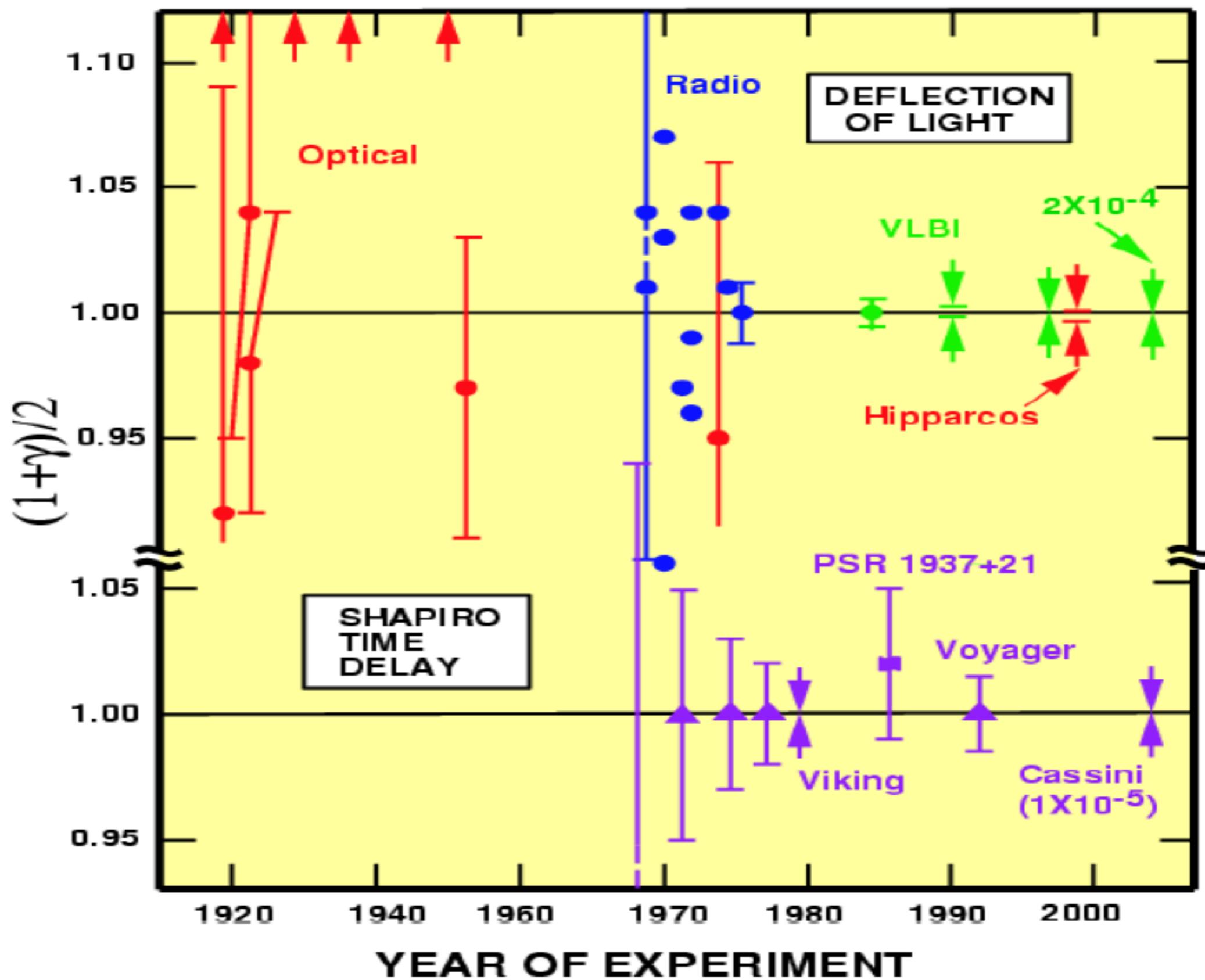
+ RDV :
 $\gamma - I = -0.7 \pm 1.3 \times 10^{-4}$

+ VCS :
 $\gamma - I = -0.8 \pm 1.2 \times 10^{-4}$

VLBA ~ 3% des sessions ~ 30% des observations

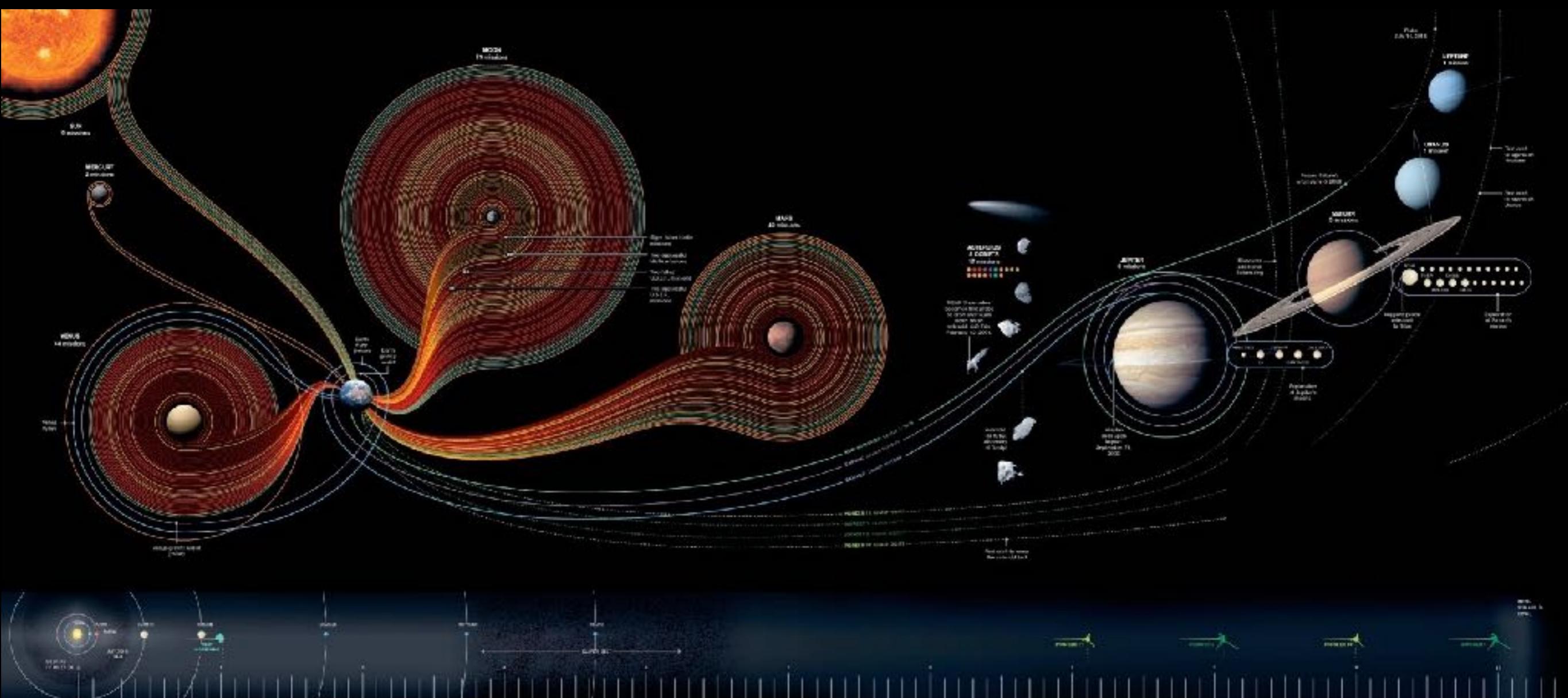
- Le VLBI mesure γ à 1.2×10^{-4} :
 - Effets coronaux difficiles à supprimer
 - Précision limitée par troposphère + structure de source
- Apport substantiel du VLBA
- Dommage que l'IVS « bloque » à 15° du soleil pour les sessions routinières
- Programmer des sources proches du soleil dans le futur...

THE PARAMETER $(1+\gamma)/2$



Exploration spatiale du Système solaire

Analyse du mouvement des corps



NOMBREUSES DONNÉES DE NAVIGATION



1. Amélioration des éphémérides
2. Amélioration des tests de la gravitation

Les éphémérides planétaires et satellitaires.

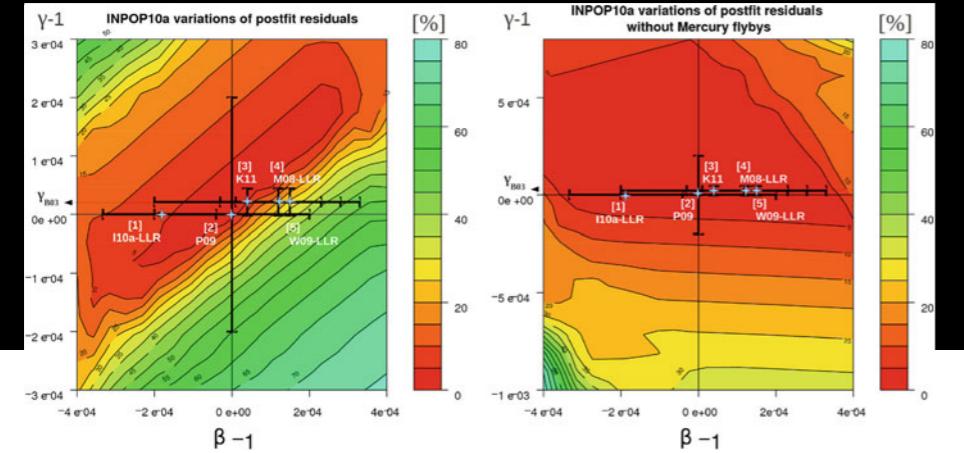
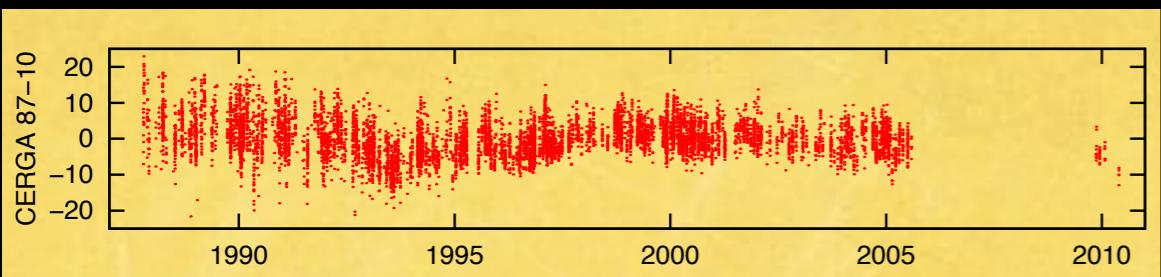


Fig. 7 Variations of postfit residuals obtained for different values of PPN β (x-axis) and γ (y-axis). [1] stands for a PPN β value obtained by Manche et al. (2010) using LLR observations with $\gamma = 0$, [2] stands for Pitjeva (2010) by a global fit of EPM planetary ephemerides. K11 stands for Konopliv et al. (2011) determinations based mainly on Mars data analysis. M08 for Müller et al. (2008) and W09 for Williams et al. (2009) give values deduced from LLR for a fixed value of γ , B03 stands for Bertotti et al. (2003) determination of γ by solar conjunction during the Cassini mission

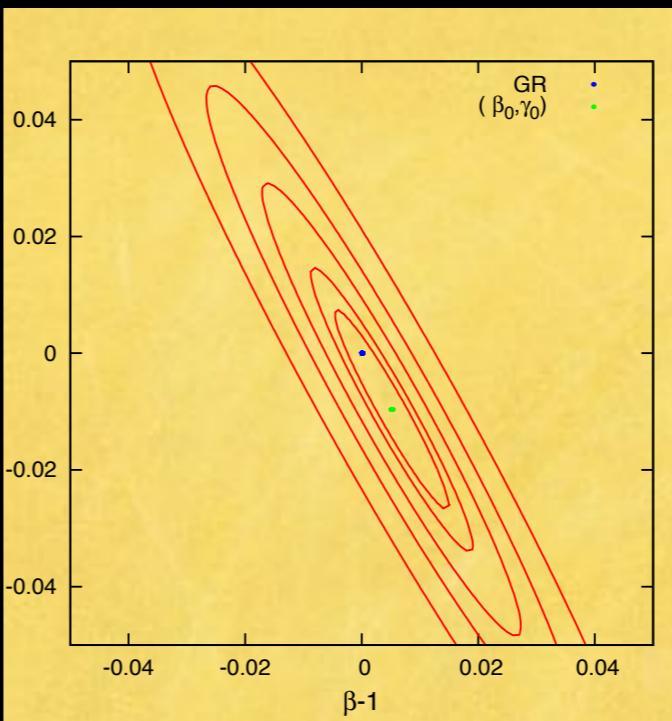
Fienga et al. 2011

Ephémérides de satellite:

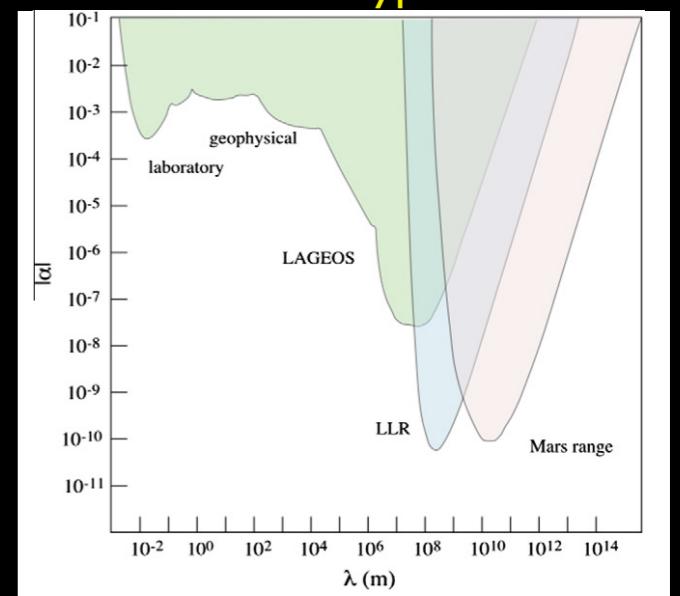
1. le mouvement de la lune (Laser-Lune)
2. les orbiteurs autour de Mars



Résidus Laser-Lune
Manche et al. 2010

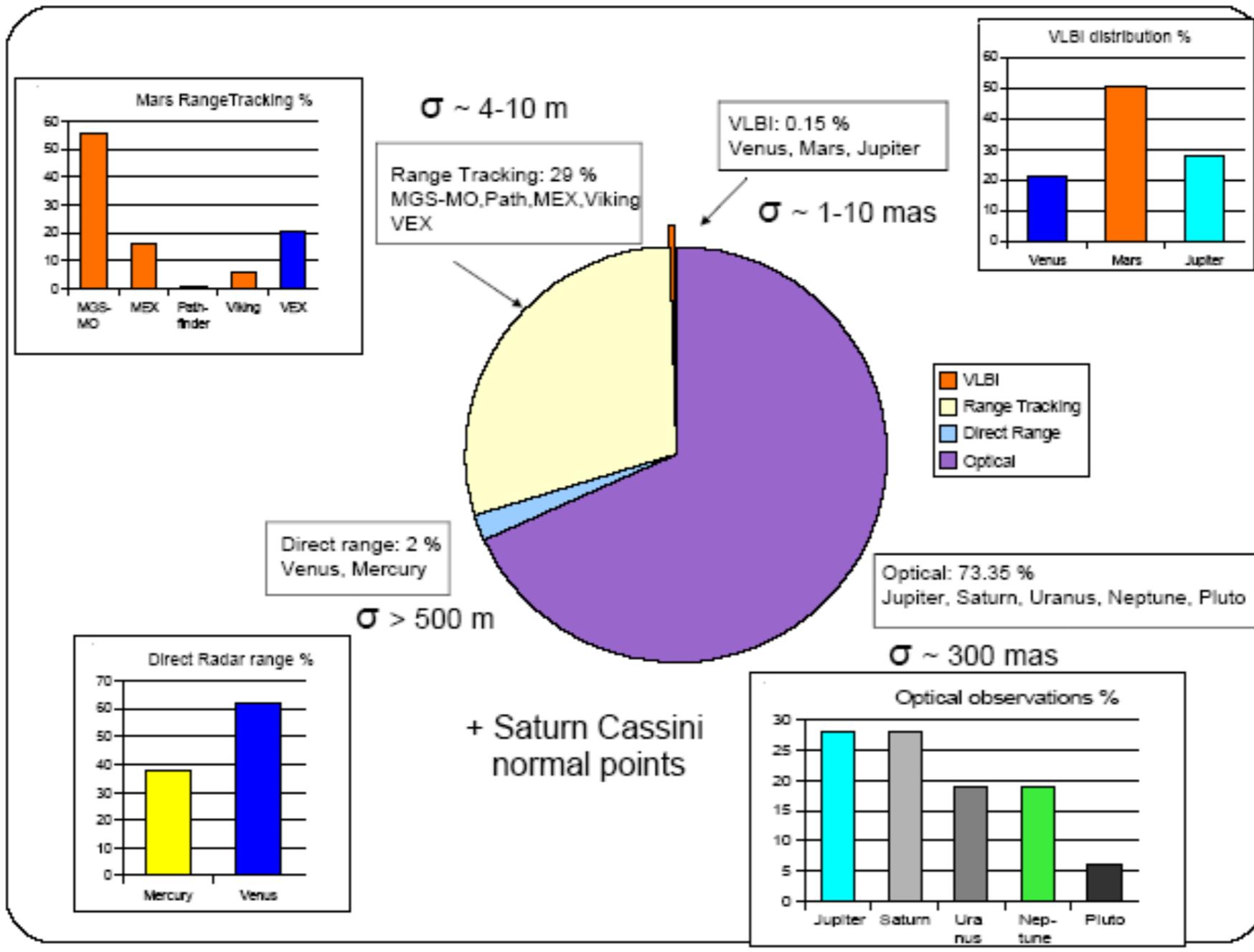


Analyse pour Mars
Déviation de type Yukawa



Konopliv et al. 2010

Ephemerides



Planet	Type of data	Time interval	<i>N</i>	INPOP06	
				$\langle(o - c)\rangle$	σ
Mercury	Radar [m]	1971–1998	444	-239	855
Venus	Radar [m]	1964–1990	737	-1727	4051
		after 1965	488	583	1385
Mars	Spacecraft VLBI [mas]	1990–1994	18	1.7	2
	Vkg lander radar [m]	1976–1983	1256	-23	18
	MGS/Odyssey radar [m]	1999–2005.45	10474	4.0	5.5
	Vkg Doppler [mm/s]	1976–1979	1501	-0.26	4.4
	Pathfinder Doppler [mm/s]	1997	1519	-0.34	0.97
	Spacecraft VLBI [mas]	1989–2003	44	0.4	0.5
Jupiter	Spacecraft VLBI [mas]	1996–1998	24	-9	12
	optical (α, δ) [mas]	1914–2004	5536	(-17; -24)	(341 ; 331)
Saturn	optical (α, δ) [mas]	1914–2004	5573	(-6; 13)	(347 ; 311)
Uranus	optical (α, δ) [mas]	1914–2004	3848	(12; 10)	(357; 366)
Neptune	optical (α, δ) [mas]	1914–2004	3898	(11; 12)	(368; 356)
Pluto	optical (α, δ) [mas]	1989–2004	1024	(11; -8)	(260; 190)

- 33 fitted GMs
 - 3 bulk densities ρ for ≈ 270 asteroids
 - tests of $\rho = \rho_0 + \rho_1 \cdot r$ [km]
 - ring ≈ 25000 small objects (Kuchynka et al.)
 - others: EMRAT, Sun J2, AU and PPN β
 - INPOP08b: AU_{IERS03} and GMs modified (GM _{\odot})
-

	Unit	DE421	INPOP06	INPOP08
Sun J2	10^{-7}	2.0	2.46 ± 0.40	1.82 ± 0.47
EMRAT		81.300569	NE	81.300540 ± 0.00005
AU-AU _{IERS03}	m	8.62	NE	8.22 ± 0.11
$\ 1 - \beta\ $		NE	$< 10^{-4}$	$<= 5.10^{-4}$



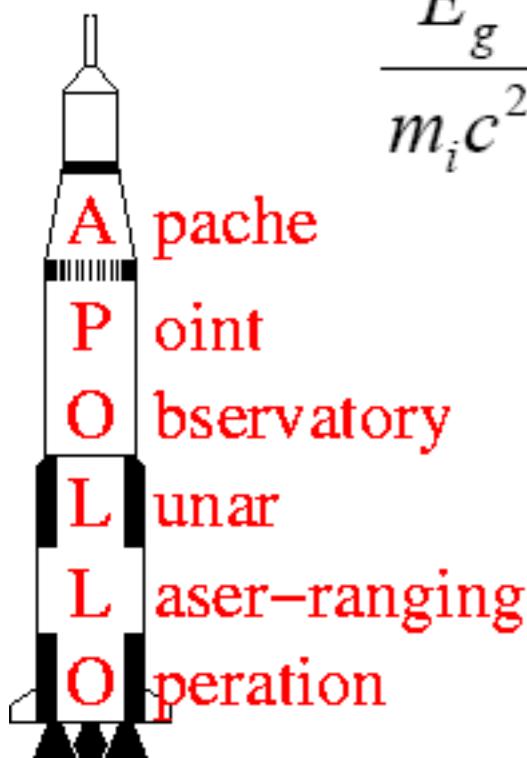
Lunar Laser Ranging and Nordtvedt effect

$$\frac{m_g}{m_i} = 1 - \eta_N \frac{E_g}{m_i c^2} = 1 + \frac{6}{5} \eta_N \frac{G m_i c^2}{R}$$

with $\eta_N = 4 \beta - \gamma - 3$

$\frac{E_g}{m_i c^2} < 10^{-27}$ for lab experiment

$$\frac{E_g}{m_i c^2} = \begin{array}{ll} 3.6 \cdot 10^{-6} & \text{Sun} \\ 10^{-8} & \text{Jupiter} \\ 4.6 \cdot 10^{-10} & \text{Earth} \\ 2 \cdot 10^{-11} & \text{Moon} \end{array}$$

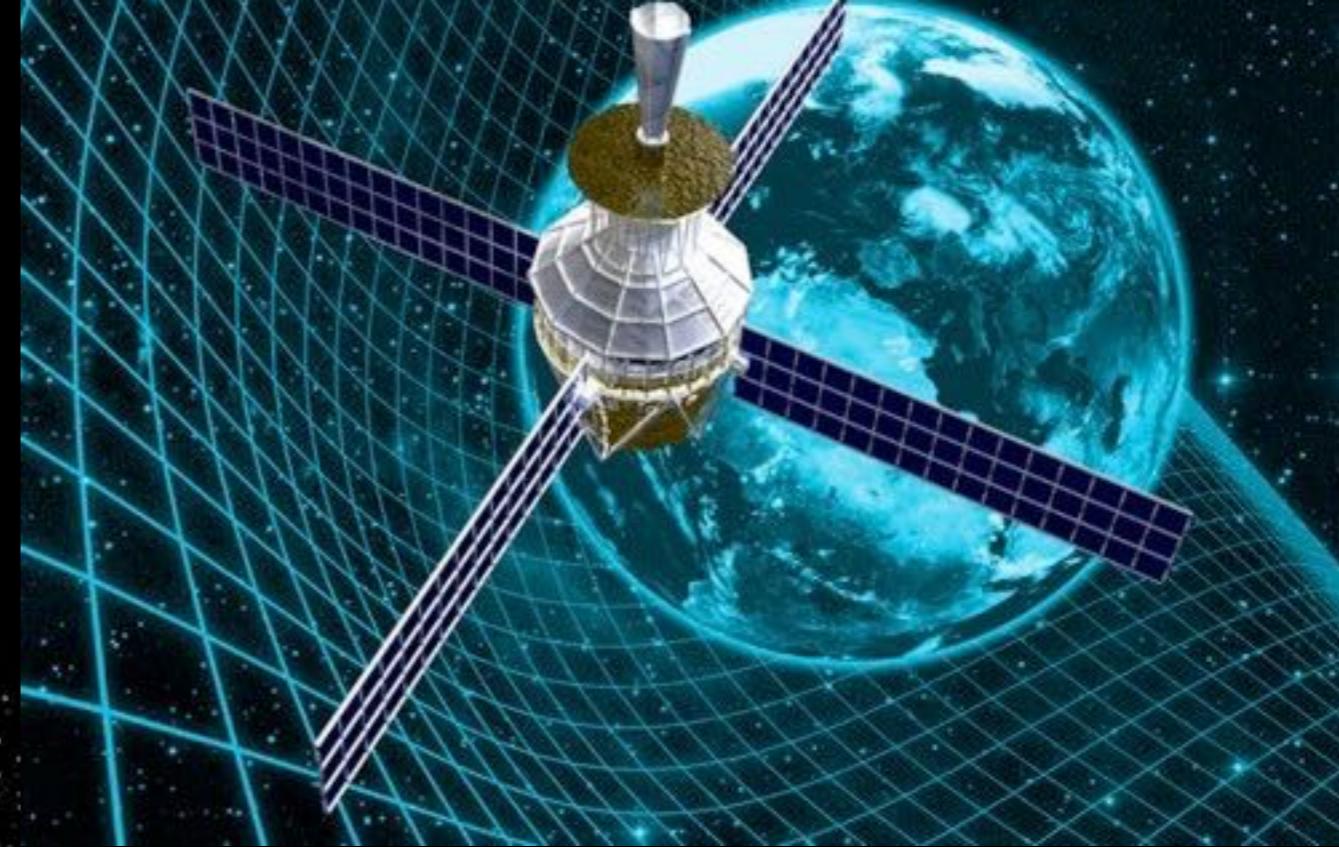
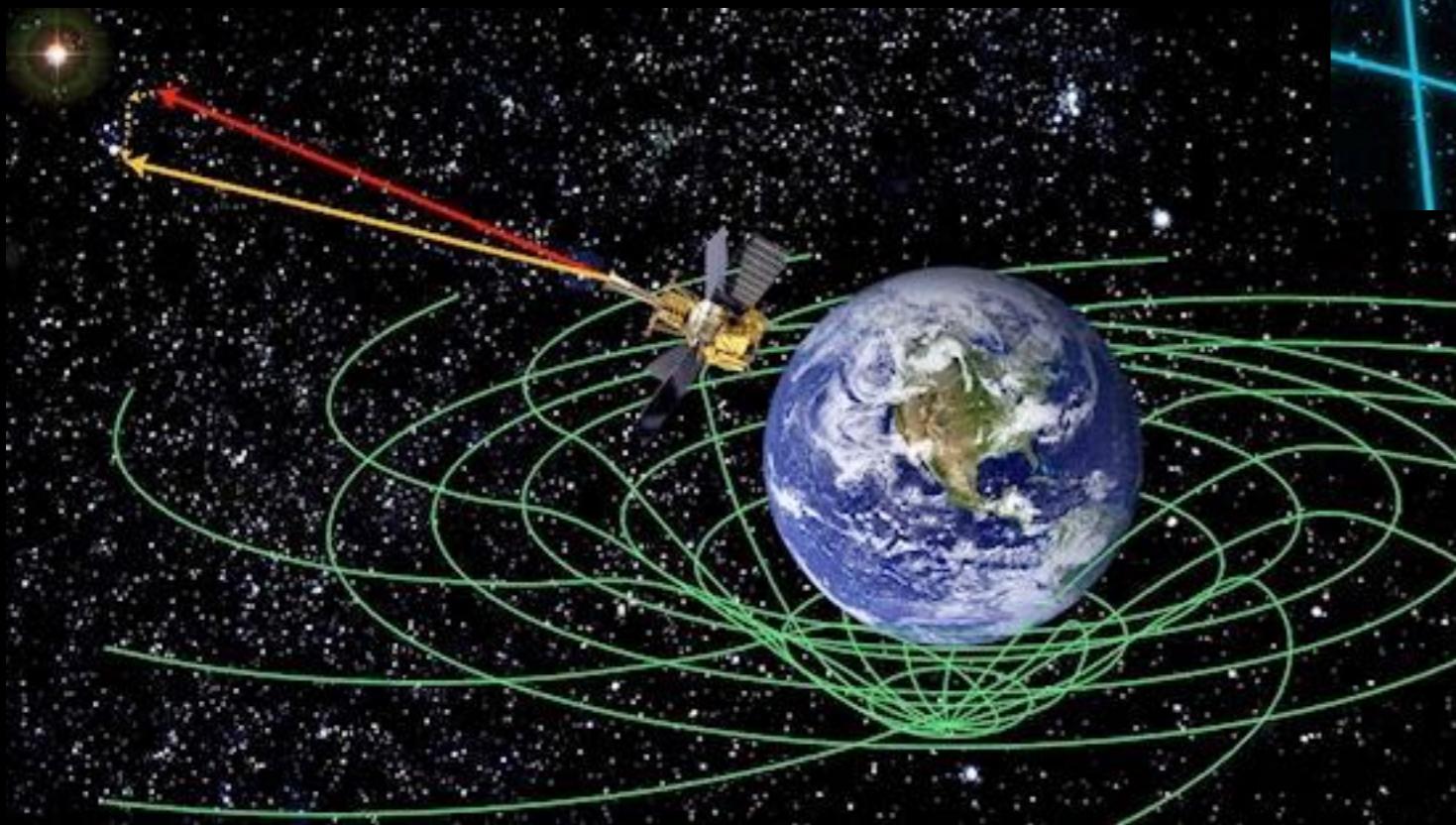


$$\eta_N = (4.4 \pm 4.5) \cdot 10^{-4}$$



précession d'accord !
mais pas que du périhélie...

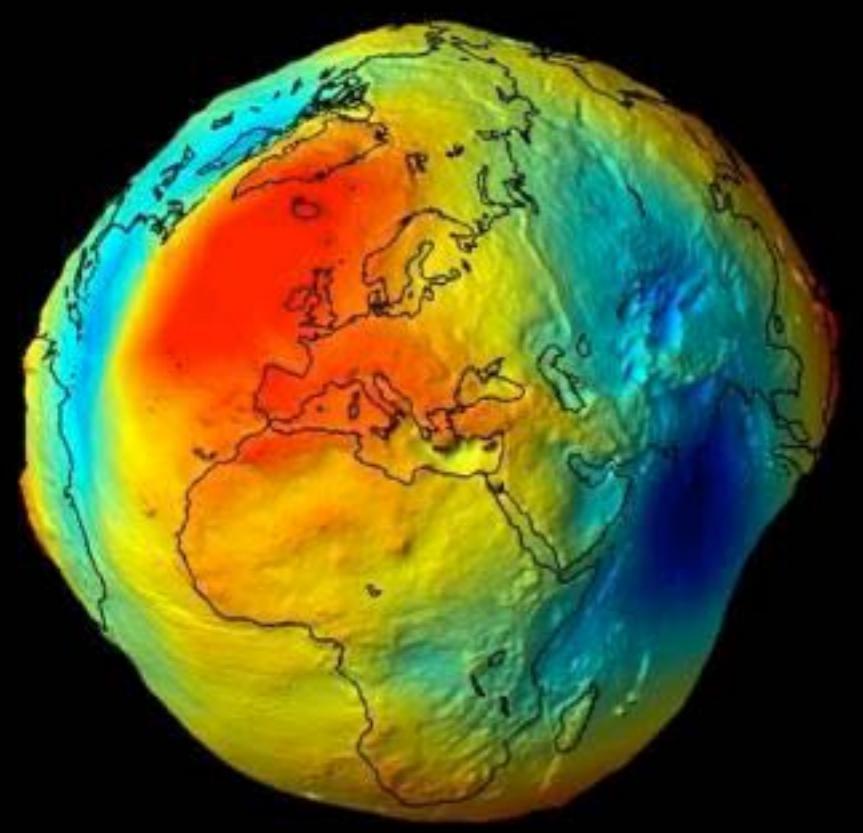
l'expérience Gravity Probe B



But : mesurer la précession de Lense Thirring

gyroscope de GPB

Projet le plus long de l'histoire spatiale :
idée proposée dans les années 50... Lancement le 20 Avril 2004 !
Malheureusement, les gyroscopes n'ont pas été performants...



L'apport de la géodésie spatiale

Multiples techniques

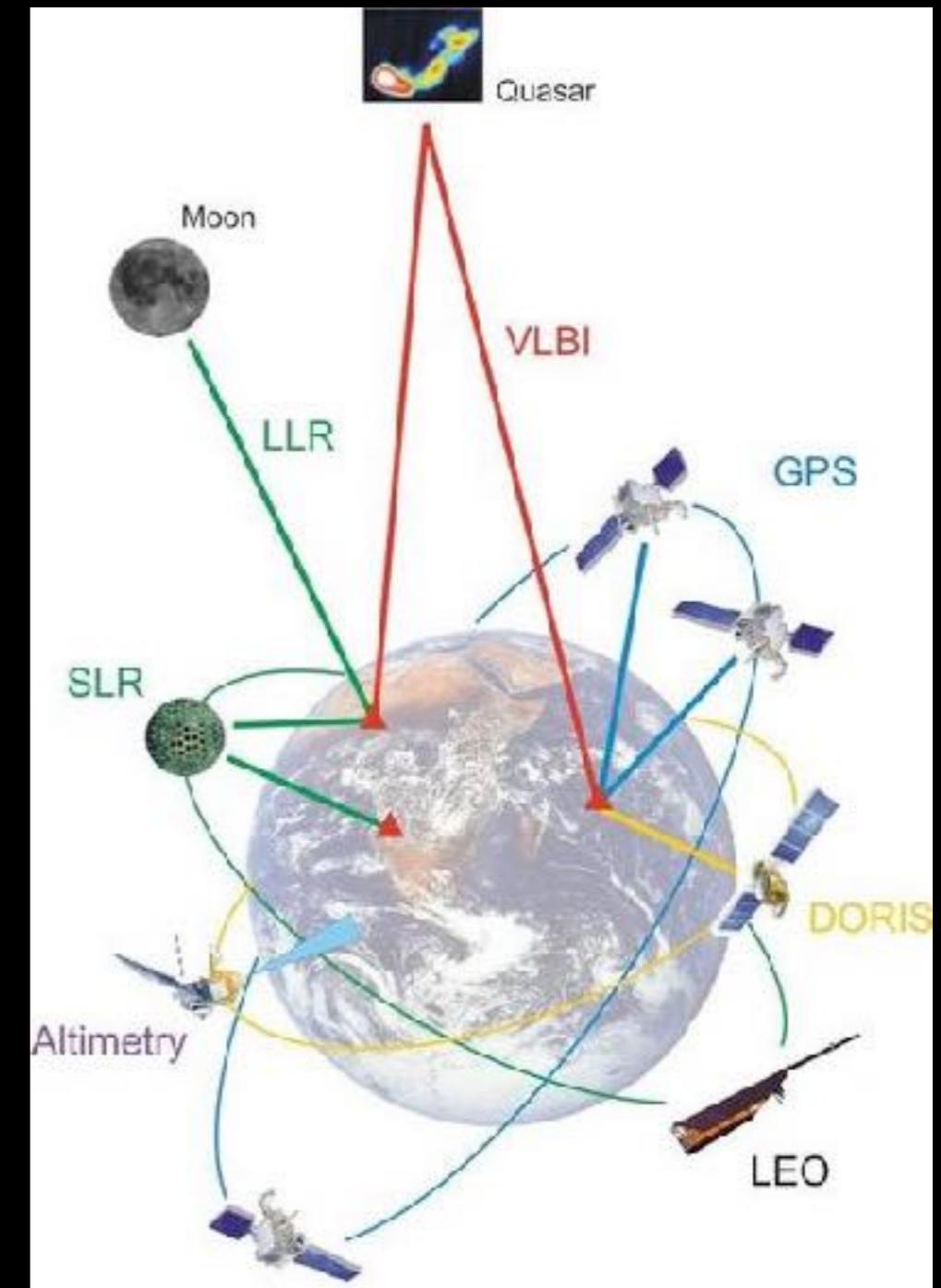
Comprendre la dynamique interne
de la Terre

Déterminer le champ de gravité

Se positionner correctement



Effet Lense-Thirring grâce à LAGEOS
Ciufolini & Pavlis, Nature 2004



Gaia will offer two ways to test GR

measurement of the
light deflection by
the Sun & planets

probing space-time with
massless particles: spatial
and temporal part of metric

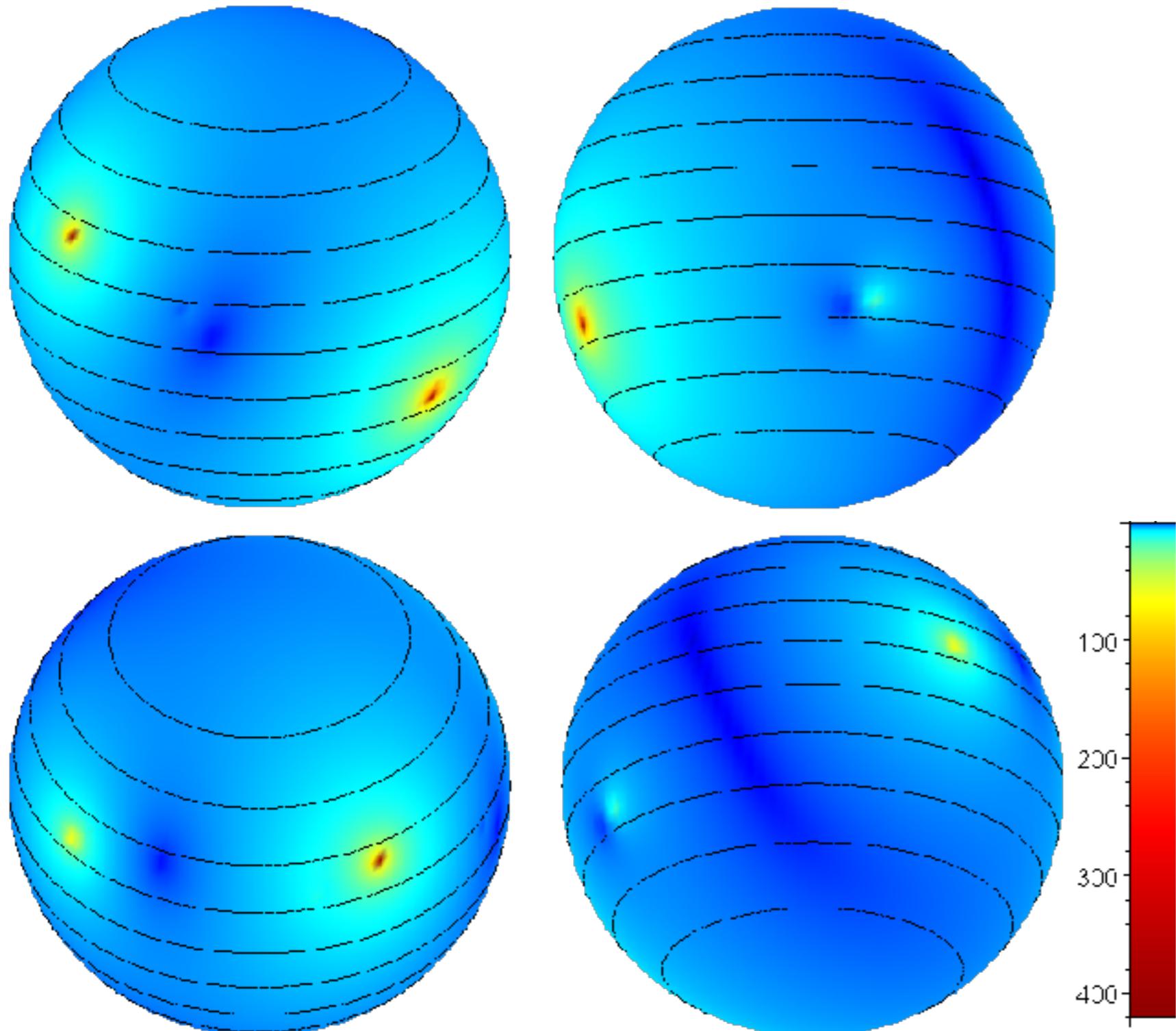
orbital dynamics of
Solar System
Objects

probing space-time with
massive test bodies: mainly
spatial part of metric



Light deflection : how much ?

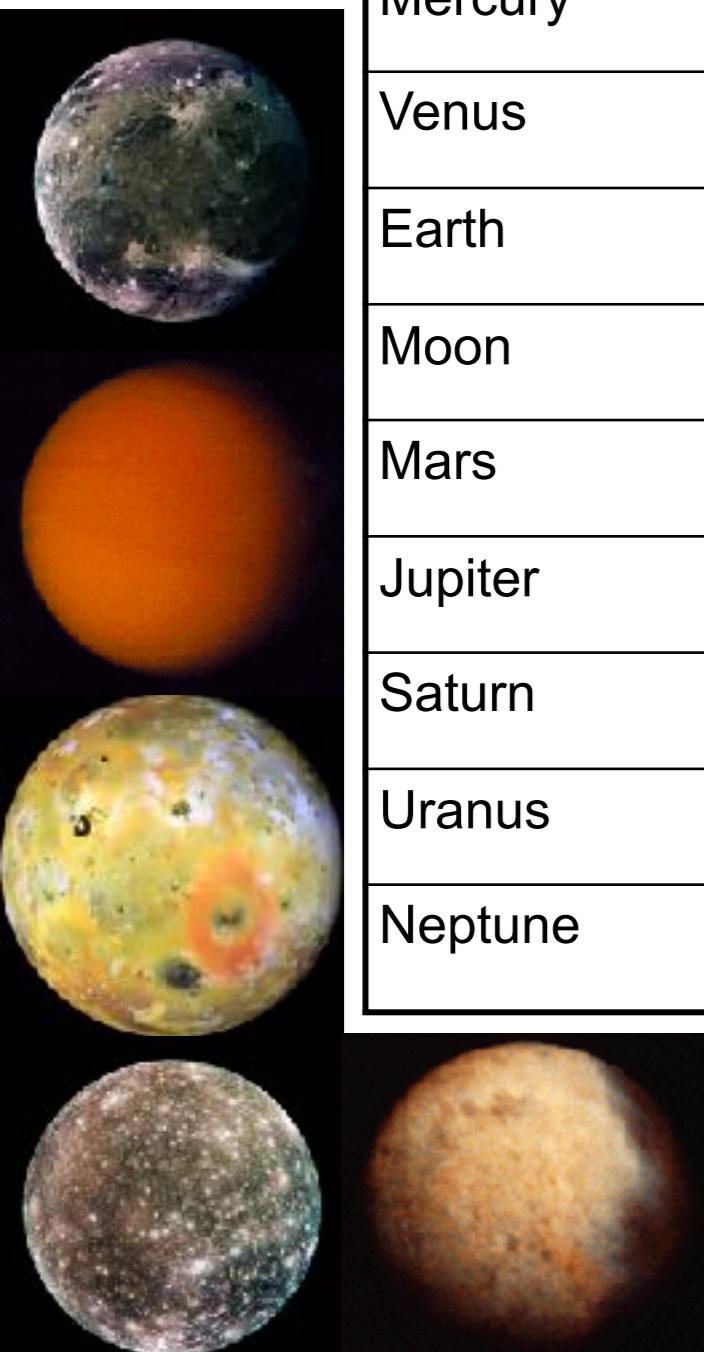
- Monopole light deflection: distribution over the sky on 25.01.2006 at 16:45 equatorial coordinates



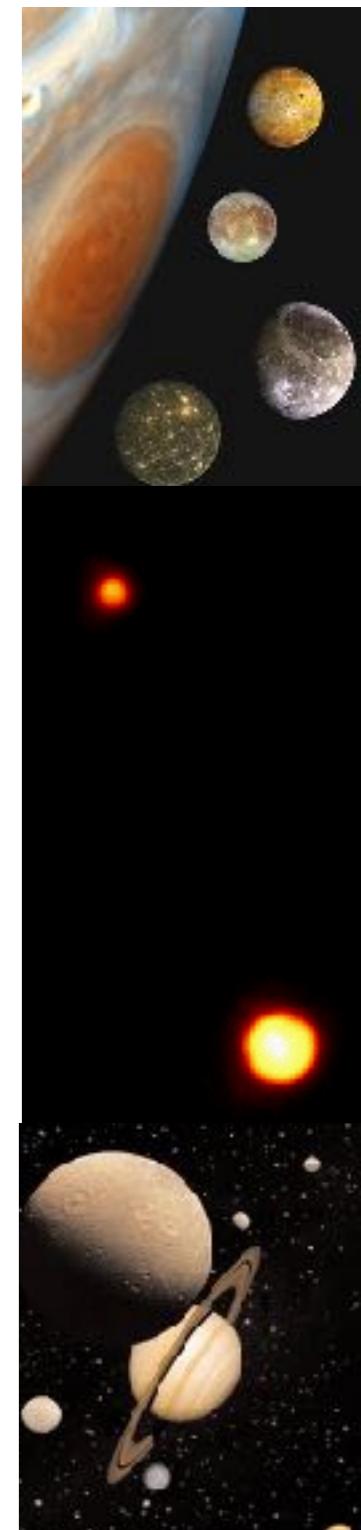
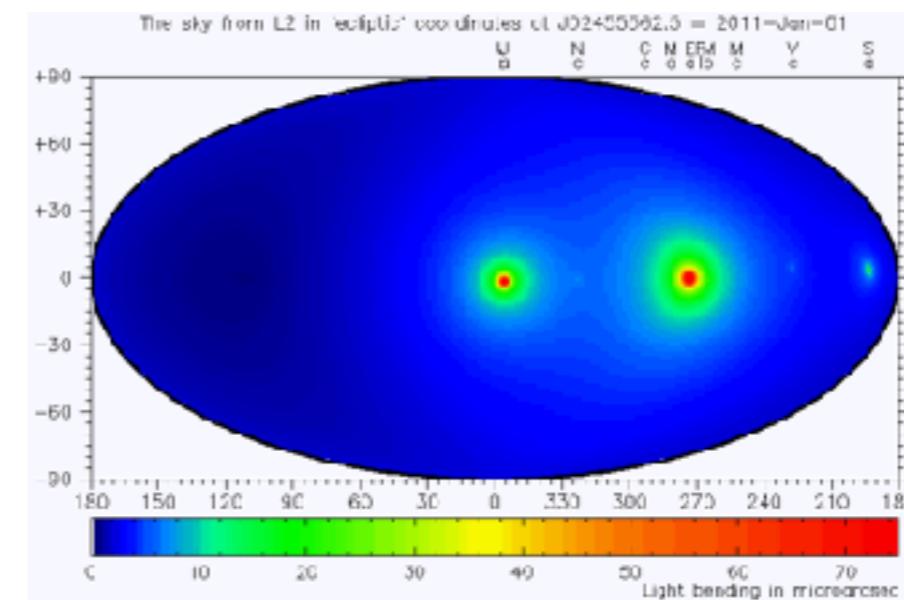
body	(μ as)	$>1\mu$ as
Sun	1.75''	180 °
Mercury	83	9 '
Venus	493	4.5 °
Earth	574	125 °
Moon	26	5 °
Mars	116	25 '
Jupiter	16270	90 °
Saturn	5780	17 °
Uranus	2080	71 '
Neptune	2533	51 '

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Order of magnitude for monopole light deflection.



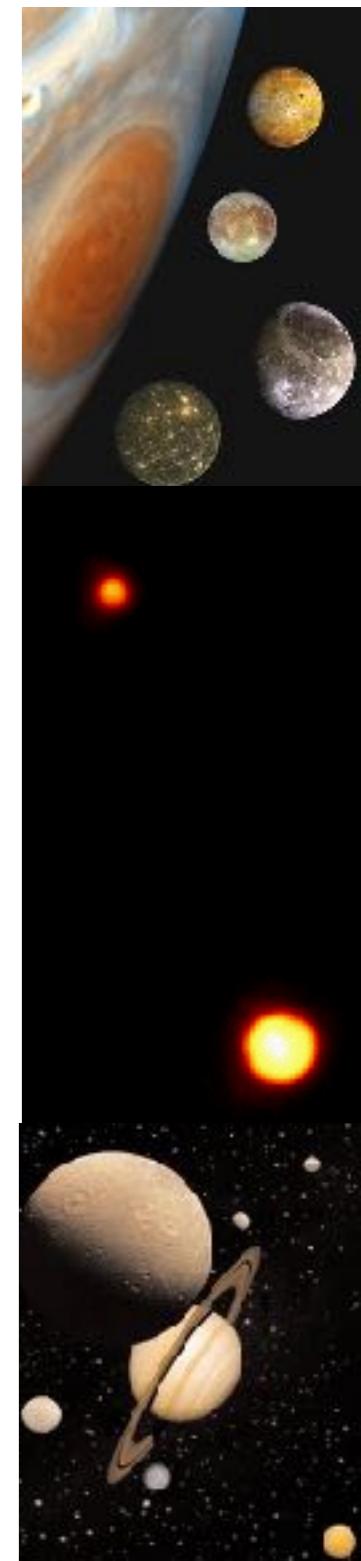
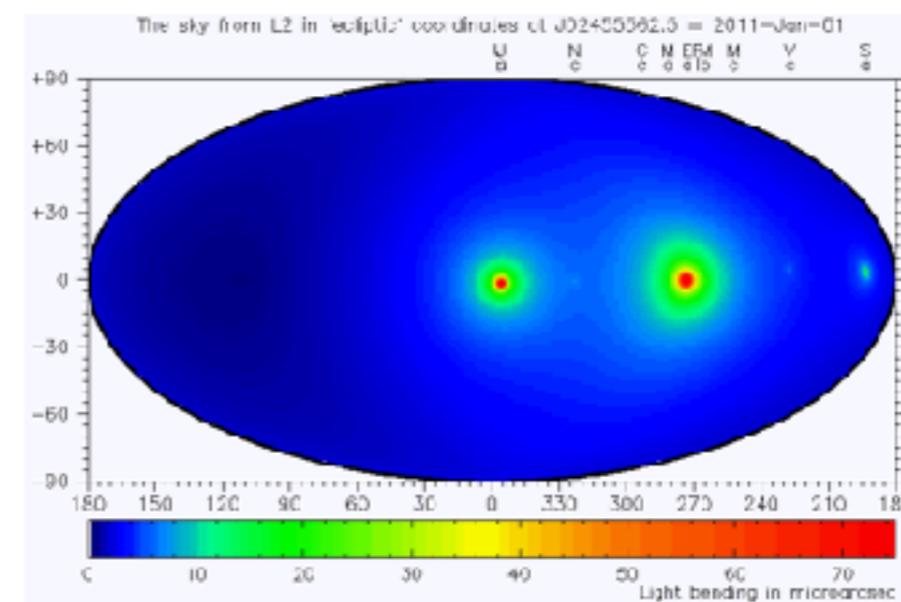
Minor bodies :

Ganymede	35
Titan	32
Io	30
Callisto	28
Pluto	7
Charon	4
Titania	3
Ceres	1

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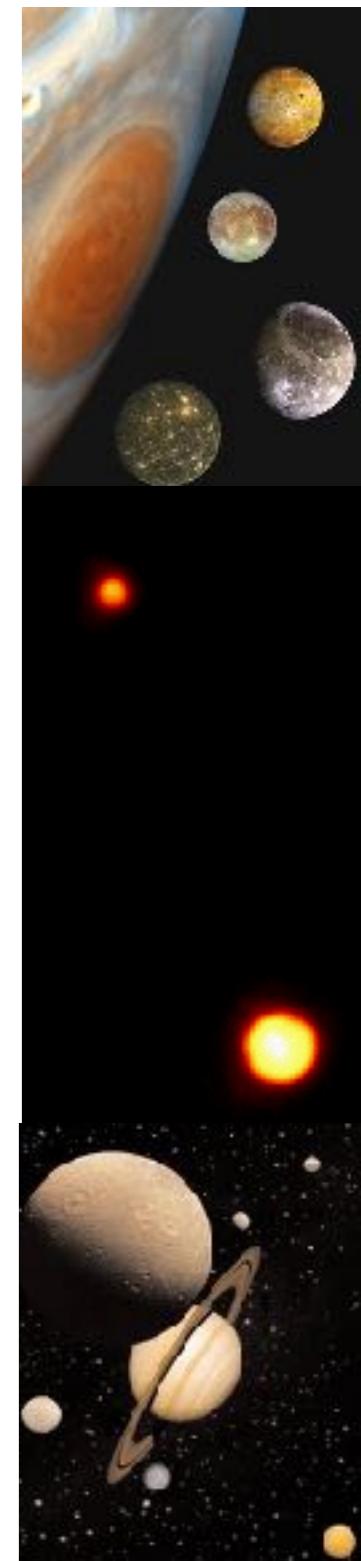
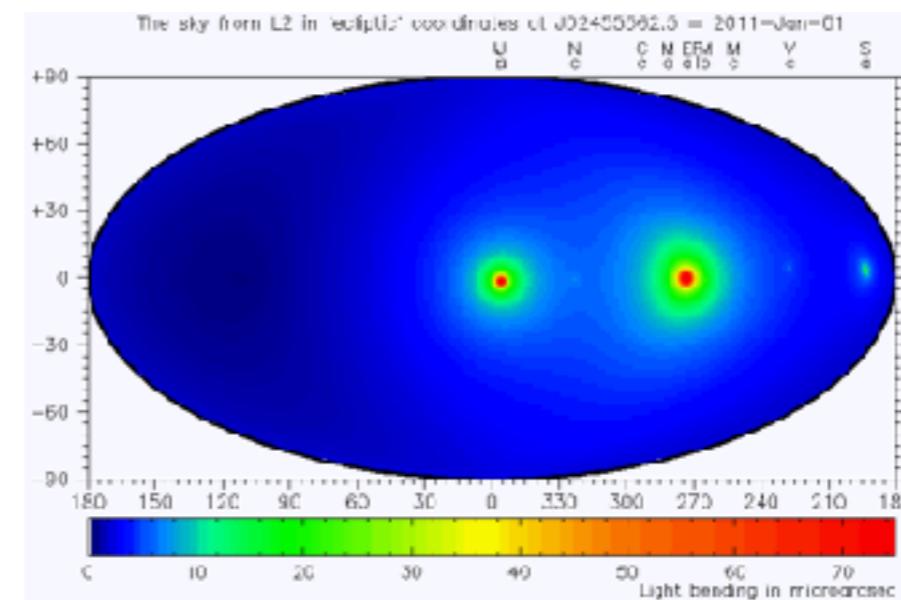
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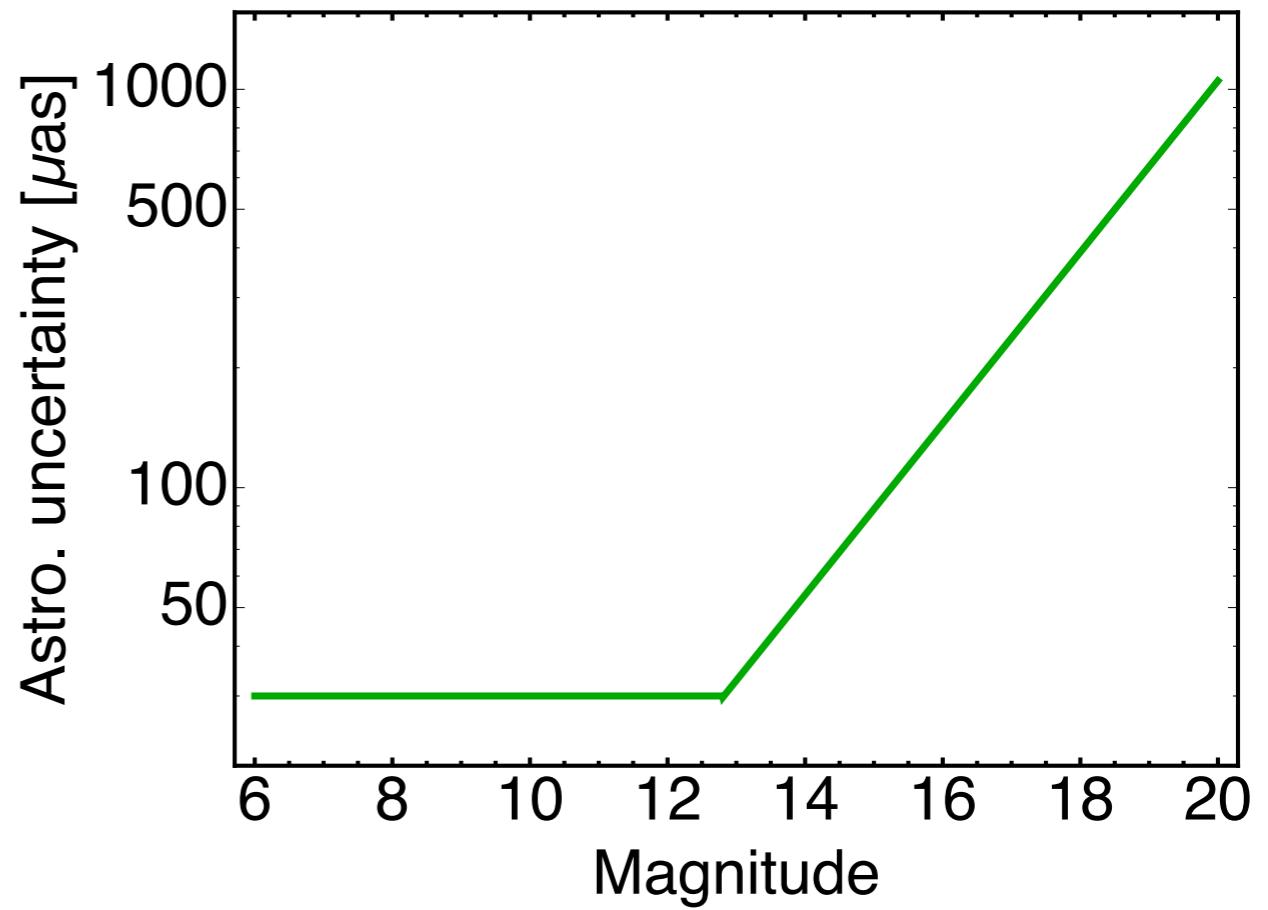
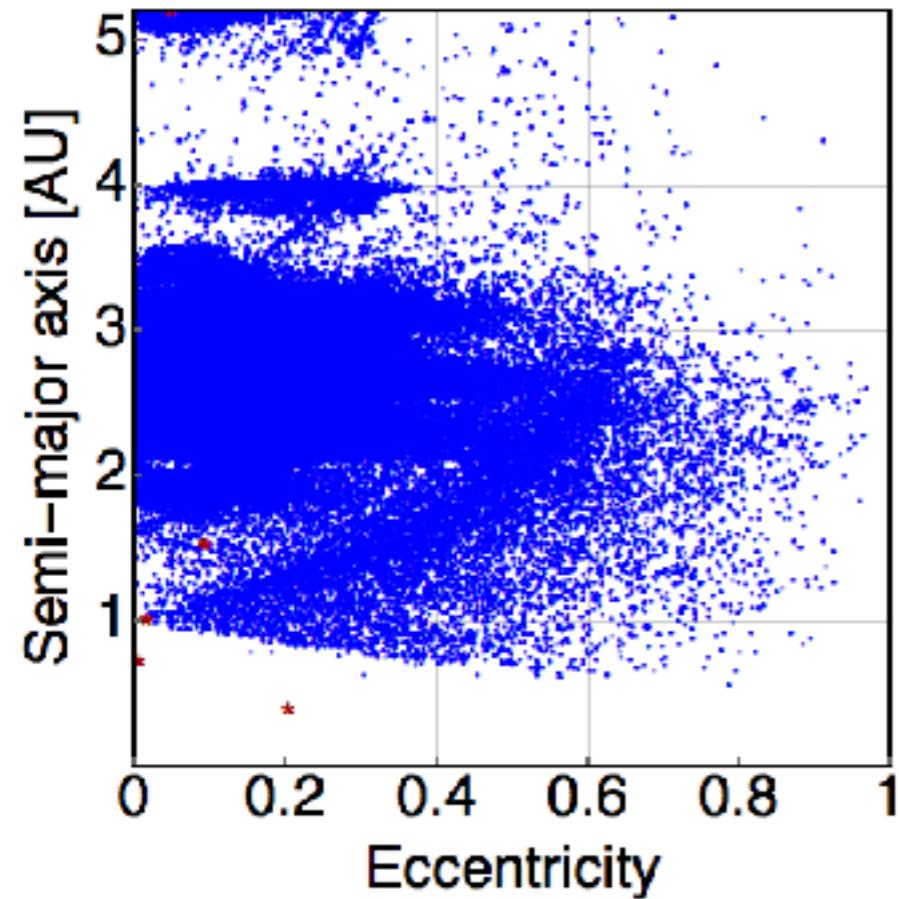


Minor bodies :

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Pluto	7
Charon	4
Titania	3
Ceres	1

Gaia will observe \sim 400 000 SSO's

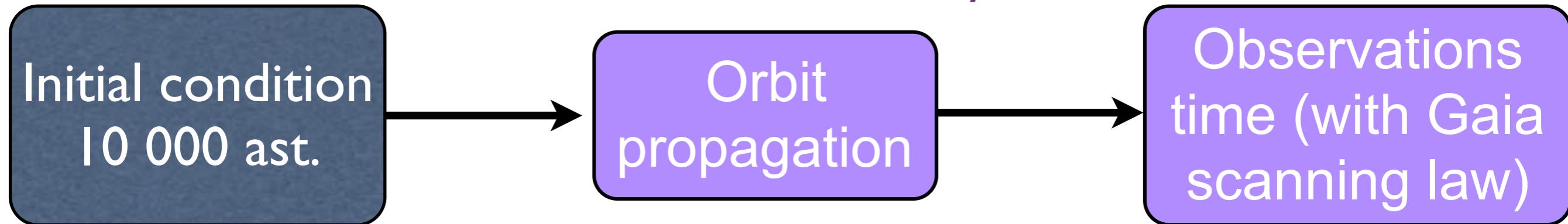
- Use GAIA SSO's observations to test GR: advantage of a large samples of different orbital parameters
 - decorrelation of parameters
 - complementary to planetary ephemerides (different bodies, different type of observations, different method to analyze the data)
- Uncertainty used in simulations depends on magnitude



- Simulations done for 5 years and also for 10 years (extended mission)

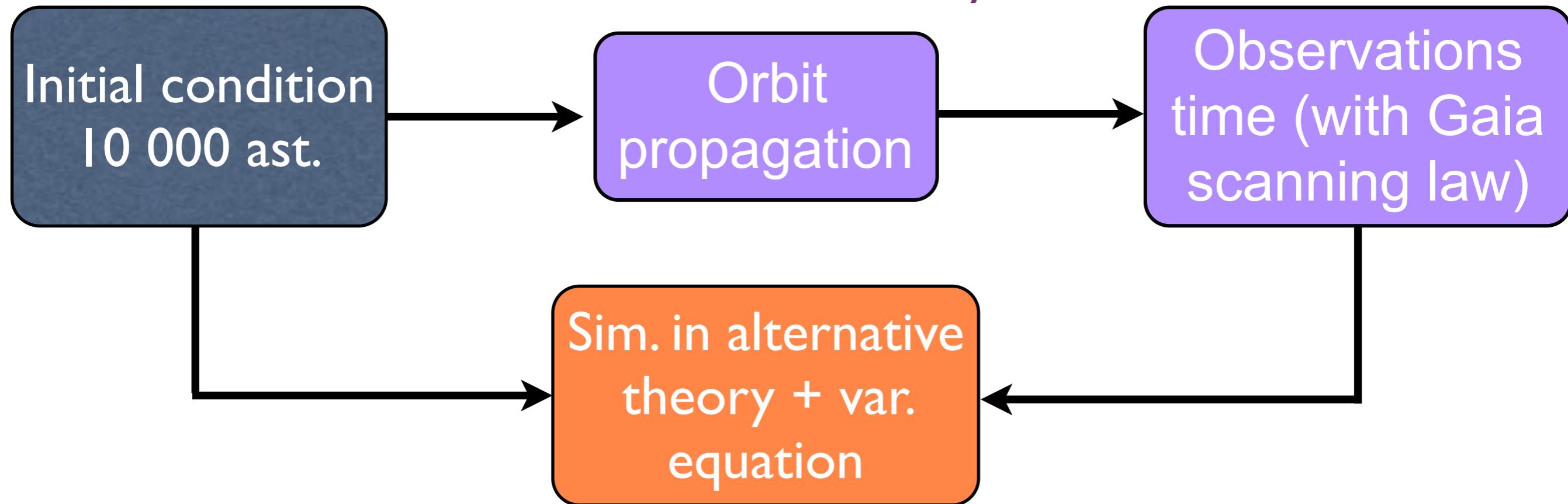
Simulations of Gaia observations

done by Gaia WP DU460



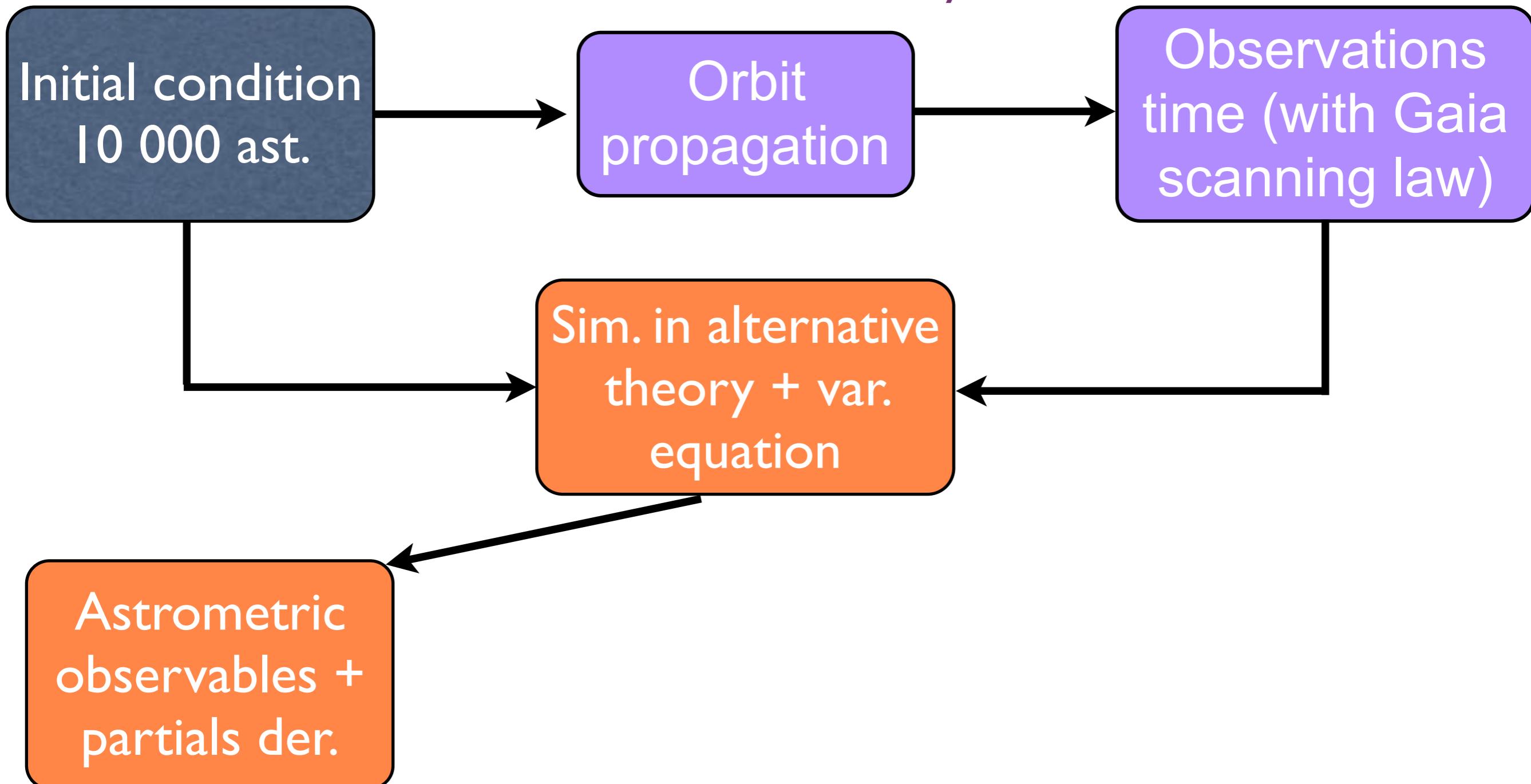
Simulations of Gaia observations

done by Gaia WP DU460



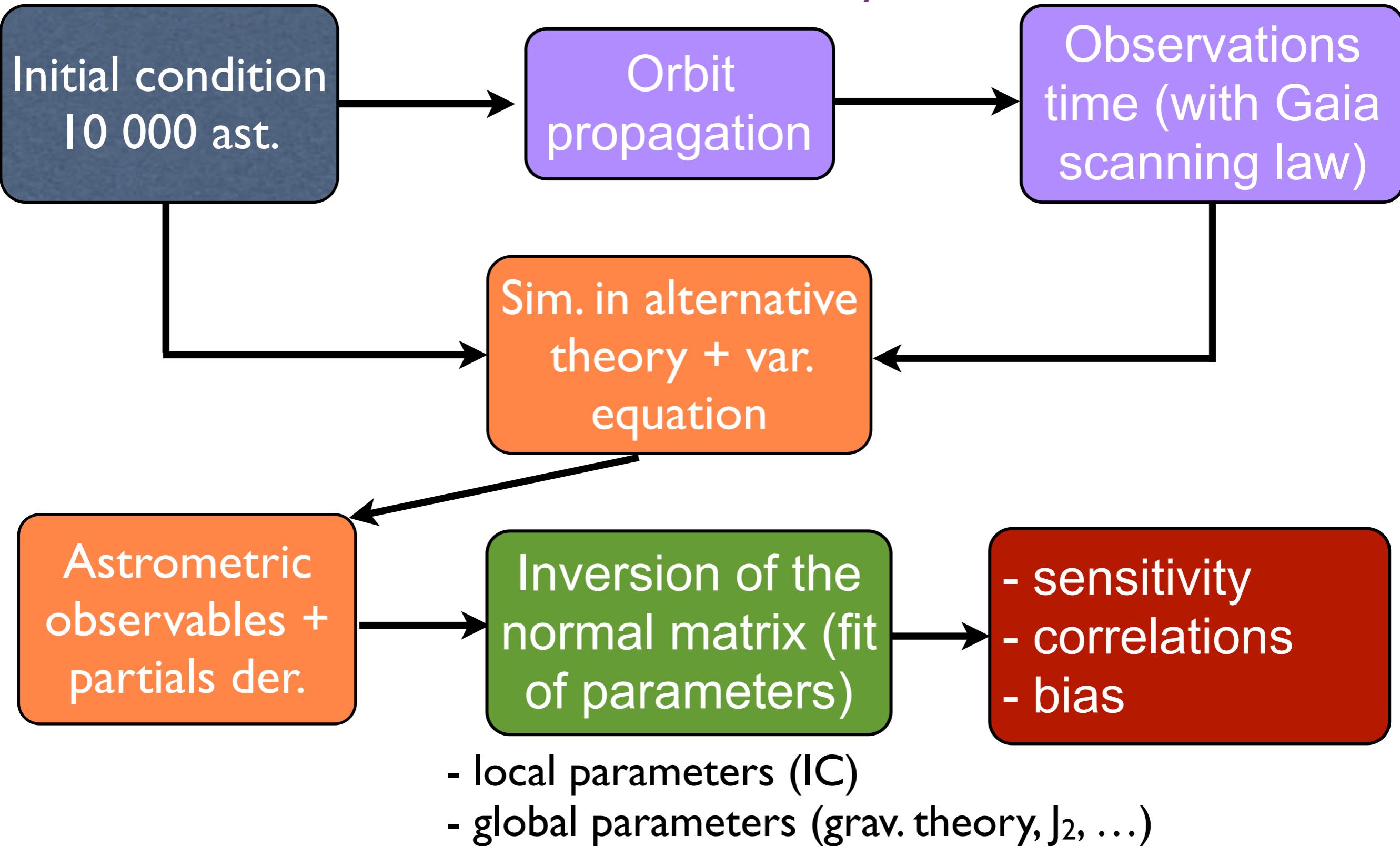
Simulations of Gaia observations

done by Gaia WP DU460



Simulations of Gaia observations

done by Gaia WP DU460



PPN formalism and Sun J_2

- highly correlated parameters: secular effect on orbital dynamics

$$\left\langle \frac{d\omega}{dt} \right\rangle = (2 + 2\gamma - \beta)n \frac{GM}{c^2 a(1 - e^2)} + \frac{3}{2}n \frac{J_2 R^2}{a^2 (1 - e^2)^2}$$

- various asteroids orbital parameters help to decorrelate
- sensitivity:

	J_2	β
GAIA [5yr]	$\sigma_{J_2} \sim 5 \times 10^{-8}$	$\sigma_\beta \sim 4 \times 10^{-4}$
GAIA [10yr]	$\sigma_{J_2} \sim 1.5 \times 10^{-8}$	$\sigma_\beta \sim 10^{-4}$
INPOP	$(2.22 \pm 0.13) \times 10^{-7}$	$(0.0 \pm 6.9) \times 10^{-5}$

- correlation ~ 0.4 INPOP results from A. Fienga et al, Cel. Mech. Dyn. Astro. 2015
- complementary to planetary ephemerides: different analysis, not the same systematics
- Interesting: combined fit Gaia + planets

Test of the SEP can help to decorrelate β and J_2

- SEP: Universality of free fall violated for self-gravitating body

see K. Nordtvedt, Phys. Rev., 169, 1014, 1968

$$m_p = m_i + \eta \frac{E_{\text{grav}}}{c^2} \quad m_i \vec{a} = m_p \vec{\nabla} U$$

- Gaia can constrain η at 3×10^{-4} [3×10^{-5} if extended mission] while the current best constraint from LLR is $\eta = (4.4 \pm 4.5) \times 10^{-4}$

see J. Williams et al, IJMPD, 18, 1129, 2009

- In the PPN formalism $\eta = 4\beta - \gamma - 3$ helps to estimate β

	J_2	β	
GAIA [5yr]	$\sigma_{J_2} \sim 4 \times 10^{-8}$	$\sigma_\beta \sim 8 \times 10^{-5}$	no correlation
GAIA [10yr]	$\sigma_{J_2} \sim 1.3 \times 10^{-8}$	$\sigma_\beta \sim 8 \times 10^{-6}$	
INPOP	$(2.22 \pm 0.13) \times 10^{-7}$	$(0.0 \pm 6.9) \times 10^{-5}$	remaining

INPOP results from A. Fienga et al, Cel. Mech. Dyn. Astro. 2015

- Considering a violation of the SEP reduces σ_β by a factor 5

A fifth force is a well motivated phenomenology

- deviation from Newtonian gravity characterized by a Yukawa potential

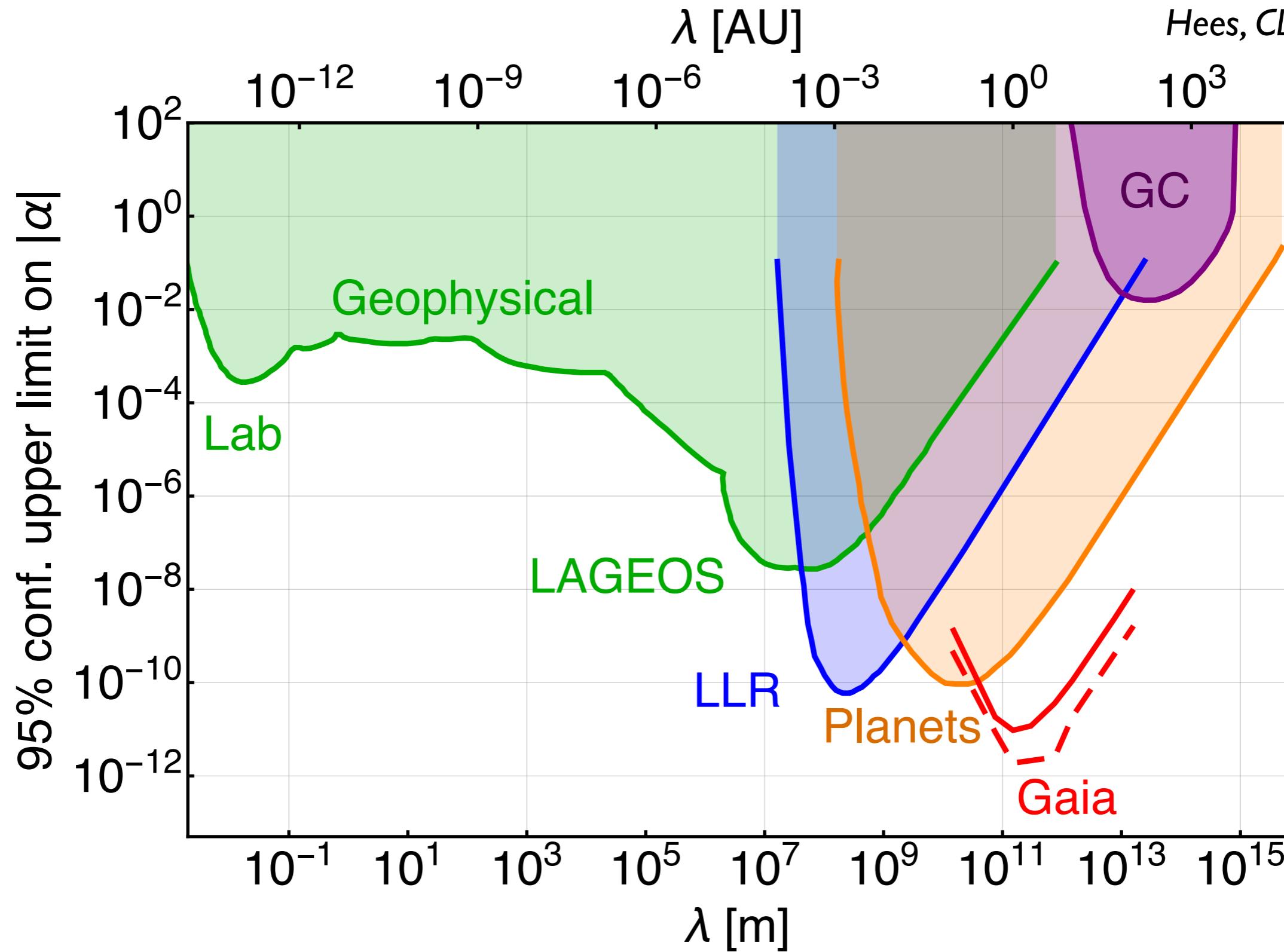
$$\phi(r) = \frac{GM}{c^2 r} \left(1 + \alpha e^{-r/\lambda} \right)$$

See E.G. Adelberger, Progress in Part. and Nucl. Phys., 62/102, 2009
“The Search for Non-Newtonian gravity”, E. Fischbach, C. Talmadge, 1998

- Phenomenology motivated by
 - new interaction with a massive gauge boson Fischbach and Talmadge, Nature, 1989
 - high dimension theories Krause and Fischbach, arXiv: hep-ph/9912276
 - Braneworld scenarios Arkani-Hamed, et al, PRD, 1999
 - massive gravity Will, PRD, 1998
 - massive tensor-scalar theory Alsing, et al, PRD, 2012
 - ...

A fifth force can be tested with Gaia

Hees, CLPL, 2017



correlation with the Sun GM needs to be assessed carefully

Lense-Thirring effect due to the Sun

- Relativistic frame dragging effect produced by the rotation of a body (due to the Spin S)
- impossible to estimate the Sun Lense-Thirring with planetary ephemerides: completely correlated with J_2 see W. Folkner et al, IPN, 2014

- Asteroids can decorrelate but Gaia not powerful enough

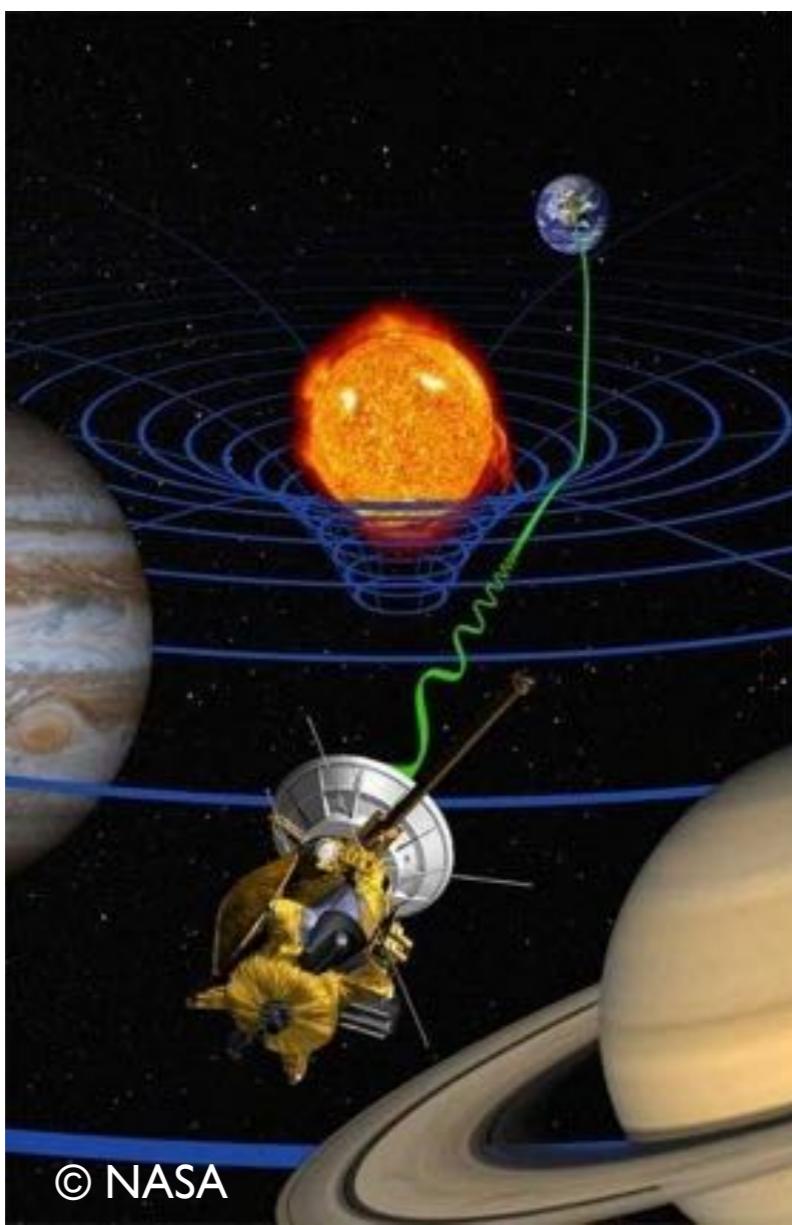
$$\frac{\sigma_S}{S} \sim 6.5 \quad [1.7 \text{ for 10yr}]$$

- Combination with radar observations to be considered
- But... not including the LT in the modeling leads to bias:
 - 10^{-8} on the J_2 (i.e. 10% of its value)
 - 5×10^{-5} on the β PPN

Constraints on PPN parameters

- Measurement of the Shapiro time delay with Cassini¹

$$\gamma - 1 = (2.1 \pm 2.3) \times 10^{-5}$$



© NASA

- Planetary ephemerides INPOP²
 $\beta - 1 = (0.2 \pm 2.5) \times 10^{-5}$
- Dynamic of the orbit of the Moon with LLR³

$$\beta - 1 = (2.1 \pm 1.1) \times 10^{-4}$$



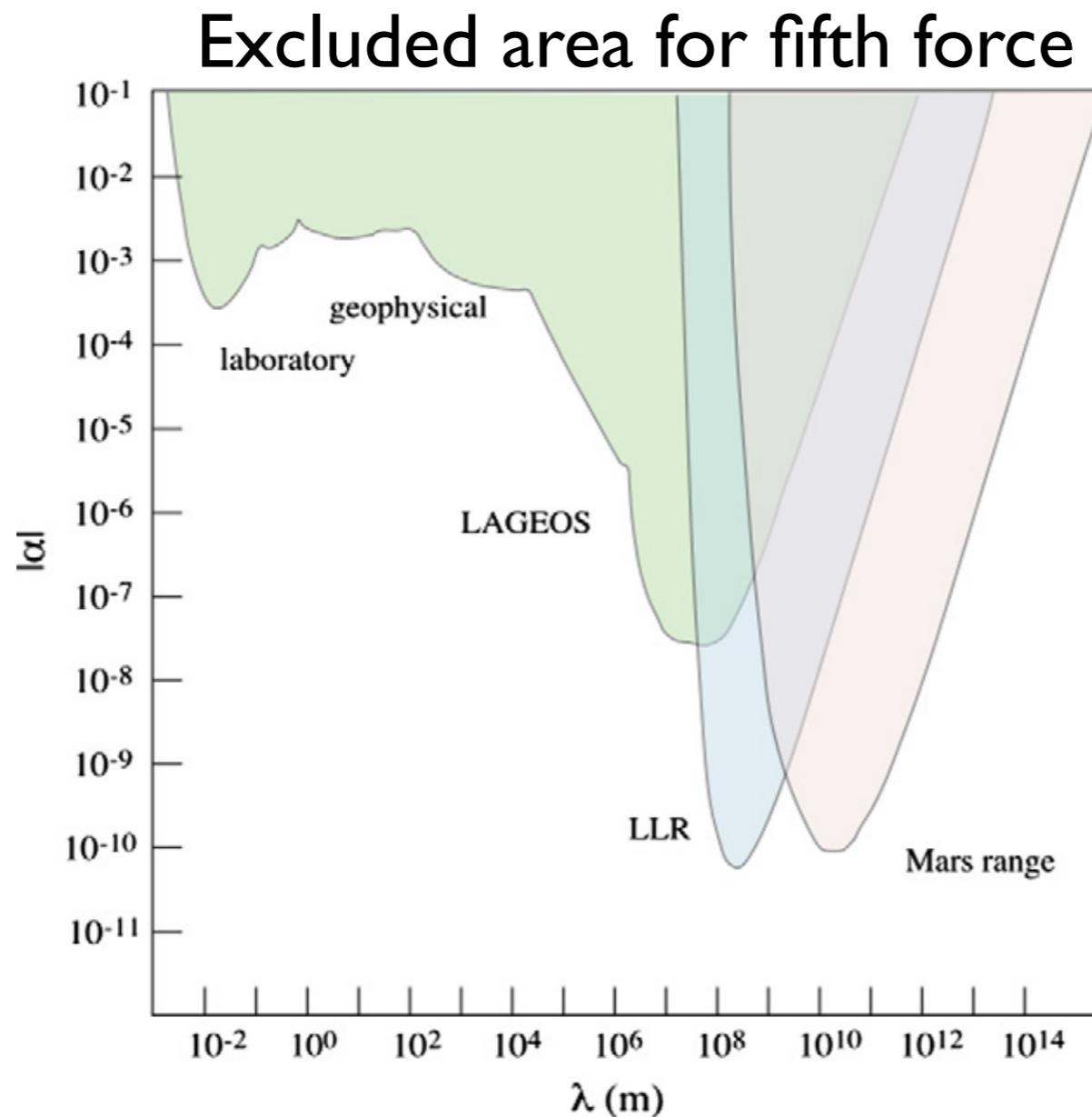
© NASA

² A. Verma et al, A & A, 561, A115, 2014

³ J. Williams, S. Turyshev, D. Boggs, IJMP D, 18/1129, 2009

Fifth force formalism

- Search for a deviation of the Newton potential of the form of a Yukawa potential¹ $\phi(r) = \frac{GM}{c^2 r} \left(1 + \alpha e^{-r/\lambda}\right)$



- Very good constraints in this formalism
except at small and large distances

from A.Konopliv et al,
Icarus, 211/401, 2011

¹ E.G. Adelberger, Progress in Part. and Nucl. Phys., 62/102, 2009
“The Search for Non-Newtonian gravity”, E. Fischbach, C. Talmadge, 1998

Is it enough ?

- Still strong motivations to improve the current tests:
 - tensor-scalar theories “naturally” converging towards GR¹
 - screening theories: modification of GR “hidden” in certain region of space-time: chameleons², symmetron³, Vainshtein mechanism⁴
 - tensor-scalar theories with a decoupling of the scalar field⁵

We have strong motivations to pursue this kind of tests!

¹ T. Damour, K. Nordtvedt, PRD 48/3436 and PRL 70/2217, 1993

² J. Khouri, A. Weltman, PRD 69/044026 and PRL 93/171104, 2004

³ K. Hinterbichler, et al, PRD84/103521 and PRL104/231301, 2010

⁴ A. Vainshtein, Phys. Let. B, 39/393, 1972

⁵ T. Damour, A. Polyakov, Nucl. Phys. B, 1994

O. Minazzoli, A. Hees, PRD 88/1504, 2013

Is it necessary to go beyond ?

Post Einsteinian Grav.

- phenomenology
- non local field equation:
quantization ?

$$G_{\mu\nu}[k] = \chi_{\mu\nu}^{\alpha\beta}[k]T_{\alpha\beta}[k]$$

- metric: parametrized by
2 arbitrary functions

M.T. Jaekel, S. Reynaud, CQG, 2005

SME

- phenomenology
- violation of Lorentz symmetry coming from a fundamental level
- action parametrized by a tensor $\bar{S}^{\mu\nu}$

Q. Bailey, A. Kostelecky, PRD, 2006

Fab Four

- General 2nd order tensor-scalar theory
- developed in cosmology: Dark Energy
- weak-field metric: parametrized by **4 parameters**

J.P. Bruneton et al, Adv. in Astr., 2012

MOND

- phenomenology
- developed for galactic observations: Dark Matter (galactic rotation curves)
- main effect in the Solar System: **External Field Effect**

$$U = \frac{GM}{r} + \frac{Q_2}{2}x^i x^j \left(e_i e_j - \frac{1}{3} \delta_{ij} \right)$$

L. Blanchet, J. Novak, MNRAS, 2011

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L. Blanchet, J. Novak, MNRAS, 2011

PPN formalism : γ, β, \dots

5th force formalism: α, λ

Is it necessary to go beyond ?

Post Einsteinian Grav.

SME

Fab Four

Currently: lack of constraints from Solar System for these theories !

Interesting to consider them and to constrain them using Solar System observations

MOND

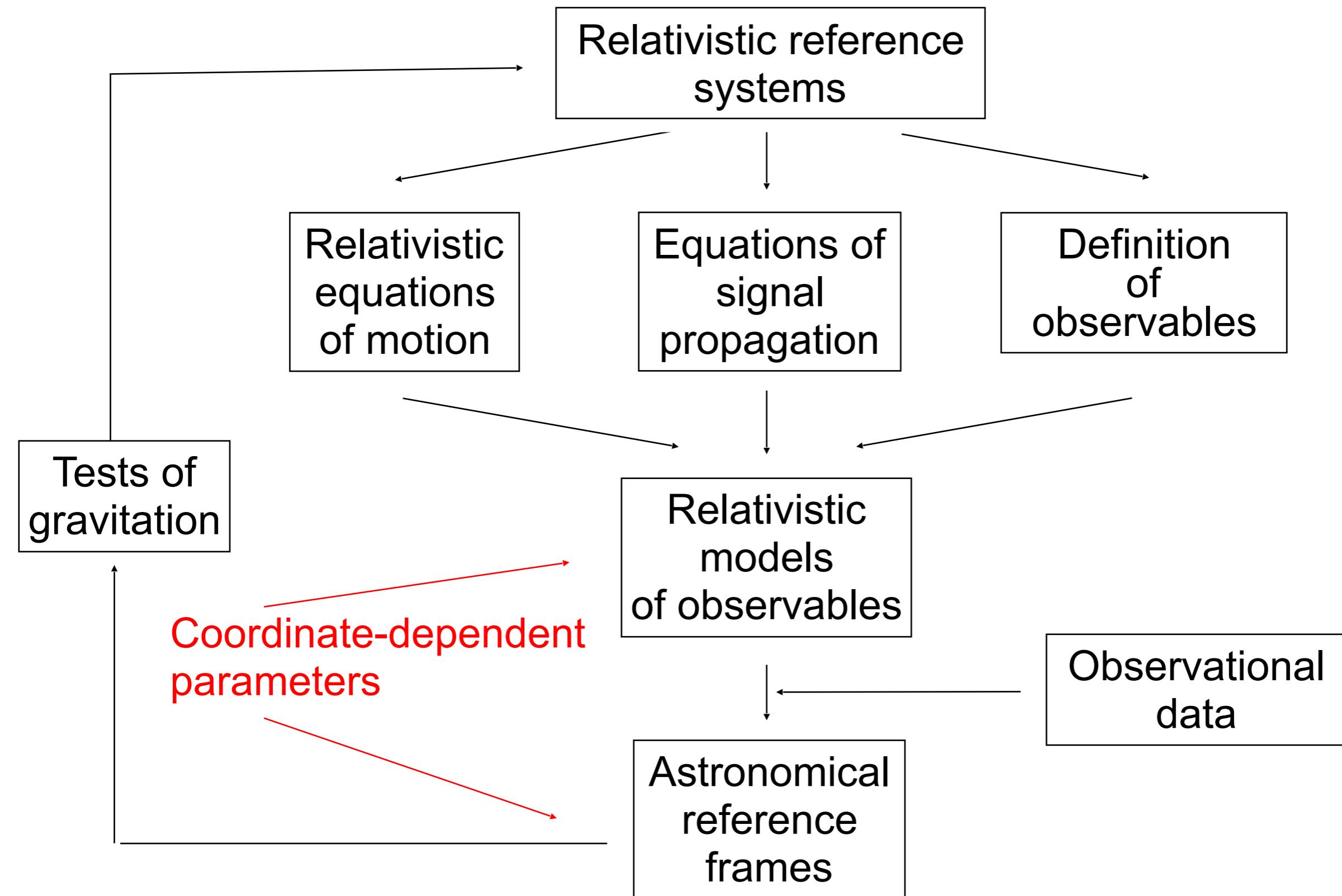
- phenomenology
- developed for galactic observations: Dark Matter (galactic rotation curves)
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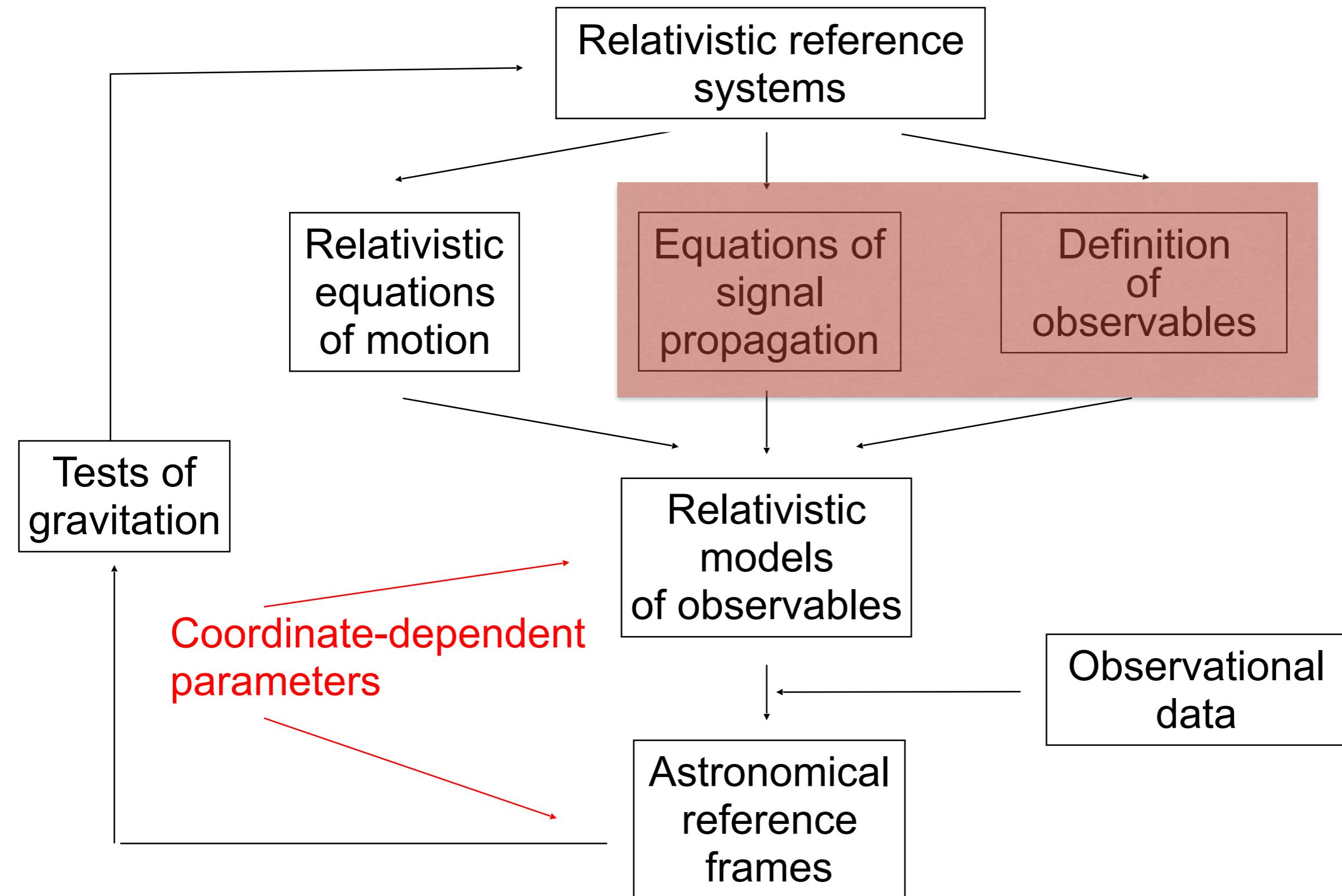
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Relativistic Astronomy : some basics



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Light propagation is crucial in the
modeling of Sol. Sys. observations

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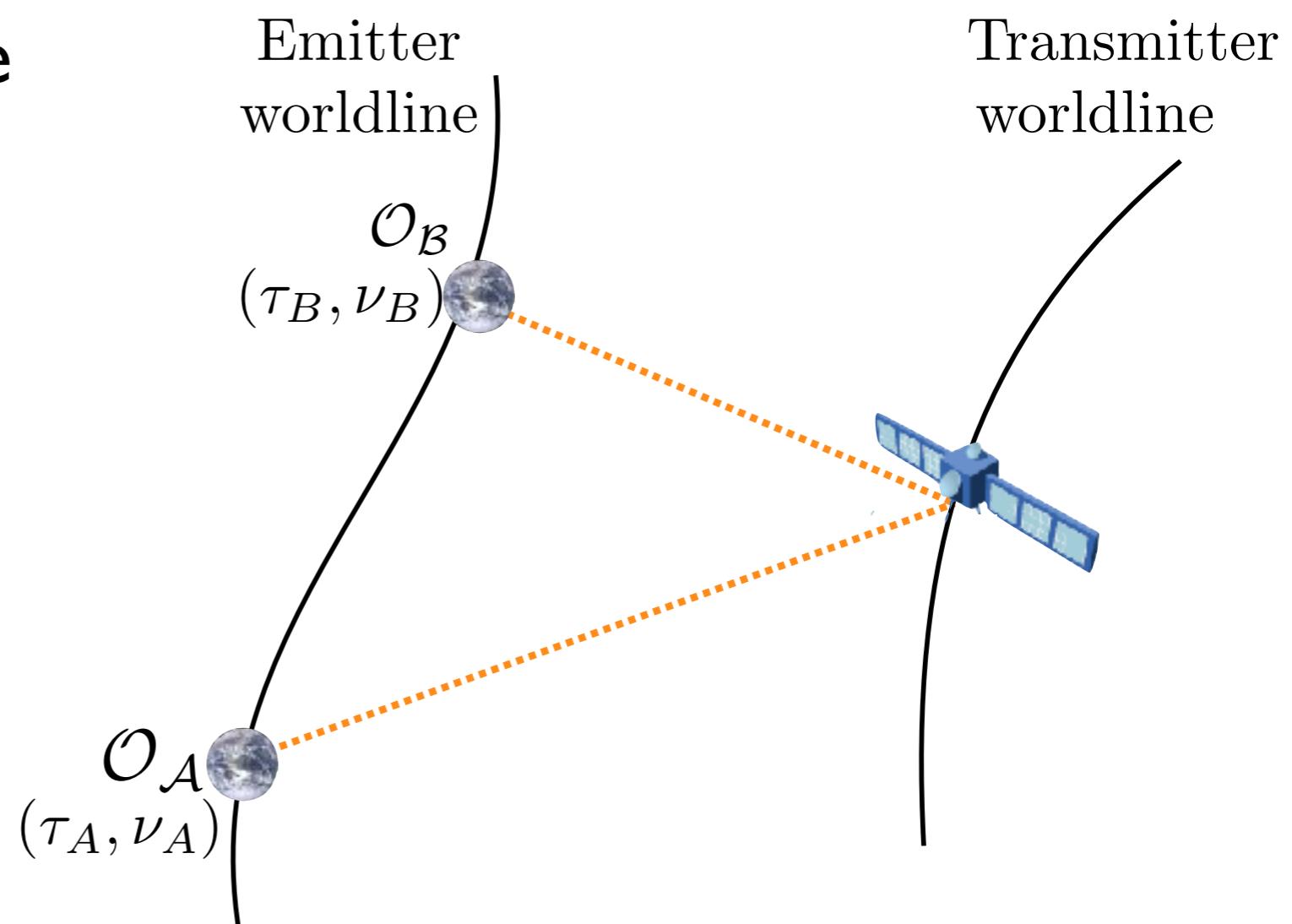
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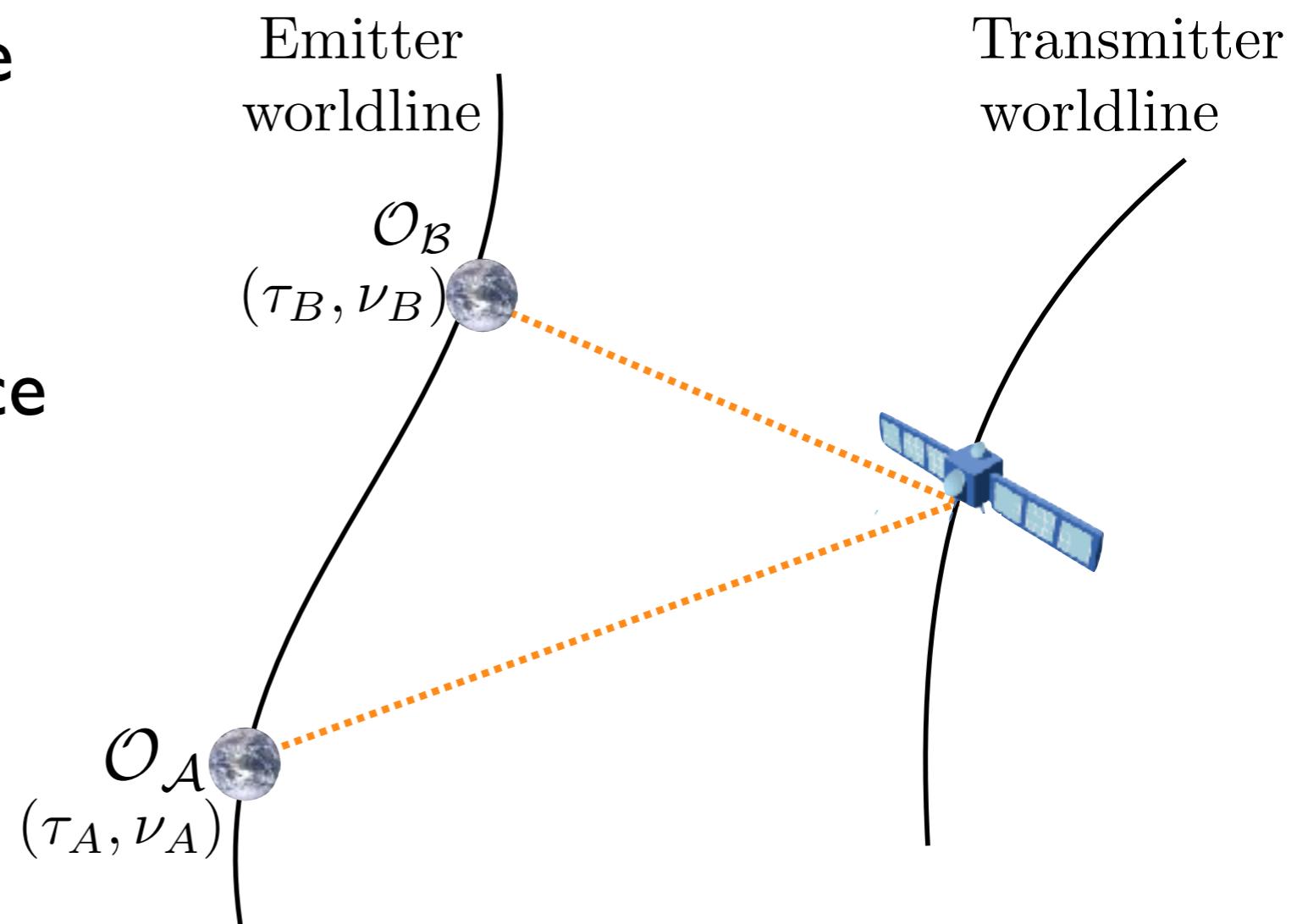
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- Difference in proper time

$$\text{Range} = c(\tau_B - \tau_A)$$

- Depends on the difference in coord. time (amongst other parameters)

$$t_B - t_A$$



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2) Doppler observable

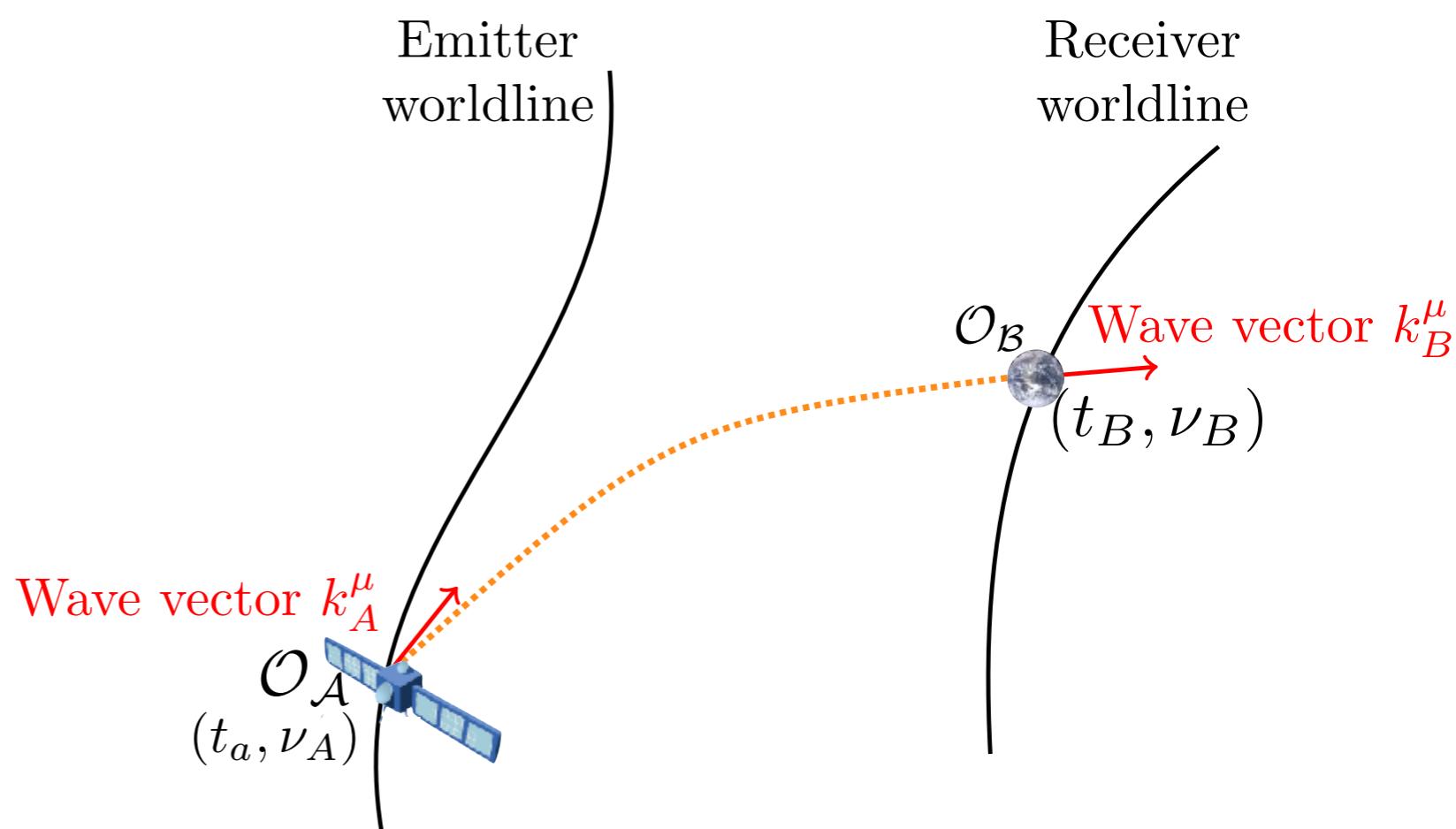
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2) Doppler observable

- Ratio of proper frequency $D = \frac{\nu_B}{\nu_A} = \left(\frac{d\tau}{dt} \right)_A \left(\frac{d\tau}{dt} \right)_B^{-1} \frac{k_0^B}{k_0^A} \frac{1 + \beta_B^i \hat{k}_i^B}{1 + \beta_A^i \hat{k}_i^A}$

with $\beta^i = v^i/c$ and

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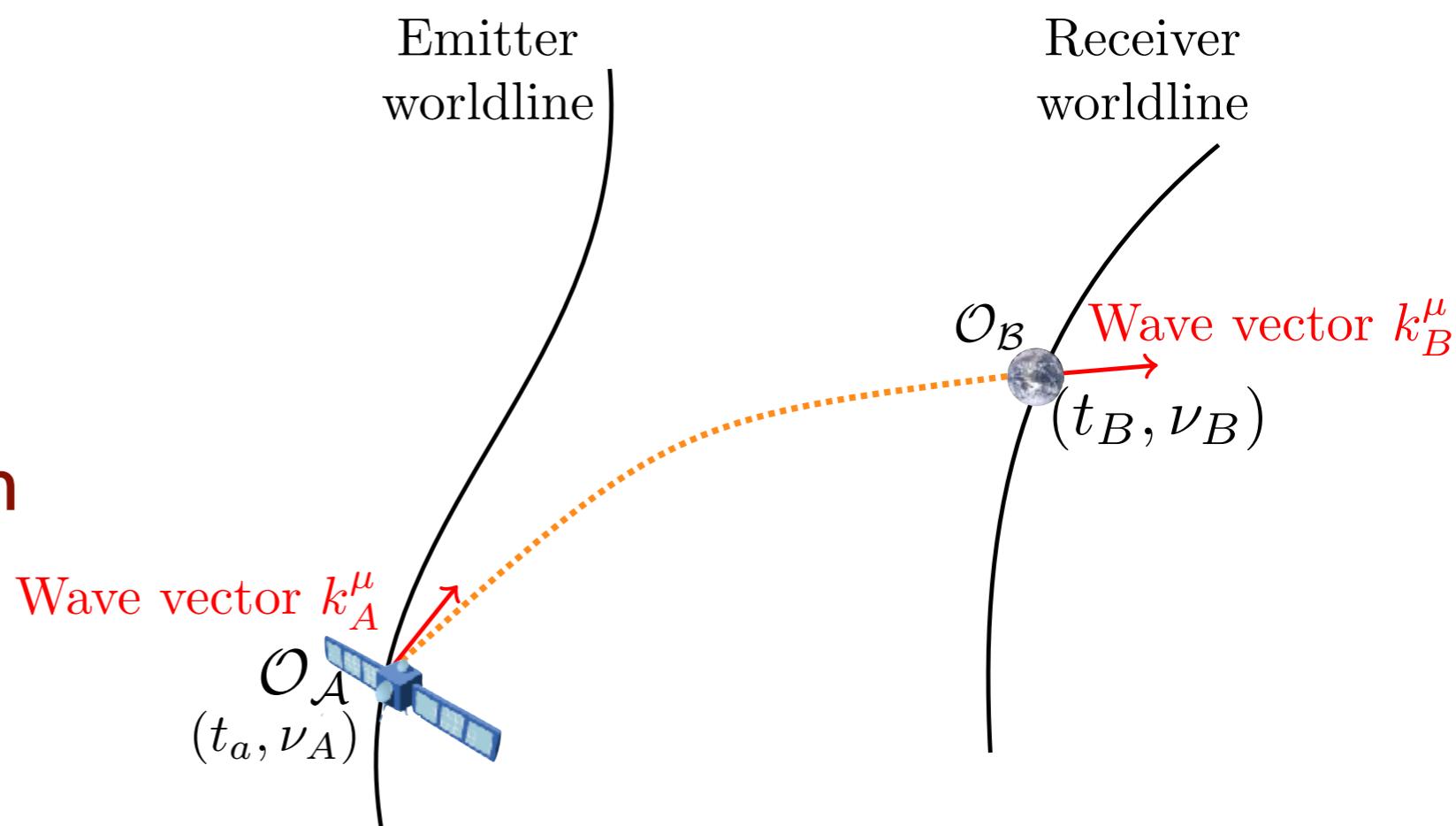
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- Wave vector at emission and reception needed



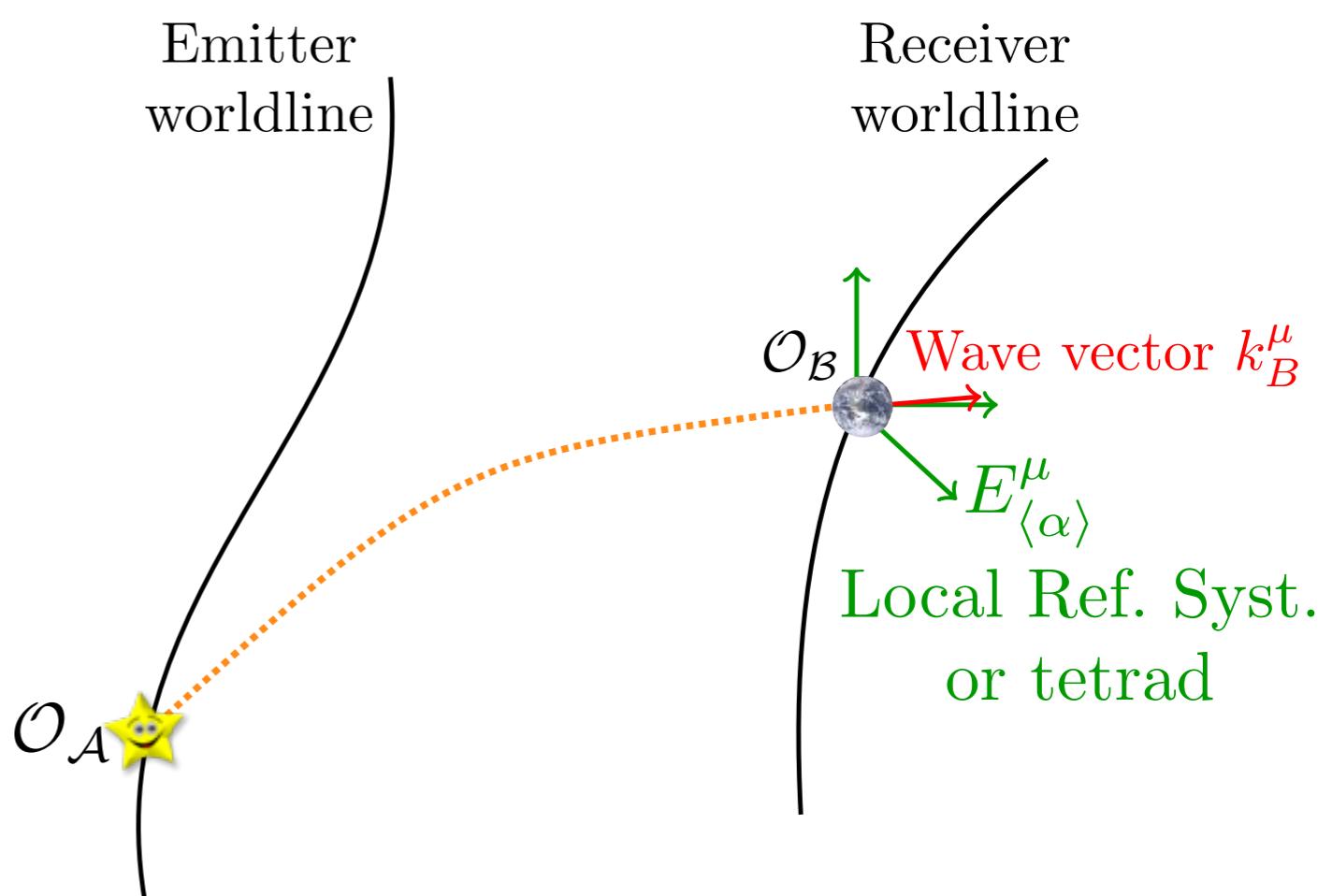
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Light propagation is crucial in the modeling of Sol. Sys. observations

3) Astrometric observables

Direction of observation of the light ray in a local reference system (or tetrad)

$$n^{\langle i \rangle} = -\frac{E_{\langle i \rangle}^0 + E_{\langle i \rangle}^j \hat{k}_j^B}{E_{\langle 0 \rangle}^0 + E_{\langle 0 \rangle}^j \hat{k}_j^B}$$



Light propagation is crucial in the modeling of Sol. Sys. observations

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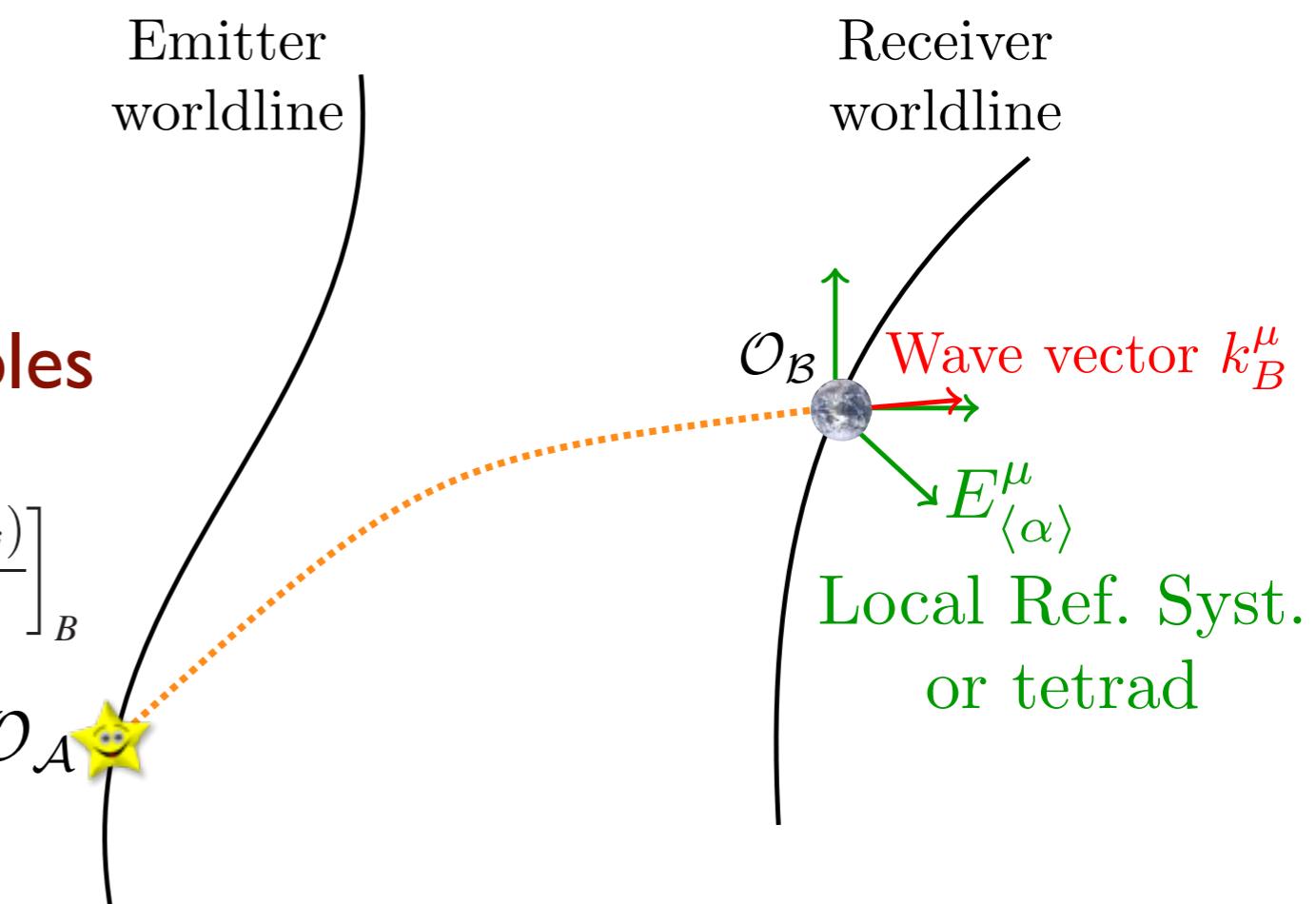
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4) Differential astrometric observables

$$\sin^2 \frac{\phi}{2} = -\frac{1}{4} \left[\frac{(g_{00} + 2g_{0k}\beta^k + g_{kl}\beta^k\beta^l)g^{ij}(\hat{k}'_i - \hat{k}_i)(\hat{k}'_j - \hat{k}_j)}{(1 + \beta^m \hat{k}_m)(1 + \beta^l \hat{k}'_l)} \right]_B$$

Angle between 2 incoming light rays



Light propagation is crucial in the modeling of Sol. Sys. observations

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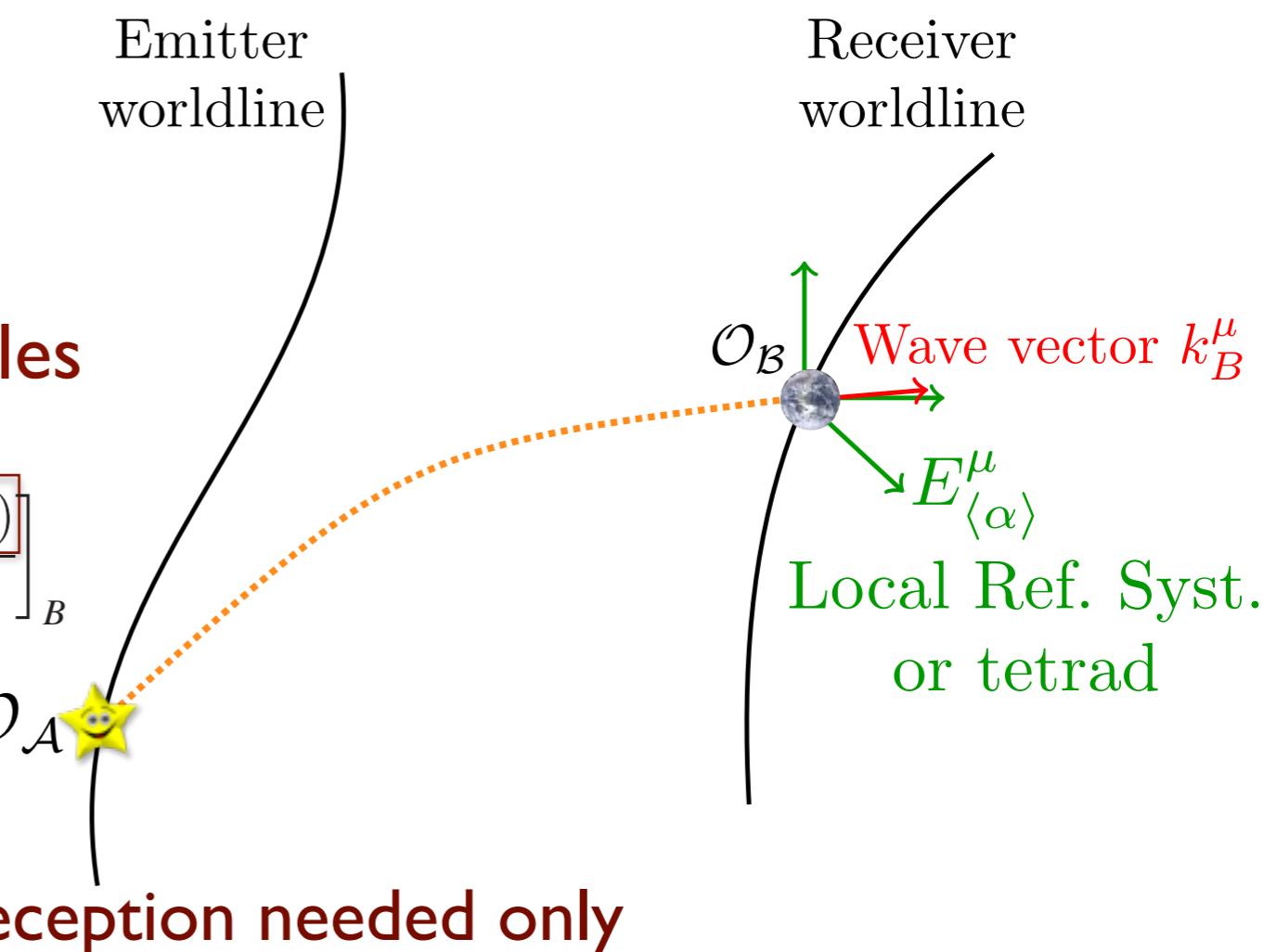
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Angle between 2 incoming light rays



How to determine the light propagation ?

- At the geometric optics approximation: photons follow null geodesics

$$\frac{dk^\mu}{d\lambda} + \Gamma_{\alpha\beta}^\mu k^\alpha k^\beta = 0 \quad k^\mu k_\mu = 0$$

with $k^\mu = \frac{dx^\mu}{d\lambda}$ the tangent vector

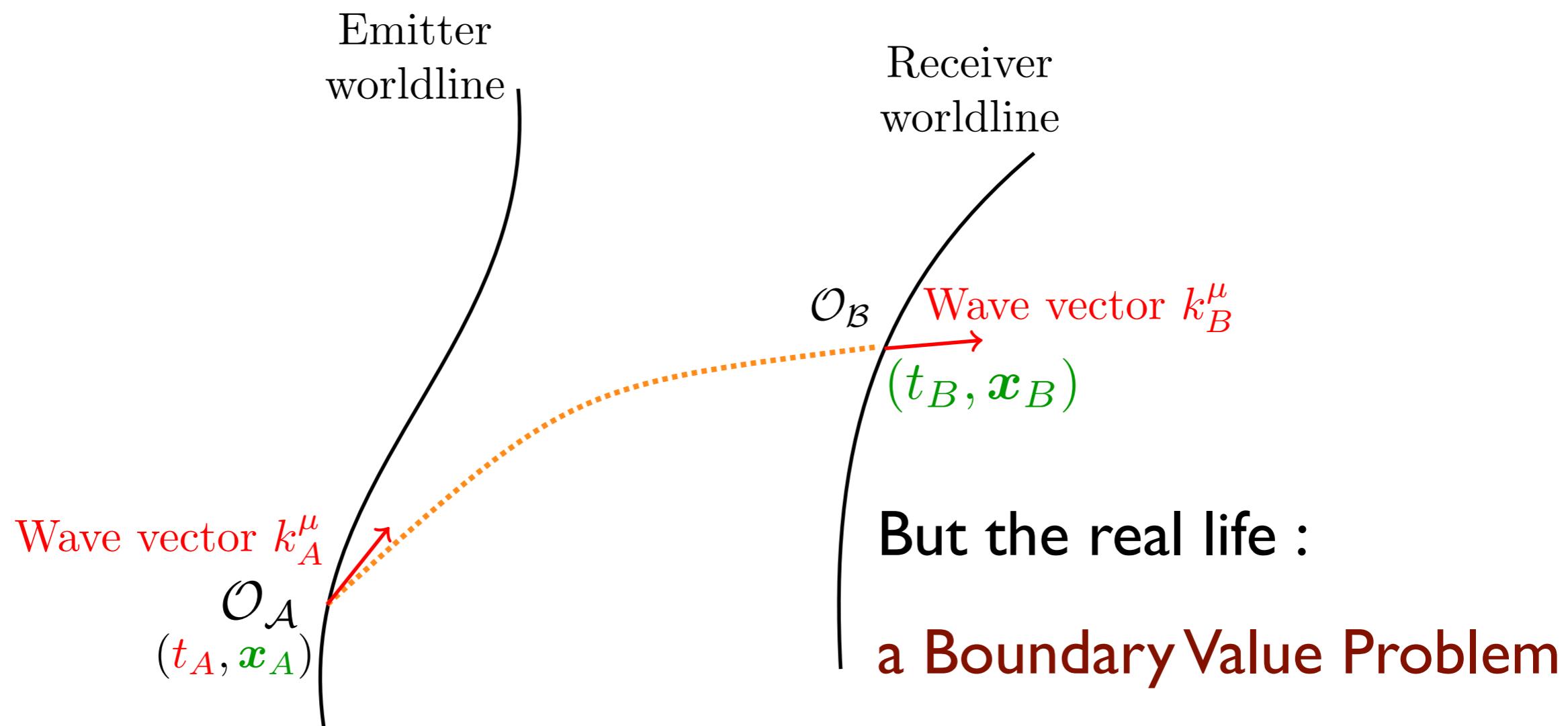
an Initial Value Problem

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- Use of the eikonal equation:
 - perturbative solution for spherically symmetric space-time
 - see for example N. Ashby, B. Bertotti, CQG 27, 145013, 2010

... and the Time Transfer Functions

see CLPL, et al, CQG 21, 4463, 2004

P.Teyssandier and CLPL, CQG 25, 145020, 2008

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- The Time Transfer Functions - TTF - are defined by

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- The derivatives of the TTF are of crucial interest since

$$\hat{k}_i^A = c \frac{\partial \mathcal{T}_r}{\partial x_A^i} \quad \hat{k}_i^B = -c \frac{\partial \mathcal{T}_r}{\partial x_B^i} \left[1 - \frac{\partial \mathcal{T}_r}{\partial t_B} \right]^{-1} \quad \frac{k_0^B}{k_0^A} = 1 - \frac{\partial \mathcal{T}_r}{\partial t_B}$$

Range, Doppler, astrometric observables can be written in terms of the TTF and its derivatives

Fundamental properties of TTF's

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TTF is a Dedicated World Function to light ray.
General Post-Minkowskian expansions are possible

Post-Minkowskian expansion of the TTF

see P.Teyssandier and CLPL, CQG 25, I45020, 2008

- A pM expansion of the TTF: $\mathcal{T}_r(x_A, t_B, x_B) = \frac{R_{AB}}{c} + \sum_{n>1} \mathcal{T}_r^{(n)}$
- Computation with an iterative procedure involving integrations over a straight line between the emitter and the spatial position of the receiver !
- Example at 1 pM: $\mathcal{T}_r^{(1)} = \frac{R_{AB}}{2c} \int_0^1 \left[g_{(1)}^{00} - 2N_{AB}^i g_{(1)}^{0i} + N_{AB}^i N_{AB}^j g_{(1)}^{ij} \right]_{z^\alpha(\lambda)} d\lambda$
with $z^\alpha(\lambda)$ the straight Mink. null path between em. and rec.
- Main advantages:
 - analytical computations relatively easy
 - very well adapted to numerical evaluation

Analytical results in Schwarzschild space-time

- A pM expansion of the TTF: $\mathcal{T} = \frac{R_{AB}}{c} + \sum_{n>1} \mathcal{T}^{(n)}$

$$\mathcal{T}^{(1)} = \frac{(1+\gamma)m}{c} \ln \frac{r_A + r_B + |\mathbf{x}_B - \mathbf{x}_A|}{r_A + r_B - |\mathbf{x}_B - \mathbf{x}_A|} \quad \text{see E. Shapiro, PRL 13, 26, 789, 1964}$$

$$\mathcal{T}^{(2)} = \frac{m^2}{r_A r_B} \frac{|\mathbf{x}_B - \mathbf{x}_A|}{c} \left[\kappa \frac{\arccos \mathbf{n}_A \cdot \mathbf{n}_B}{|\mathbf{n}_A \times \mathbf{n}_B|} - \frac{(1+\gamma)^2}{1 + \mathbf{n}_A \cdot \mathbf{n}_B} \right]$$

see CLPL, et al, CQG 21, 4463, 2004
 S. Klioner, S. Zschocke, CQG 27, 075015, 2010

$$\mathcal{T}^{(3)} = \frac{m^3}{r_A r_B} \left(\frac{1}{r_A} + \frac{1}{r_B} \right) \frac{|\mathbf{x}_B - \mathbf{x}_A|}{c(1 + \mathbf{n}_A \cdot \mathbf{n}_B)} \left[\kappa_3 - (1+\gamma)\kappa \frac{\arccos \mathbf{n}_A \cdot \mathbf{n}_B}{|\mathbf{n}_A \times \mathbf{n}_B|} + \frac{(1+\gamma)^3}{1 + \mathbf{n}_A \cdot \mathbf{n}_B} \right]$$

see B. Linet and P.Teyssandier, CQG 30, 175008, 2014

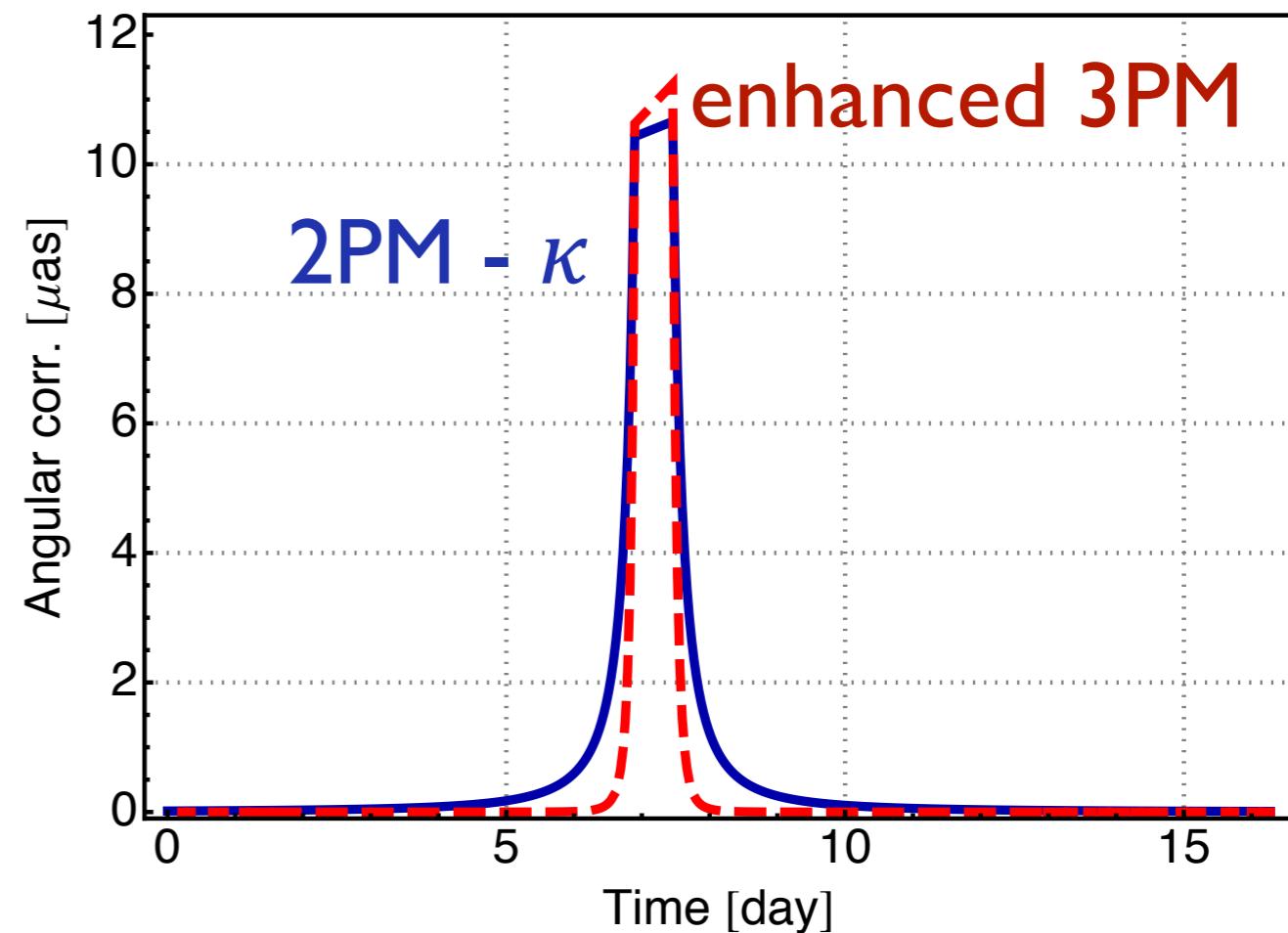
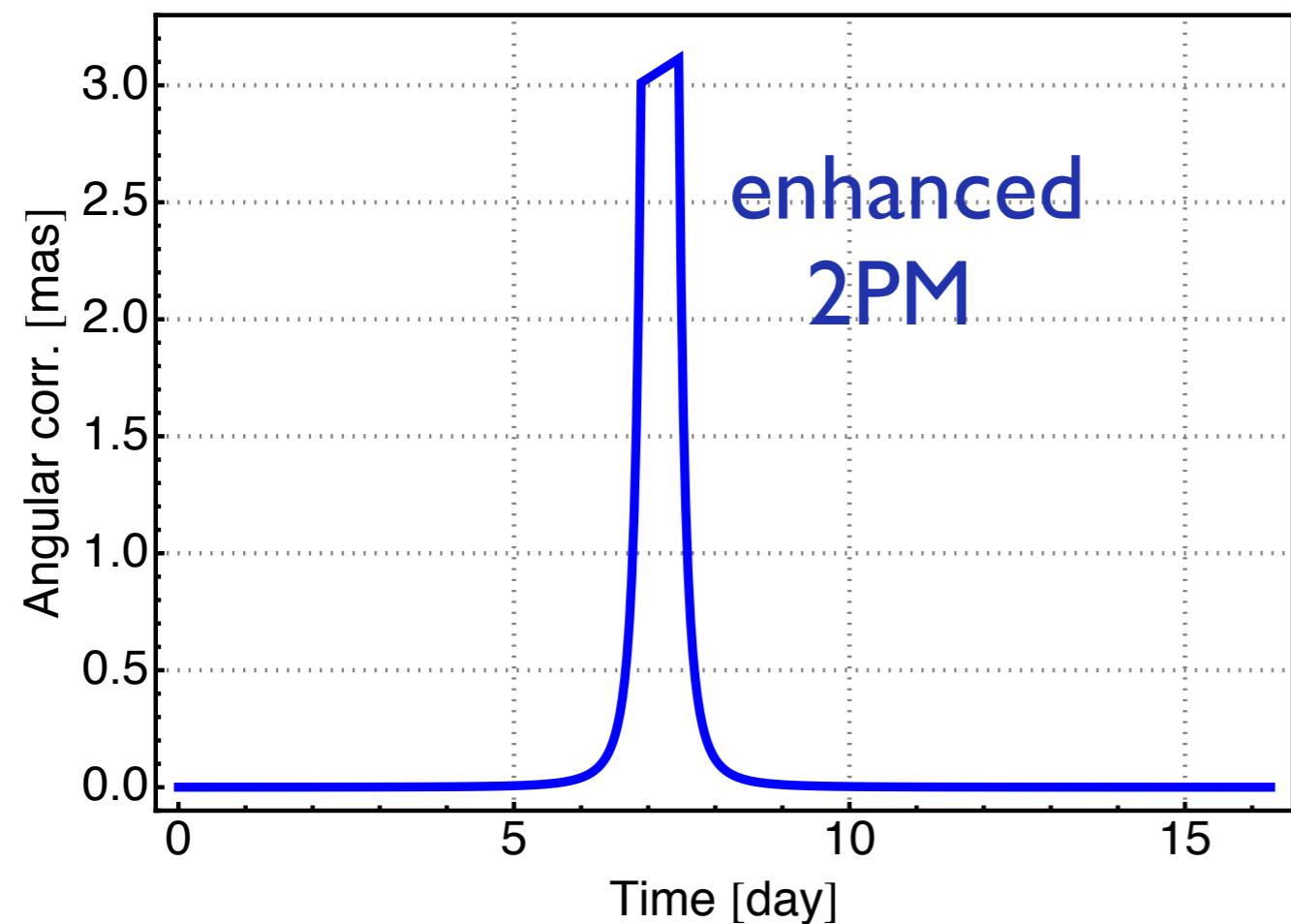
with $\kappa = 2 + 2\gamma - \beta + \frac{3}{4}\epsilon$

$$\kappa_3 = 2\kappa - 2\beta(1+\gamma) + \frac{1}{4}(3\beta_3 + \gamma_3)$$

and $\mathbf{n}_{A/B} = \frac{\mathbf{x}_{A/B}}{r_{A/B}}$

Is it necessary to go to the 3rd order?

- In a conjunction geometry, at each order n , there are enhanced terms proportional to $(1 + \gamma)^n$
- Ex. with light deflection for Sun grazing rays: AGP space mission (old GAME). Expected accuracy: μas
 \Rightarrow 3pM term needed

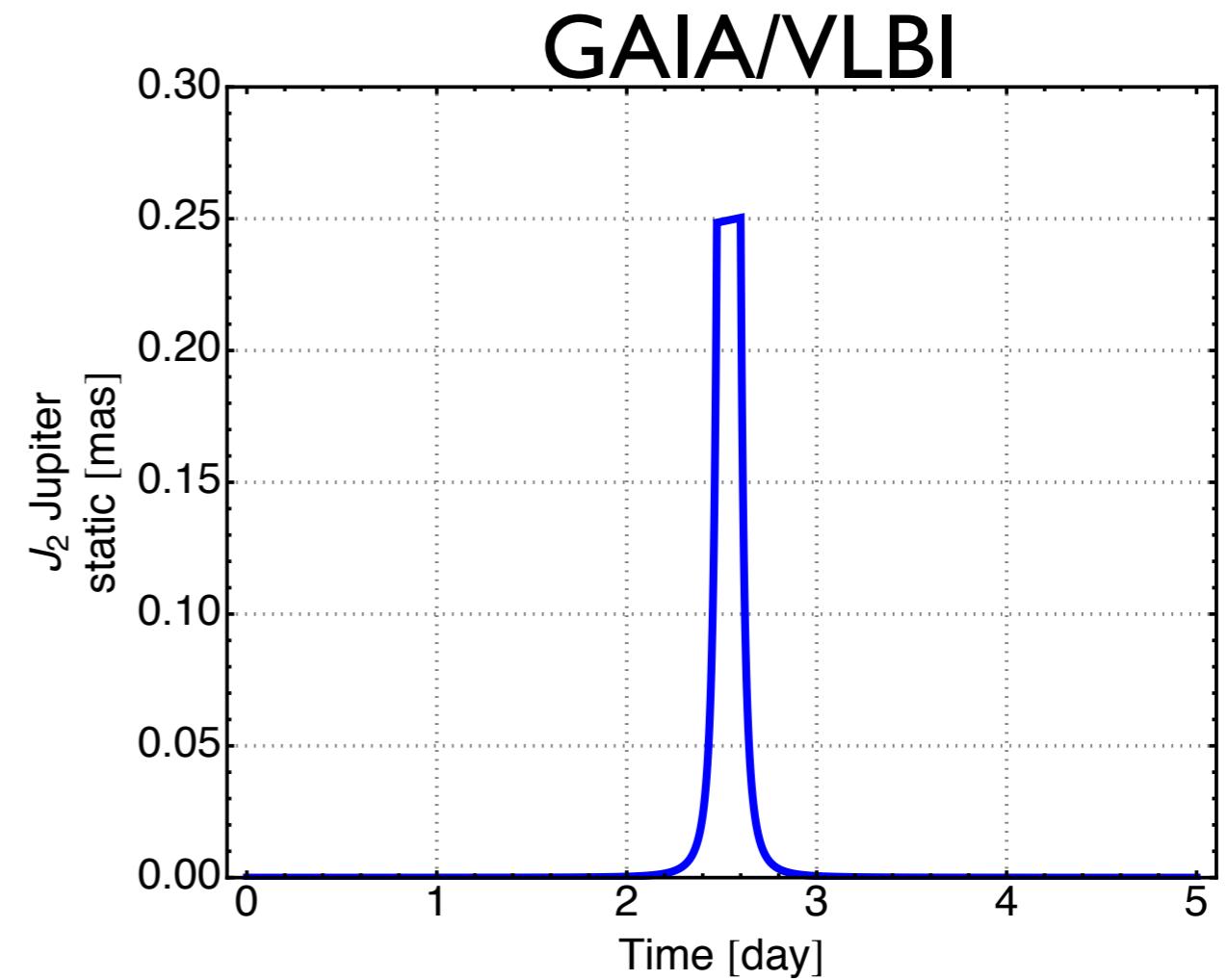
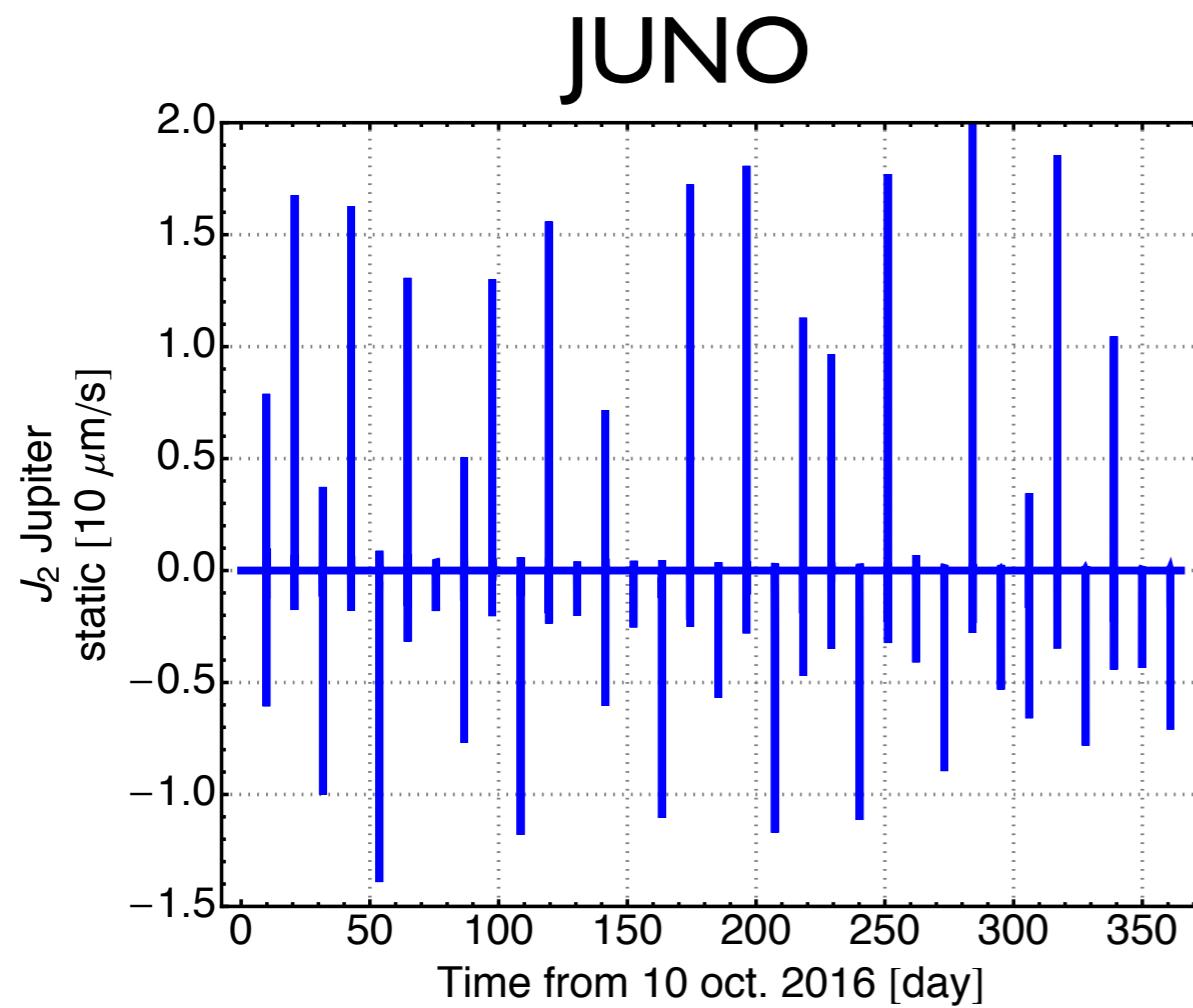


see A. Hees, S. Bertone, CLPL, PRD 89, 064045, 2014

P.Teyssandier, B. Linet, proceedings of JSR 2013, arXiv:1312.3510

Analytical result around axisymmetric bodies

- Influence of all the multipole moments J_n from the grav. potential
see CLPL, P.Teyssandier, PRD 77, 044029, 2008 for a computation with the TTF
or S. Kopeikin, J. of Math. Physics 38, 2587, 1997 for another approach
- Influence of Jupiter J_2 on the JUNO Doppler ($1 \mu\text{m/s}$ accuracy)
and for GAIA ($10 \mu\text{as}$ acc.)



- terms important for the data analysis for these missions

see Hees, Bertone, CLPL, PRD 90, 084020, 2014

What happens if the body is moving ?

see Hees, Bertone, CLPL, PRD 90, 084020, 2014

- At first pM order, the TTF for uniformly moving bodies can easily be derived from the TTF generated by a static body

$$\Delta(\mathbf{x}_A, t_B, \mathbf{x}_B) = \gamma(1 - \mathbf{N}_{AB} \cdot \boldsymbol{\beta}) \tilde{\Delta}(\mathbf{R}_A + \gamma \boldsymbol{\beta} \mathbf{R}_{AB}, \mathbf{R}_B)$$

TTF in the moving case

static TTF

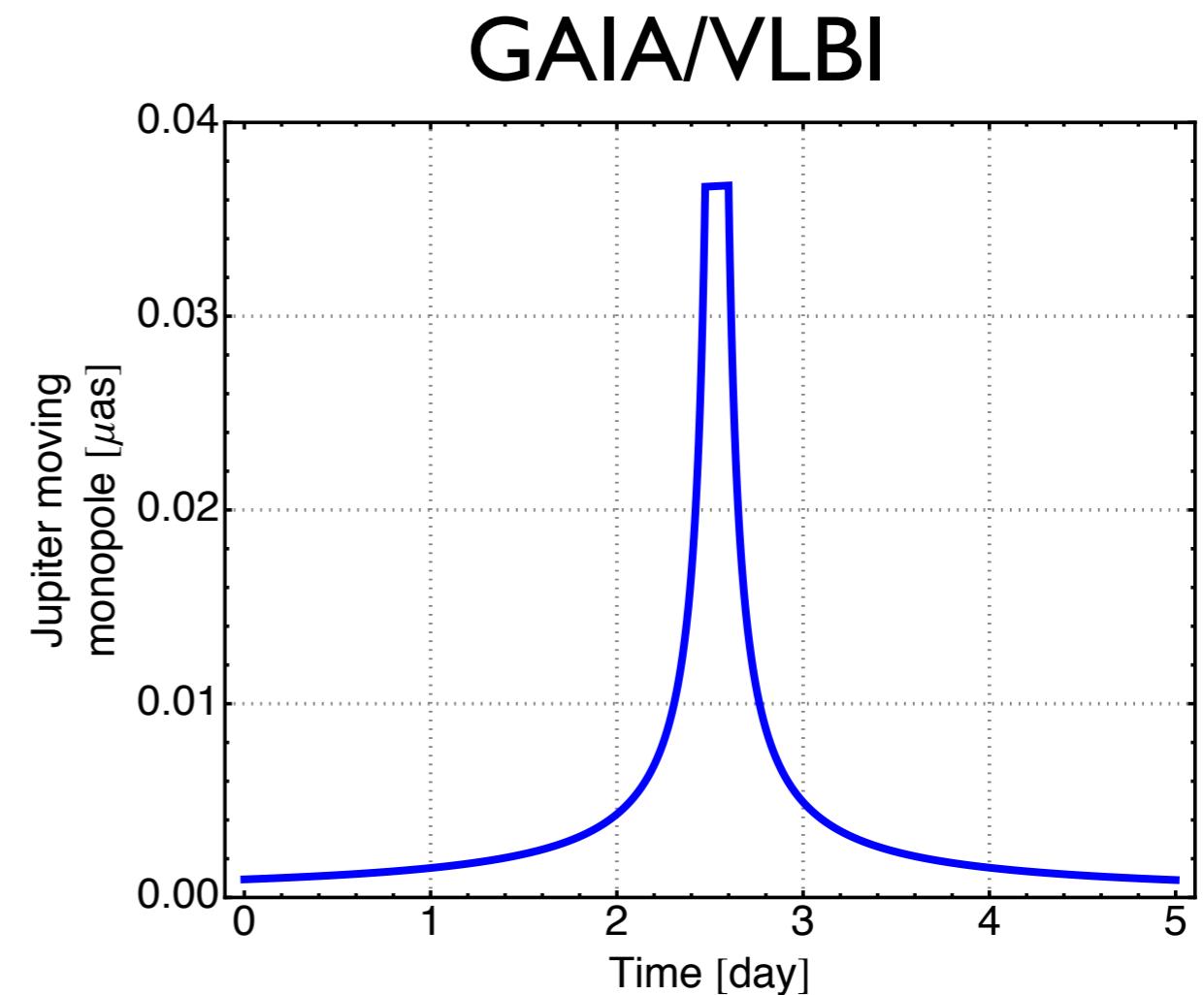
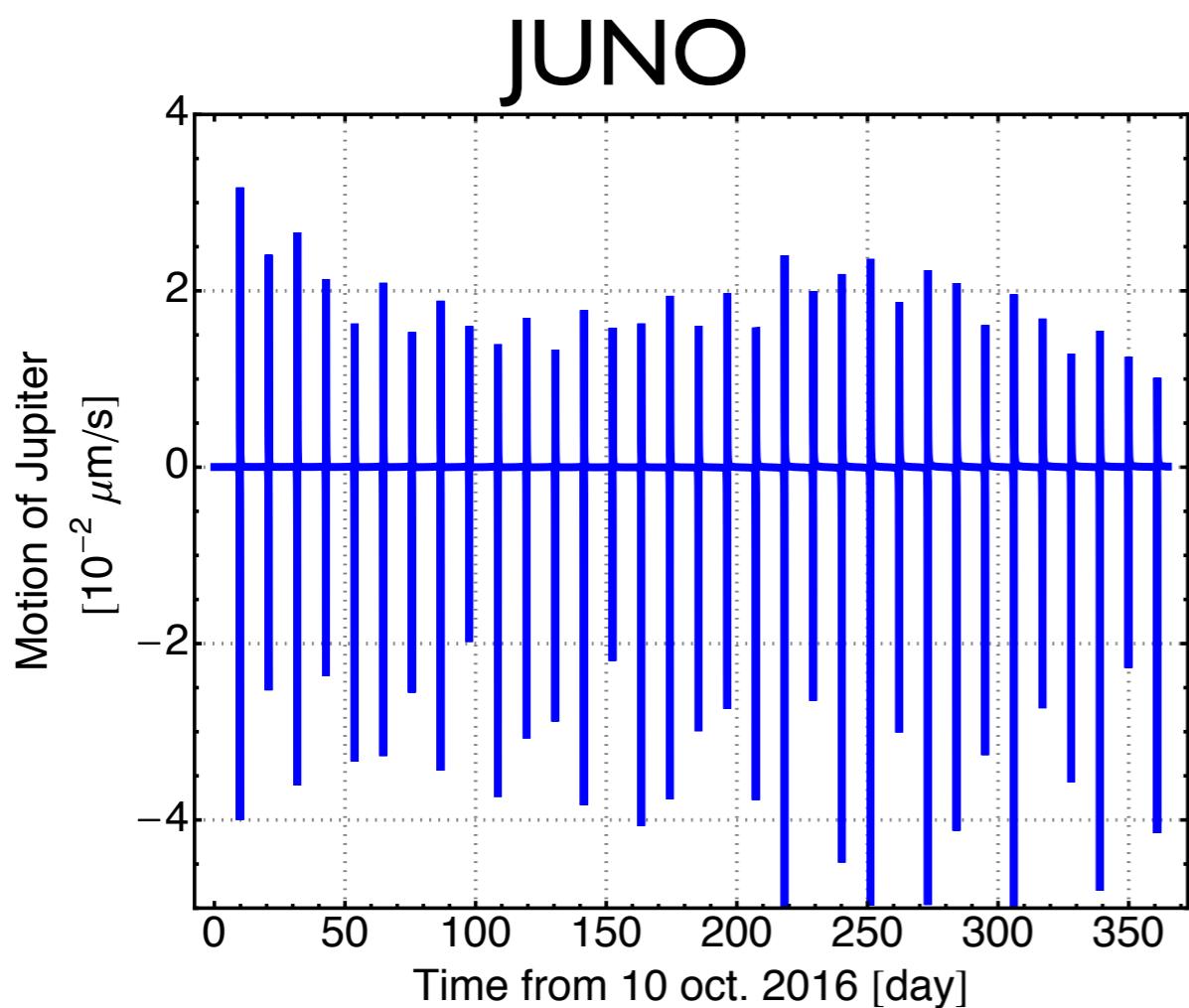
with $\boldsymbol{\beta} = \mathbf{v}/c$, $\gamma = (1 - \beta^2)^{-1/2}$

and \mathbf{R}_X depends on $\mathbf{x}_X, \boldsymbol{\beta}$

- All the analytical results computed for a static source can be extended in the case of a uniformly moving source

Ex.: motion of Jupiter

- Influence of Jupiter velocity on the JUNO Doppler (1 $\mu\text{m/s}$ accuracy) and for GAIA (10 μas acc.)



- depend highly on the orbit geometry: conjunction and $\beta \cdot N_{AB}$
- In particular: should be reassessed for JUICE orbit

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$$\mathcal{T}^{(2)} = \int_0^1 \int_0^1 n \left[z^\alpha(\mu\lambda); g_{\alpha\beta}^{(2)}, g_{\alpha\beta}^{(1)}, g_{\alpha\beta,\gamma}^{(1)}, \mathbf{x}_A, t_B, \mathbf{x}_B \right] d\lambda d\mu$$

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- Numerically efficient ; useful when no analytical solution can be found

see Hees, Bertone, CLPL, PRD 89, 064045, 2014

Some fundamental unified theories break Lorentz symmetry

- like e.g.: strings, noncommutative space-time, loop quan. theory
- General framework to study Lorentz violation:
Standard-Model Extension (SME)
developed by Kostelecky and collaborators in the 90ies
- SME is an effective field theory developed from a Lagrangian

$$\mathcal{L} = \mathcal{L}_{\text{SM}} + \mathcal{L}_{\text{GR}} + \mathcal{L}_{\text{LV}}$$

standard model General Relativity All possible Lorentz violating terms constructed from SM & GR fields and background coefficients

The diagram shows the Lagrangian \mathcal{L} as a sum of three terms: \mathcal{L}_{SM} , \mathcal{L}_{GR} , and \mathcal{L}_{LV} . An arrow points from \mathcal{L}_{SM} to the text 'standard model'. An arrow points from \mathcal{L}_{GR} to the text 'General Relativity'. A green circle highlights \mathcal{L}_{LV} , with an arrow pointing from it to the text 'All possible Lorentz violating terms constructed from SM & GR fields and background coefficients'.

The gravity sector of the minimal SME introduces 9 coefficients

- minimal SME = linearized gravity limit $g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$

$$\mathcal{L}_{\text{LV}} = \frac{c^3}{32\pi G} h^{\mu\nu} \cancel{s}^{\alpha\beta} \mathcal{G}_{\alpha\mu\nu\beta} + \dots$$

STF tensor: 9 Lorentz-violating coefficients

non-minimal
higher order terms

See Kostelecky, PRD, 04 - Bailey and Kostelecky, PRD, 06 - Kostelecky and Mewes, PLB, 16

- this modifies the equations of motion

$$\left[\frac{d^2 x^j}{dt^2} \right]_{\text{SME}} = \frac{GM}{r^3} \left[\cancel{s}^{jk} r^k - \frac{3}{2} \cancel{s}^{kl} \frac{r^k r^l}{r^2} r^j + 2 \cancel{s}^{0k} \frac{v^k}{c} r^j - 2 \cancel{s}^{0j} \frac{v^k}{c} r^k + \dots \right]$$

- Can be constrained by: LLR, pulsars, VLBI, atom interferometry, etc ...

Bourgoin et al.,
PRL, 2016

Le Poncin-Lafitte et al.,
PRD, 2016

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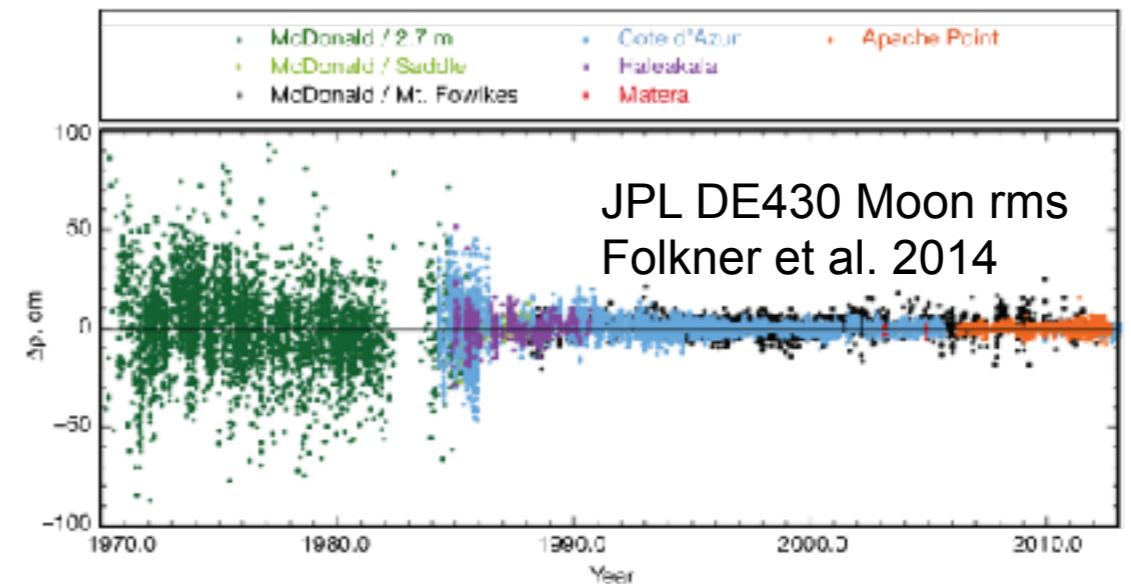
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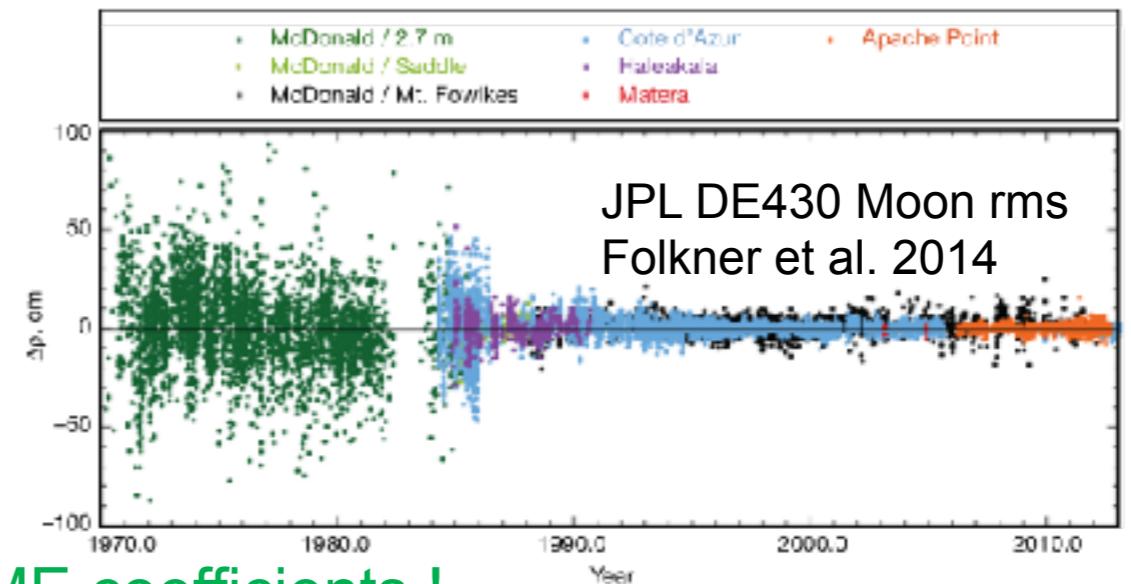
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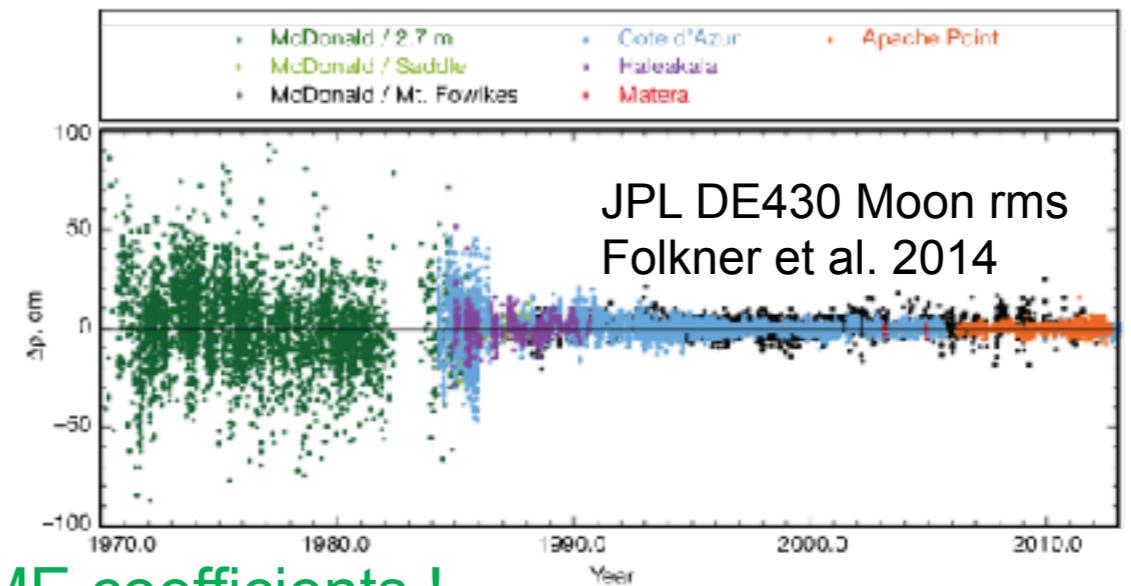
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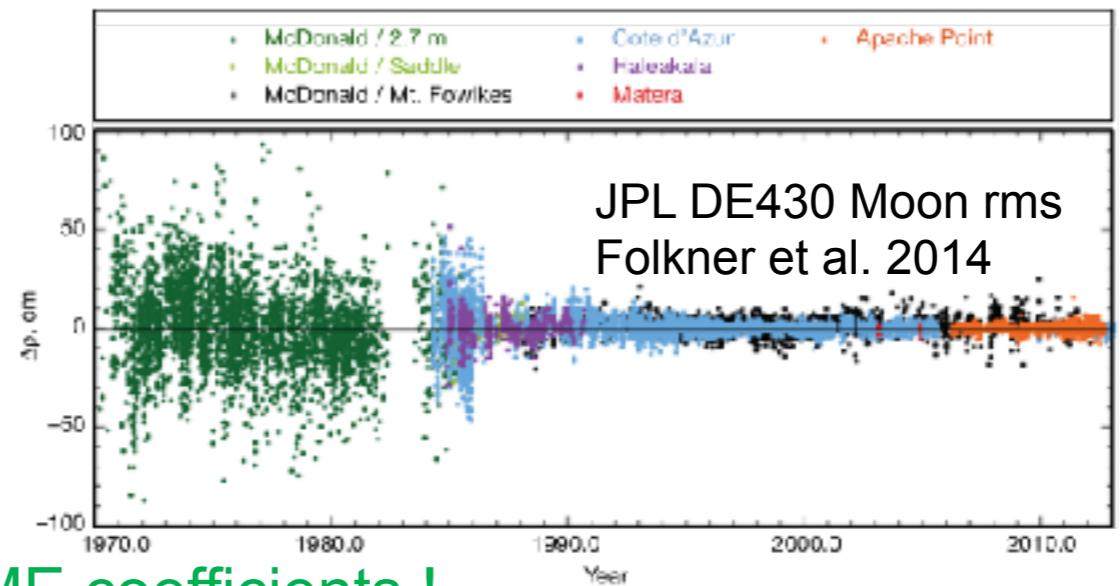
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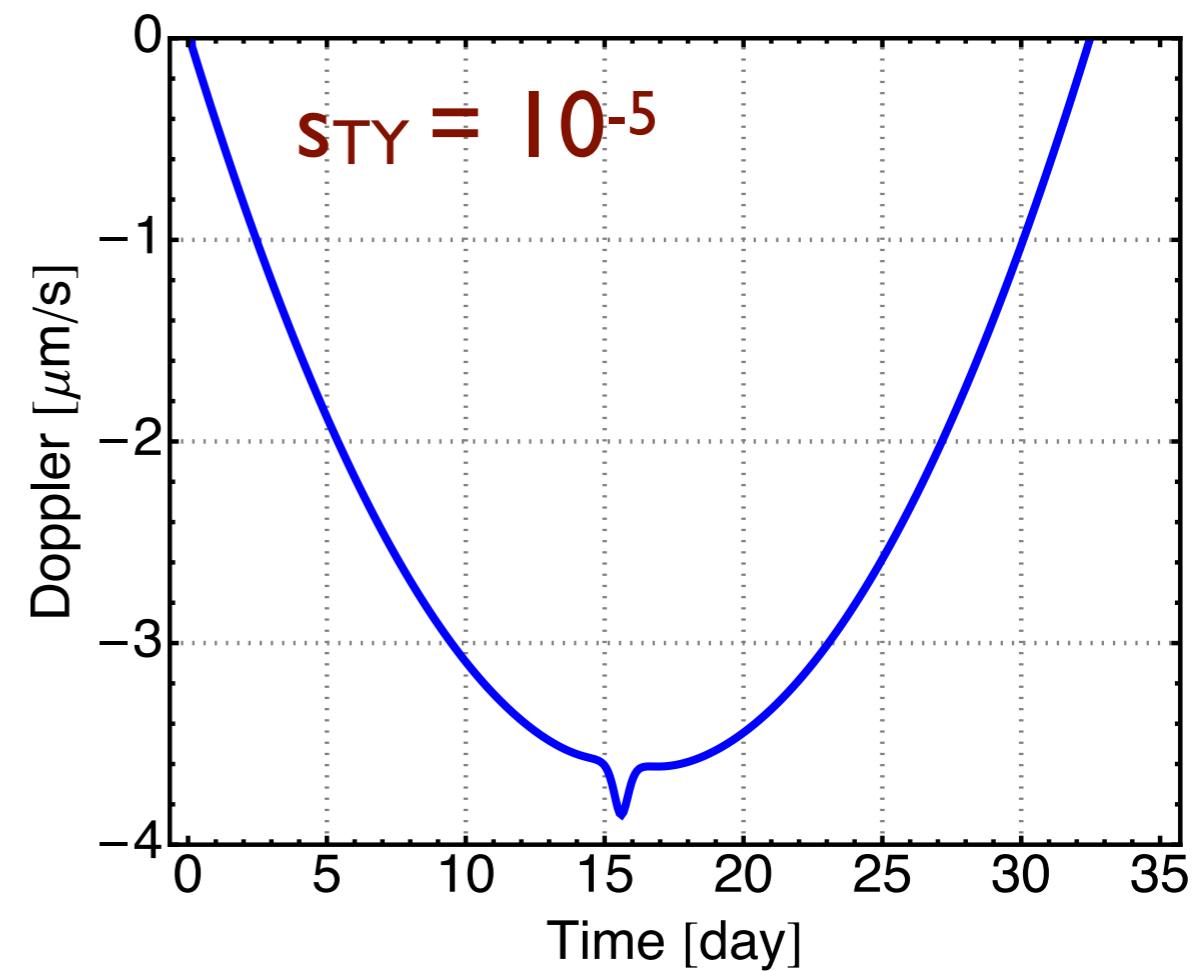
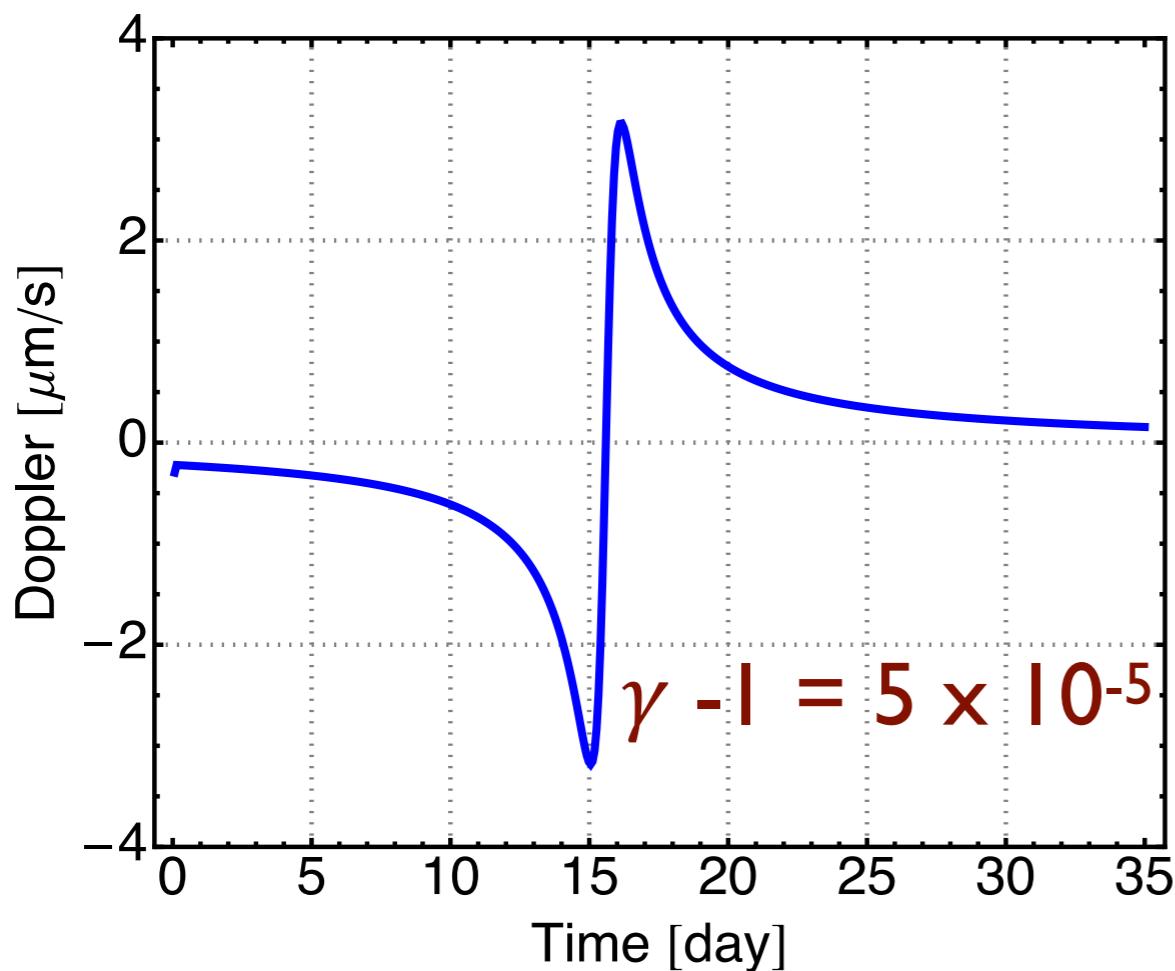


→ Pre-Process data, dynamical modeling & fit in a complete SME framework
In 3 words : Our Ultimate Goal !

Numerical evaluation of the TTF in SME

- Numerical evaluation appropriate to evaluate effects due to alternative theories of gravitation
- Example: Doppler for 30 days of Cassini tracking between Jupiter and Saturn (“ γ experiment”)
- Effect of the γ PPN and of Standard Model Extension s_{TY} on Cassini Doppler

for SME, see Q. Bailey and A. Kostelecky, PRD 74, 045001, 2006

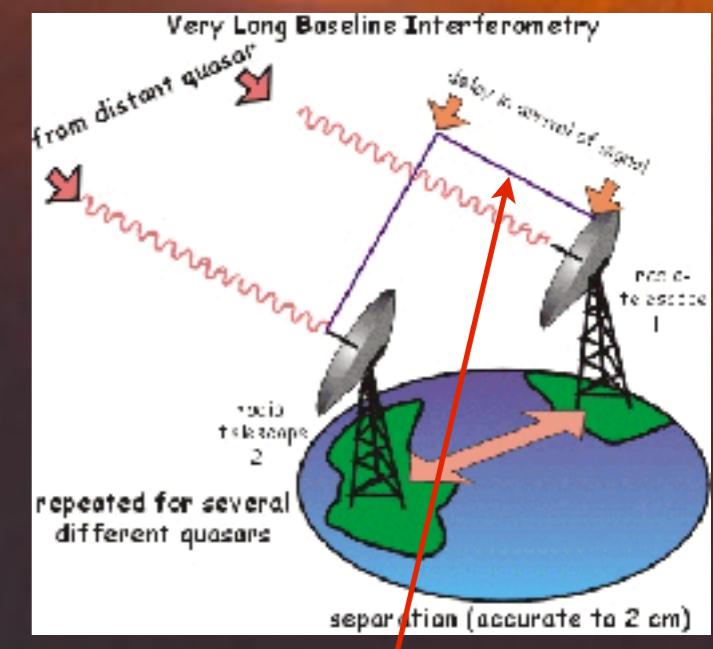


Towards VLBI test of SME

Observations of quasars

1. Statically not moving
2. With 2 radiotelescopes, one are able to fix the Earth orientation with respect to quasars

Position kinematical
position of the Earth in
space



observable :
time delay between the
reception of signal at the
radiotelescopes

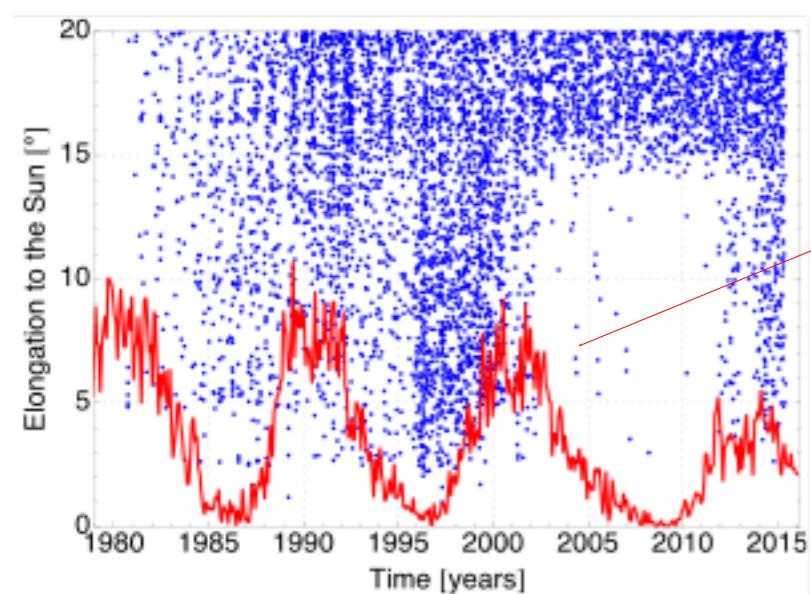
Modeling SME-VLBI delay & fit

Lambert & CLPL, 2009 and 2011 : determination of PPN
Gamma at the level of 10^{-4} ,
1 order of mag below Cassini **but strong statistics & robustness**

First, we derive the VLBI delay in SME from Bailey (2009) :

$$\Delta\tau_{(\text{grav})} = 2 \frac{\widetilde{GM}}{c^3} \left(1 - \frac{2}{3} \bar{s}^{TT}\right) \ln \frac{r_1 + \mathbf{k} \cdot \mathbf{x}_1}{r_2 + \mathbf{k} \cdot \mathbf{x}_2} + \frac{2}{3} \frac{\widetilde{GM}}{c^3} \bar{s}^{TT} (\mathbf{n}_2 \cdot \mathbf{k} - \mathbf{n}_1 \cdot \mathbf{k}) .$$

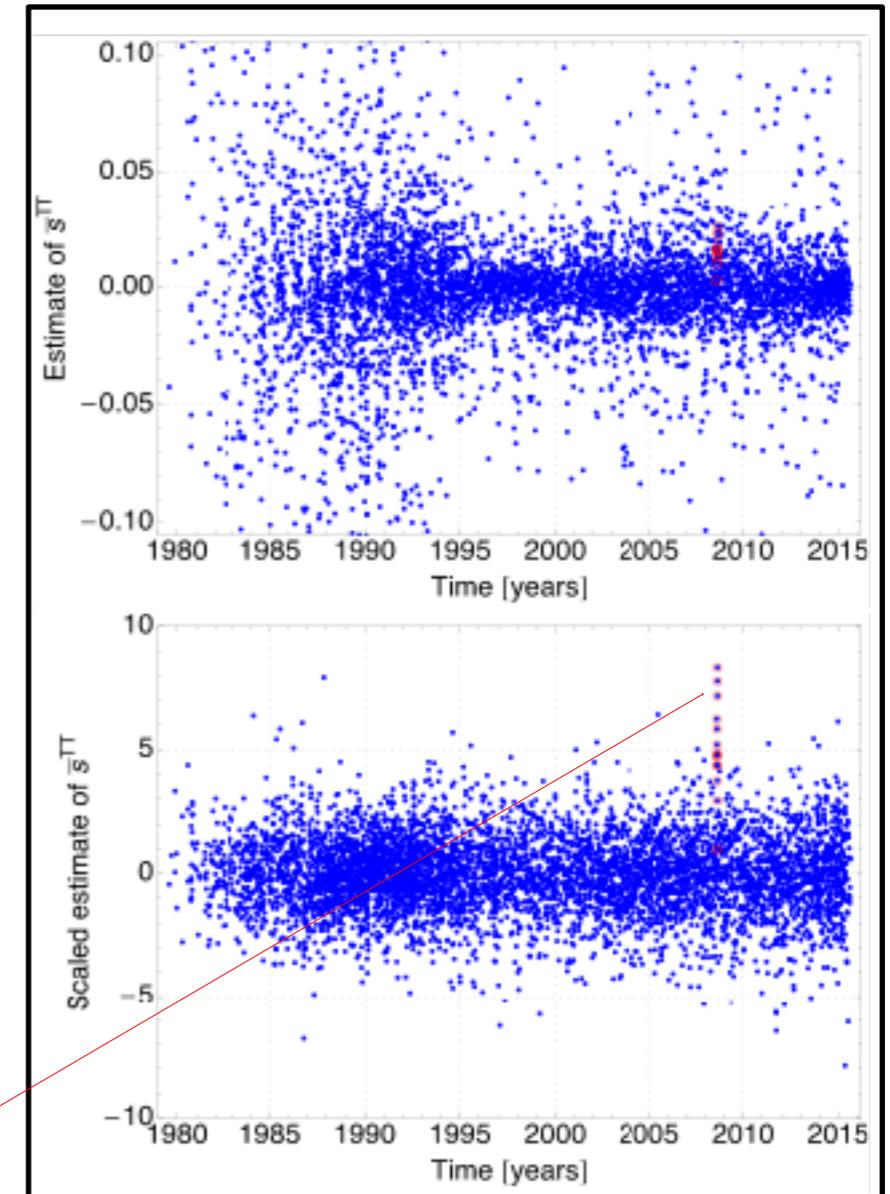
with $x_{1/2}$ positions of stations and $r_{1/2} = |\mathbf{x}_{1/2}| \quad \mathbf{n}_{1/2} = \frac{\mathbf{x}_{1/2}}{r_{1/2}}$
and \mathbf{k} is the direction of the source.



- Modification of CALC with module USERPART. Test with post-fit analysis :
 $\bar{s}^{TT} = (-0.6 \pm 2.1) \times 10^{-8}$
- 2 & 8 Ghz for solar activity
- 8 Ghz for SME analysis
- Systematics on CONT08 data but we kept them.

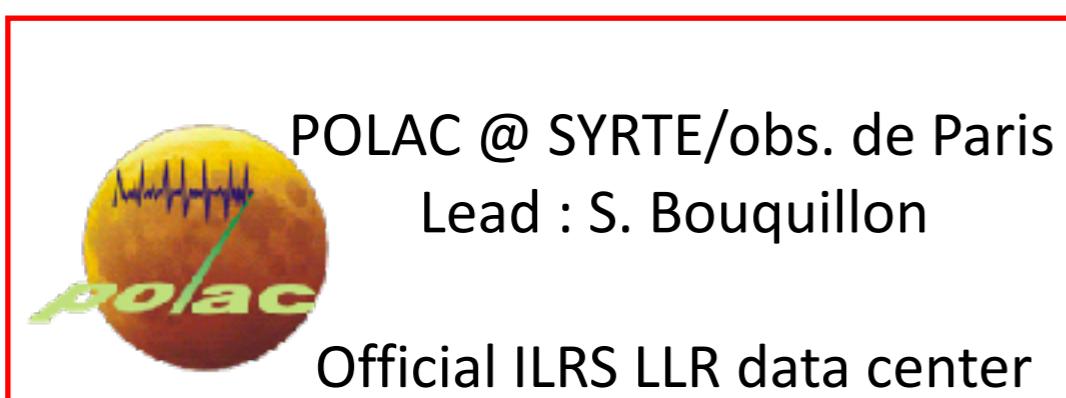
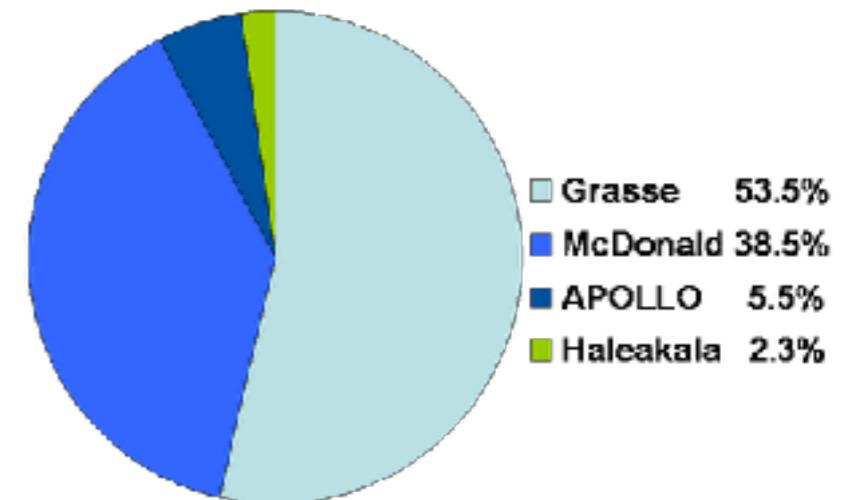


$$\bar{s}^{TT} = (-5 \pm 8) \times 10^{-5}$$



CLPL, Hees & Lambert, PRD 2016
arXiv:1604.01663

International Laser Ranging Service (ILRS)



- 20721 normal points 08/1969 to 12/2013
- Prediction tool for LLR station
- Validation of LLR observations
- Analytical theory of Moon motion : ELP

SME and planetary motions

LLR + gravimetry

PHYSICAL REVIEW D 92, 064049 (2015)

Testing Lorentz symmetry with planetary orbital dynamics

A. Hees,^{1,*} Q. G. Bailey,² C. Le Poncin-Lafitte,³ A. Bourgoin,³ A. Rivoldini,⁴ B. Lamine,⁵ F. Meynadier,³ C. Guerlin,^{6,3} and P. Wolf³

- Main advantage: decorrelation of the SME parameters

- Use of perihelion precession

Planet	$\dot{\Omega}$ (mas × cy ⁻¹)	$\dot{\omega}$ (mas × cy ⁻¹)
Mercury	1.4 ± 1.8	0.4 ± 0.6
Venus	0.2 ± 1.5	0.2 ± 1.5
EMB	0.0 ± 0.9	-0.2 ± 0.9
Mars	-0.05 ± 0.13	-0.04 ± 0.15
Jupiter	-40 ± 42	-41 ± 42
Saturn	-0.1 ± 0.4	0.15 ± 0.65

- 7 linear combinations determined

SME linear combinations	Estimation
b_1	$(-0.8 \pm 2.0) \times 10^{-10}$
b_2	$(2.3 \pm 2.3) \times 10^{-11}$
b_3	$(3.0 \pm 9.7) \times 10^{-12}$
b_4	$(0.2 \pm 1.1) \times 10^{-12}$
b_5	$(-0.3 \pm 2.4) \times 10^{-13}$
b_6	$(0.2 \pm 1.1) \times 10^{-9}$
b_7	$(-0.6 \pm 2.3) \times 10^{-9}$
b_8	$(0.3 \pm 1.7) \times 10^{-9}$

$$b_1 = (\bar{s}^{XX} - \bar{s}^{YY}), \quad (15a)$$

$$b_2 = -1.37b_1 + \bar{s}^Q, \quad (15b)$$

$$b_3 = -0.15b_1 - 0.31\bar{s}^Q + \bar{s}^{XY}, \quad (15c)$$

$$b_4 = 0.013b_1 + 0.064\bar{s}^Q - 0.48\bar{s}^{XY} + \bar{s}^{XZ}, \quad (15d)$$

$$b_5 = 0.26b_1 - 0.31\bar{s}^Q + 0.81\bar{s}^{XY} - 1.67\bar{s}^{XZ} + \bar{s}^{YZ} \quad (15e)$$

$$b_6 = -35.5b_1 + 9.35\bar{s}^Q - 22.67\bar{s}^{XY} - 33.95\bar{s}^{XZ} \\ + 7.83\bar{s}^{YZ} + \bar{S}_\odot^X, \quad (15f)$$

$$b_7 = 1641.4b_1 - 2101.1\bar{s}^Q + 4939.9\bar{s}^{XY} - 8846.8\bar{s}^{XZ} \\ + 4810.6\bar{s}^{XZ} - 0.89\bar{S}_\odot^X + \bar{S}_\odot^Y, \quad (15g)$$

- Use of Lunar Laser Ranging and gravimetry

SME coefficients	Estimation
$\bar{s}^{XX} - \bar{s}^{YY}$	$(9.6 \pm 5.6) \times 10^{-11}$
$\bar{s}^Q = \bar{s}^{XX} + \bar{s}^{YY} - 2\bar{s}^{ZZ}$	$(1.6 \pm 0.78) \times 10^{-10}$
\bar{s}^{XY}	$(6.5 \pm 3.2) \times 10^{-11}$
\bar{s}^{XZ}	$(2.0 \pm 1.0) \times 10^{-11}$
\bar{s}^{YZ}	$(4.1 \pm 5.0) \times 10^{-12}$
\bar{s}^{TX}	$(-7.4 \pm 8.7) \times 10^{-6}$
\bar{s}^{TY}	$(-0.8 \pm 2.5) \times 10^{-5}$
\bar{s}^{TZ}	$(0.8 \pm 5.8) \times 10^{-5}$
$\alpha(\bar{a}_{\text{eff}}^e)^X + \alpha(\bar{a}_{\text{eff}}^p)^X$	$(-7.6 \pm 9.0) \times 10^{-6} \text{ GeV}/c^2$
$\alpha(\bar{a}_{\text{eff}}^e)^Y + \alpha(\bar{a}_{\text{eff}}^p)^Y$	$(-6.2 \pm 9.5) \times 10^{-5} \text{ GeV}/c^2$
$\alpha(\bar{a}_{\text{eff}}^e)^Z + \alpha(\bar{a}_{\text{eff}}^p)^Z$	$(1.3 \pm 2.2) \times 10^{-4} \text{ GeV}/c^2$
$\alpha(\bar{a}_{\text{eff}}^n)^X$	$(-5.4 \pm 6.3) \times 10^{-6} \text{ GeV}/c^2$
$\alpha(\bar{a}_{\text{eff}}^n)^Y$	$(4.8 \pm 8.2) \times 10^{-4} \text{ GeV}/c^2$
$\alpha(\bar{a}_{\text{eff}}^n)^Z$	$(-1.1 \pm 1.9) \times 10^{-3} \text{ GeV}/c^2$

Fitted in residuals.
 Different experiments = different linear combination
 All together = find constraint on single coefficient...

Gaia is very powerful to constrain SME

- Main advantage: decorrelation of the 9 SME parameters because of the variety of orbital parameters (not feasible with planets)

SME Parameter	1σ - 5yr	1σ - 10yr
$\bar{s}^{XX} - \bar{s}^{YY}$	3.7×10^{-12}	6.5×10^{-12}
$\bar{s}^{XX} + \bar{s}^{YY} - \bar{s}^{ZZ}$	6.4×10^{-12}	2.1×10^{-12}
\bar{s}^{XY}	1.6×10^{-12}	7.0×10^{-13}
\bar{s}^{XZ}	9.2×10^{-13}	3.7×10^{-13}
\bar{s}^{YZ}	1.7×10^{-12}	5.8×10^{-13}
\bar{s}^{TX}	5.6×10^{-9}	1.1×10^{-9}
\bar{s}^{TY}	8.8×10^{-9}	2.0×10^{-9}
\bar{s}^{TZ}	1.6×10^{-8}	4.0×10^{-9}

1 order of magnitude improvement wrt current constraints

- To be extended to take into account violations of the Einstein Equivalence Principle (gravity-matter Lorentz violating terms)

Extremely promising results !

LLR and SME

State of the art

PRL 99, 241103 (2007) PHYSICAL REVIEW LETTERS week ending 14 DECEMBER 2007

Testing for Lorentz Violation: Constraints on Standard-Model-Extension Parameters via Lunar Laser Ranging

James B. R. Battat, John F. Chandler, and Christopher W. Stubbs
Harvard-Smithsonian Center for Astrophysics, Cambridge, Massachusetts 02138, USA
(Received 6 September 2007; published 13 December 2007)

We present constraints on violations of Lorentz invariance based on archival lunar laser-ranging (LLR) data. LLR measures the Earth-Moon separation by timing the round-trip travel of light between the two bodies and is currently accurate to the equivalent of a few centimeters (parts in 10^{11} of the total distance). By analyzing this LLR data under the standard-model extension (SME) framework, we derived six observational constraints on dimensionless SME parameters that describe potential Lorentz violation. We found no evidence for Lorentz violation at the 10^{-6} to 10^{-11} level in these parameters. This work constitutes the first LLR constraints on SME parameters.

DOI: 10.1103/PhysRevLett.99.241103 PACS numbers: 04.80.-y, 06.30.Gv, 11.30.Cp

14401 normal points spanning over 09/1969 to 12/2003.

Post-fit LLR analysis:

- Looked for analytical signals derived in Bailey *et. al.*, 2006.
- Planetary Ephemeris Program (PEP) developed at MIT to re-iterate => **cross-correlation possible**

Provide 6 SME coefficient estimates combinations at the level 10^{-6} and 10^{-11} .

Realistic error $\sigma_r = F\sigma$ with $F = 20$, from PPN analysis.

$\alpha = \text{cste}$ and $\beta = \text{cste}$. From observation $T = 2\pi/\dot{\alpha} = 2\pi/\dot{\beta} = 18, 6 \text{ y}$.
Analytic solution only accounting for short periodic terms. Only available for few years time-span.

Least-square fit, estimating only SME coefficients. No correlations taken into account with others global parameters, only cross-correlation.

$$\delta r_{SME}(t) = A_{SME} \cos(2\omega t + 2\theta) + B_{SME} \sin(2\omega t + 2\theta)$$

SME oscillating signatures at the same frequencies than natural frequencies :

Lunar potential 2d degree !

$$\delta r_{2\omega,2\theta}(t) = [A_{20} + A_{22}] \cos(2\omega t + 2\theta) + B_{22} \sin(2\omega t + 2\theta)$$

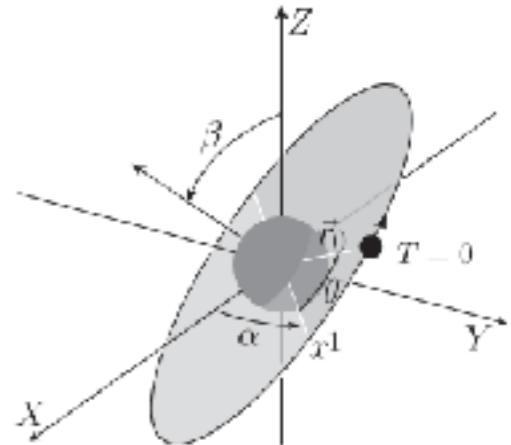


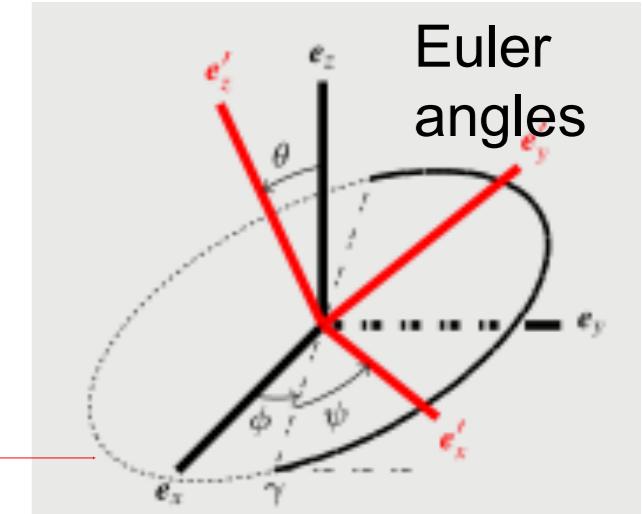
FIG. 2. Lunar orbital parameters: here the Earth is shown translated to the center of the Sun-centered coordinate system. The lunar orbit is described by r_0 , the mean distance between the Earth and Moon, e (not labeled) the eccentricity of the lunar orbit, α , the longitude of the ascending node, β , the angle between the normal to the lunar orbital plane and the normal to the Earth's equatorial plane, and θ , the angle, along the lunar orbit, subtended by the ascending node line and the position of the Moon at $t = 0$. Reprinted figure with permission from [6]. Copyright 2006 by the American Physical Society.

ELPN, SME lunar ephemeride

Dynamical modeling from scratch :

- Integrate the motion of Solar System bodies
 - Newtonian point-mass interactions.
 - Figure potential of bodies :
 - Orientation of bodies,
 - J_2 of the Sun,
 - J_2, J_3, J_4 and J_5 of the Earth,
 - Degree 2, 3, 4 and 5 of the Moon.
 - Tidal and spin effects :
 - Dissipation inside anelastic bodies,
 - Time-lag of degree 2 with RK4.
 - Relativistic point-mass interactions :
 - Solar system barycentre,
 - Integrate the time scale correction (in pure GR).
 - SME correction for Earth-Moon system only
 - Lunar librations :
 - Momentums due to punctual (5th degree) and extended (2th degree) bodies,
 - Geodetic precession effect,
 - Fluid lunar core,
 - Friction between solid mantle and fluid core.
 - Integrate partials at the same time than forces and momentums. **ODE system of 6000 equations**

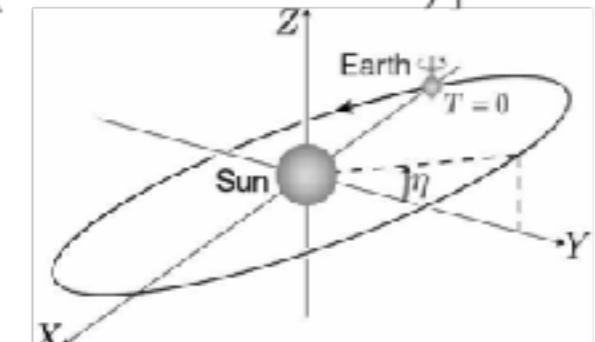
ODEX, Everheart
quadruple precision = 10^{-34}
6 CPU days of a solution !



Pre-processing of LLR normal points : Update of the CAROLL software

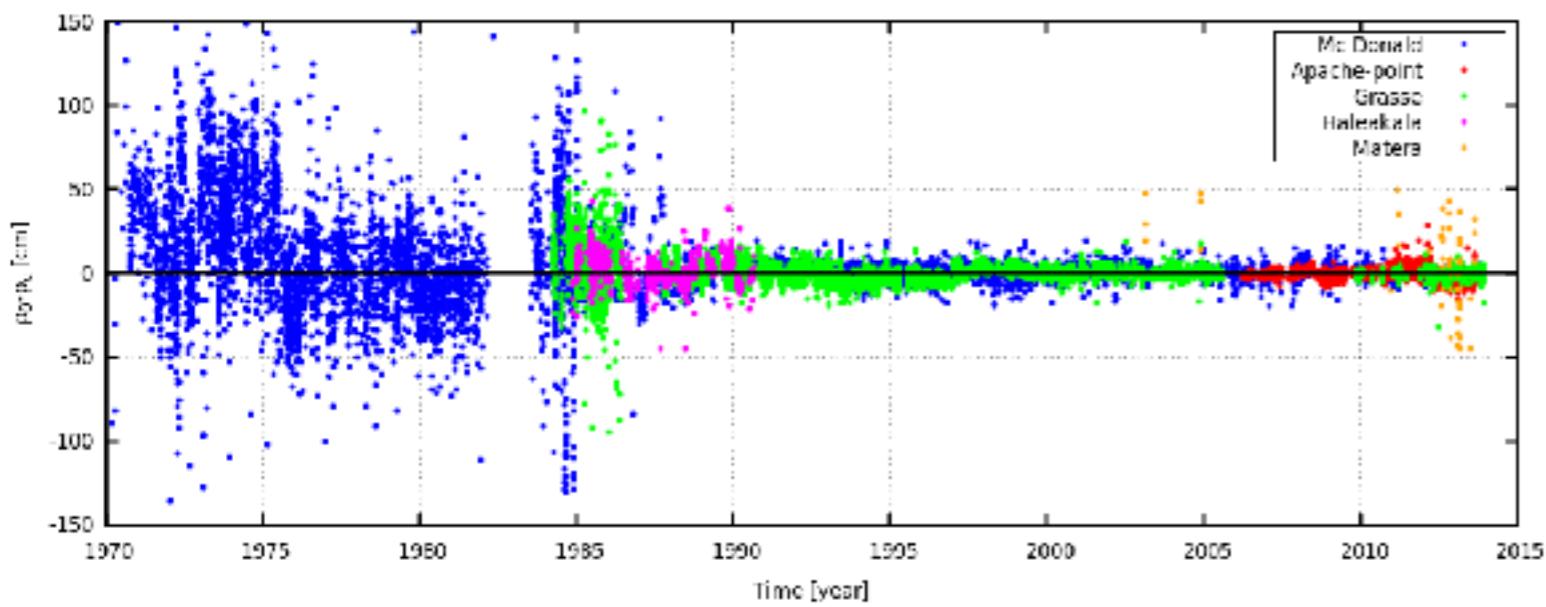
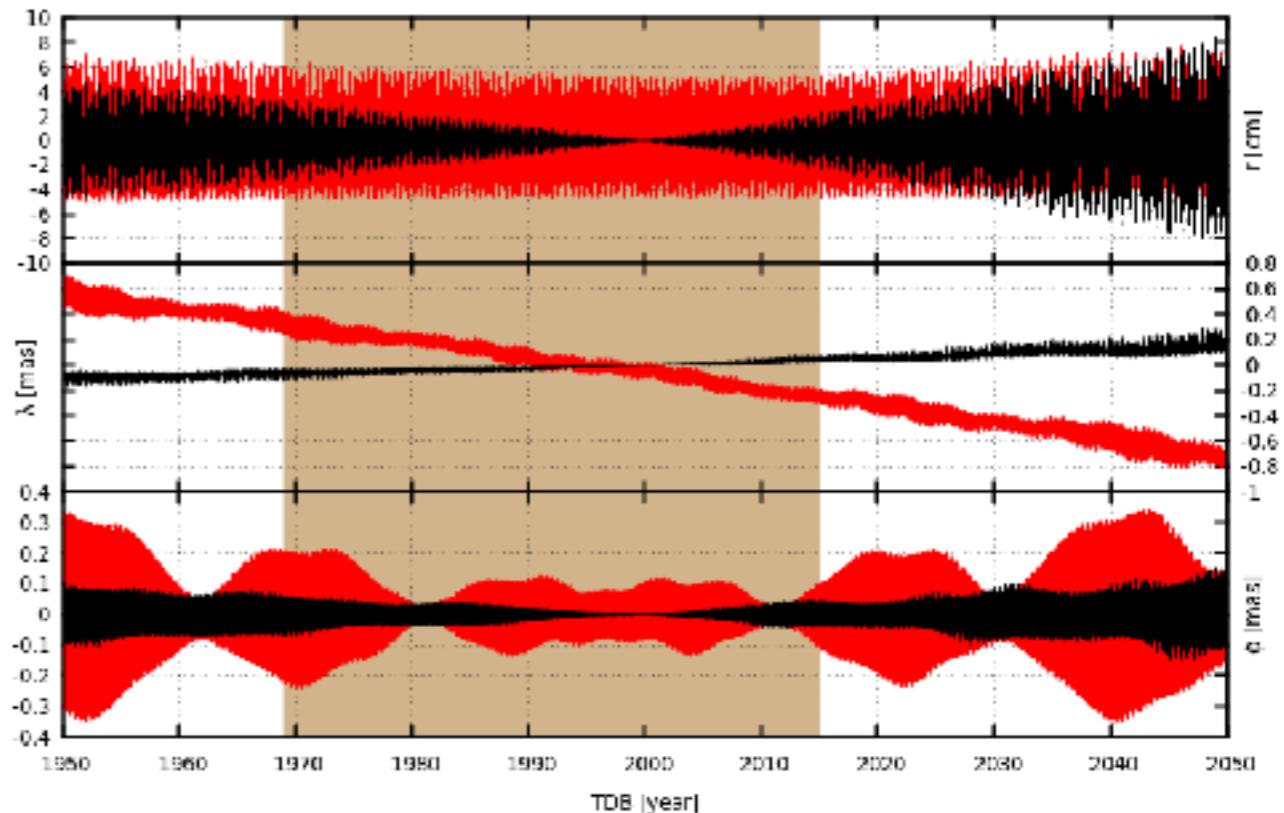
- Tchebychev polynomials of the solution and partials.
- LLR analysis in SME framework by chi-square fitting

$$a_{LV}^J = \frac{\bar{G}M}{r^3} \left[\bar{s}_t^{JK} r^K - \frac{3}{2} \bar{s}_t^{KL} \hat{r}^K \hat{r}^L r^J + 3 \bar{s}^{TK} \hat{V}^K r^J - \bar{s}^{TJ} \hat{V}^K r^K - \bar{s}^{TK} \hat{V}^J r^K + 3 \bar{s}^{TL} \hat{V}^K \hat{r}^K \hat{r}^L r^J + 2 \frac{\delta m}{M} (\bar{s}^{TK} \hat{v}^K r^J - \bar{s}^{TJ} \hat{v}^K r^K) \right],$$



ELPN vs JPL-DE430

We compute difference pre (black curve) and post-fit (red curve) between DE430 and ELPN over the orbit of the Moon.



LLR Stations	Years	NP	wrms (cm)
Mc Donald 270cm	1969-1985	3480	29.3
Mc Donald MLRS1	1983-1988	584	43.6
Mc Donald MLRS2	1988-2014	3100	4.5
Grasse (Rubis)	1984-1986	1154	14.7
Grasse (Yag)	1987-2005	9294	3.4
Grasse (MeO)	2009-2014	966	1.2
Haleakala	1984-1990	735	7.4
Matera	2003-2014	79	9.3
Apache Point	2006-2014	1787	3.5

Our SME analysis

see Bourgoin et al., PRL, 2016

SME parameters considered :

$$\begin{aligned}\bar{s}^A &= \bar{s}^{XX} - \bar{s}^{YY} & \bar{s}^B &= \bar{s}^{XX} + \bar{s}^{YY} - 2 \bar{s}^{ZZ} \\ \bar{s}^C &= \bar{s}^{TY} + 0.43 \bar{s}^{TZ} & \bar{s}^D &= \bar{s}^B - 0.045 \bar{s}^{YZ}. \\ &\bar{s}^{TX}, \bar{s}^{XY}, \bar{s}^{XZ}.\end{aligned}$$

\bar{s}^A and \bar{s}^B

Enforce the traceless condition

Our SME analysis

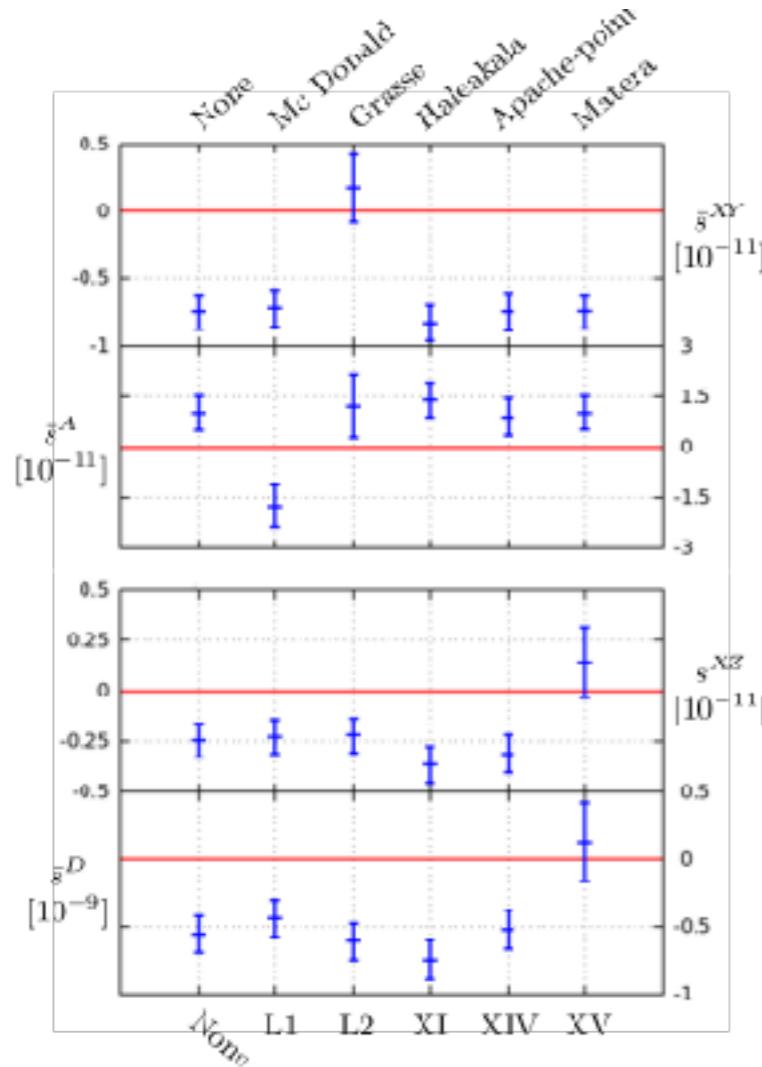
see Bourgoin et al., PRL, 2016

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\bar{s}^A and \bar{s}^B

Enforce the traceless condition



Study of systematics, i.e. split data set !

Our SME analysis

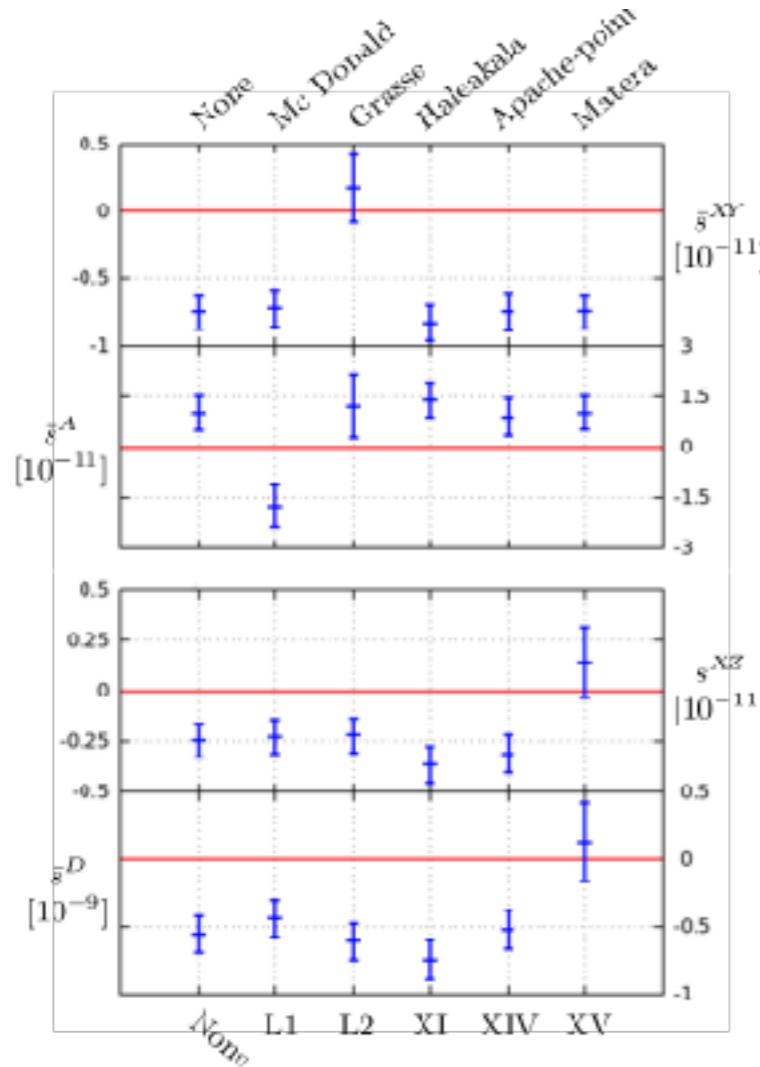
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\bar{s}^A and \bar{s}^B

Enforce the traceless condition



Variation of SME sigma with data-set

Sigma over-estimated.
Need to find a **realistic scale factor F** (not from PPN !)

Study of systematics, i.e. split data set !

Our SME analysis

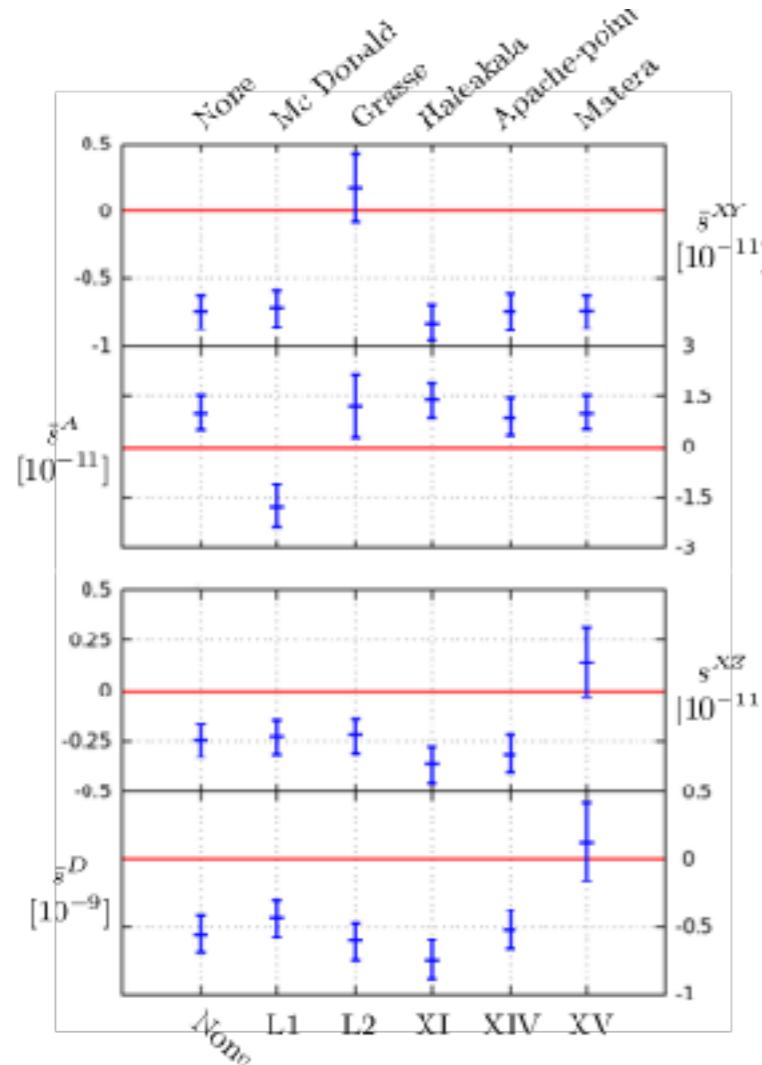
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\bar{s}^A and \bar{s}^B

Enforce the traceless condition



Variation of SME sigma with data-set

Sigma over-estimated.
Need to find a **realistic scale factor F** (not from PPN !)

Jackknife resampling method allows to estimate systematics uncertainties :

SME	Other works	This work
\bar{s}^{TX}	$(+5.2 \pm 5.3) \times 10^{-9}$	$(-0.9 \pm 1.0) \times 10^{-8}$
\bar{s}^{XY}	$(-3.5 \pm 3.6) \times 10^{-11}$	$(-5.7 \pm 7.7) \times 10^{-12}$
\bar{s}^{XZ}	$(-2.0 \pm 2.0) \times 10^{-11}$	$(-2.2 \pm 5.9) \times 10^{-12}$
\bar{s}^A	$(-1.0 \pm 1.0) \times 10^{-10}$	$(+0.6 \pm 4.2) \times 10^{-11}$
\bar{s}^C	$(-1.0 \pm 0.9) \times 10^{-8}$	$(+6.2 \pm 7.9) \times 10^{-9}$
\bar{s}^D	$(-1.2 \pm 1.2) \times 10^{-10}$	$(+2.3 \pm 4.5) \times 10^{-11}$

Study of systematics, i.e. split data set !

Our SME analysis

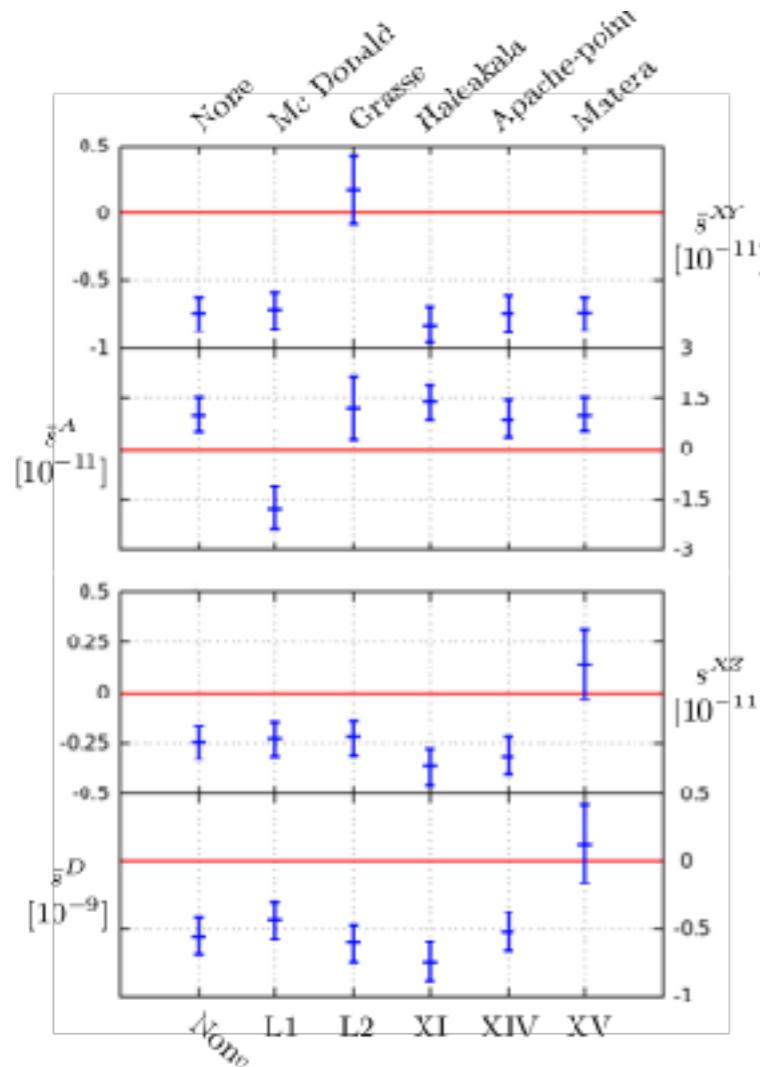
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\bar{s}^A and \bar{s}^B

Enforce the traceless condition



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\bar{s}^D	$(-1.2 \pm 1.2) \times 10^{-10}$	$(+2.3 \pm 4.5) \times 10^{-11}$

Study of systematics, i.e. split data set !

We improve :

- by a factor 30 to 800 results from Battat et al. 2007 (different combinaison)
- by a factor 5 post-fit analysis of 1 coefficient from binary pulsars

LLR & GRAIL

Launched : 09 / 2011

Science : 03-05 /2012

Improved knowledge of Moon's gravity field by a factor 100.

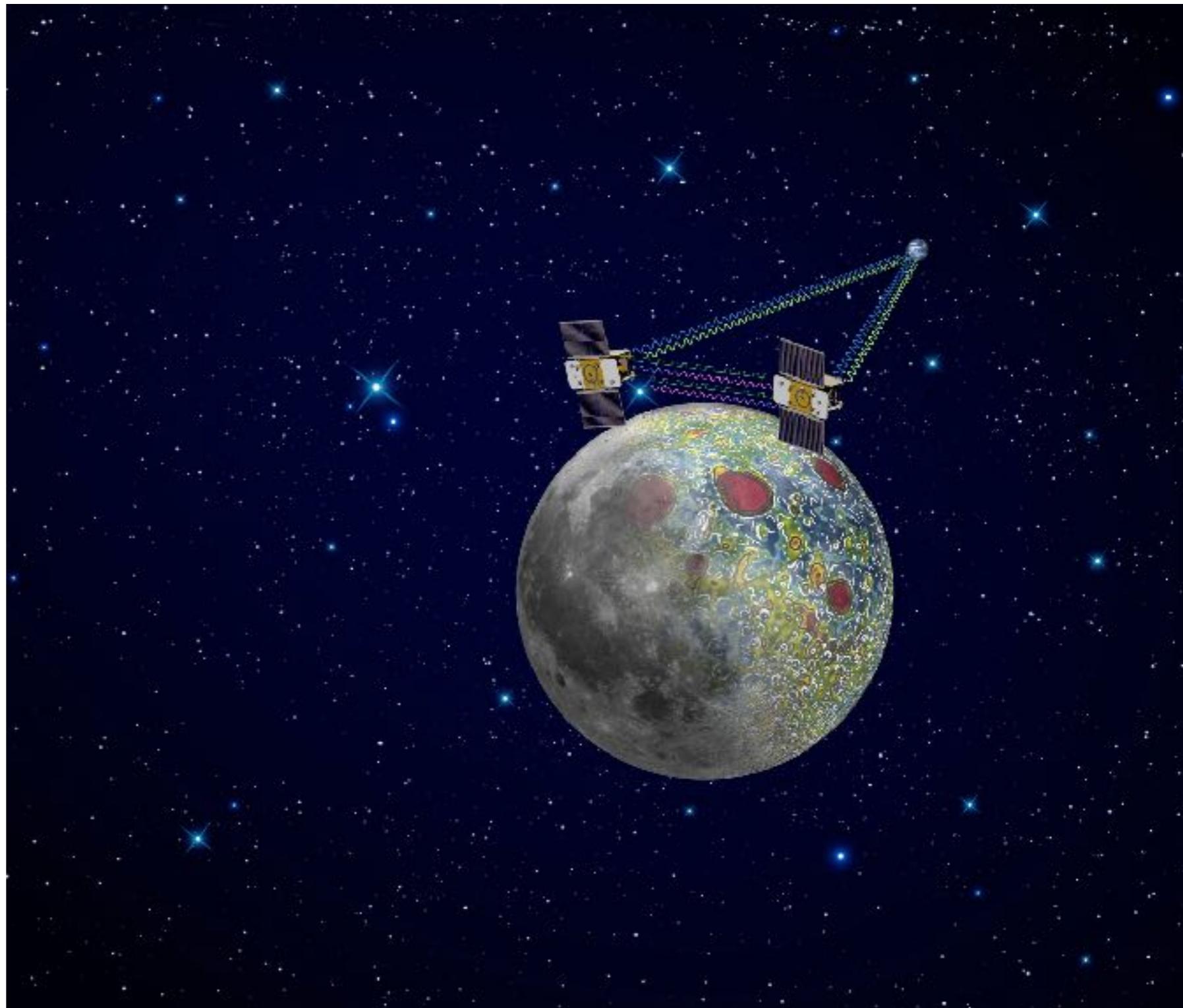
Our idea :

Combine LLR & GRAIL data together.

Why ?

Traceless condition is slightly correlated with effects from lunar potential (at same frequency)

Project ongoing @ SYRTE
(CLPL, Bourgoin) + UNI Bern
(Bertone)

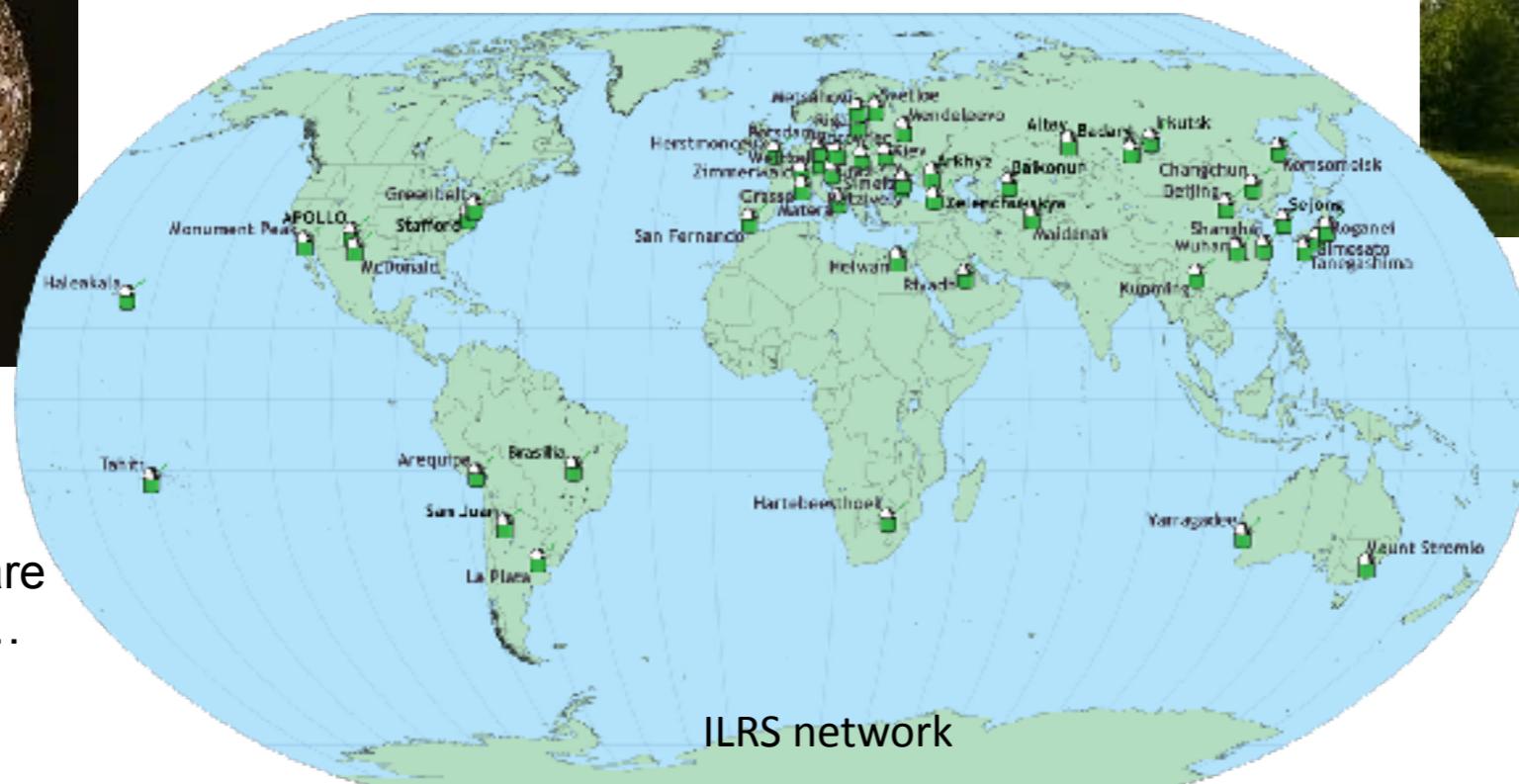


What's next ?

Satellite Laser Ranging (SLR)



LAGEOS
1976 – today !



But a lot of probes are tracked every day...



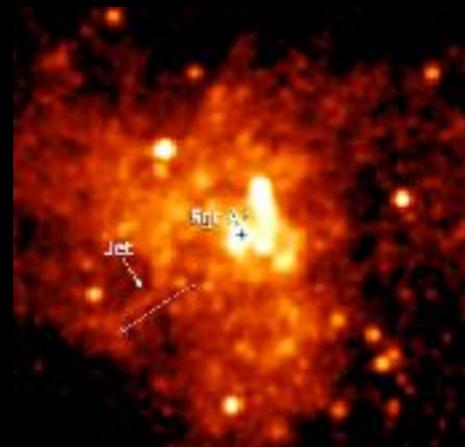
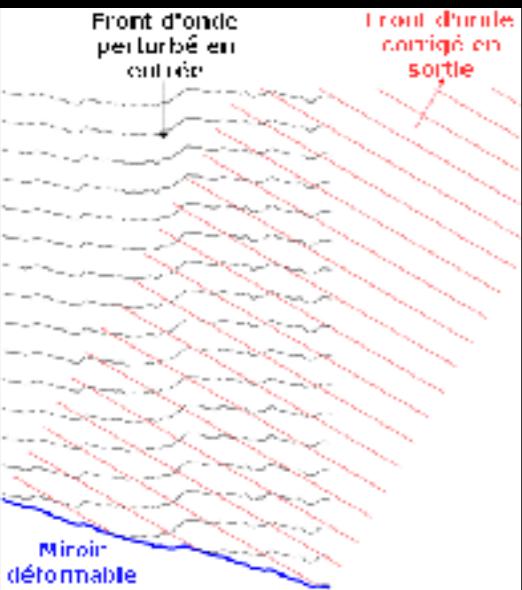
Wetzell Geodetic Obs., Germany

Modification of CNES/GINS software (similar to OD-ODP, Orbit14 & GeoDyn) to be able to perform orbit determination of probe in SME framework :

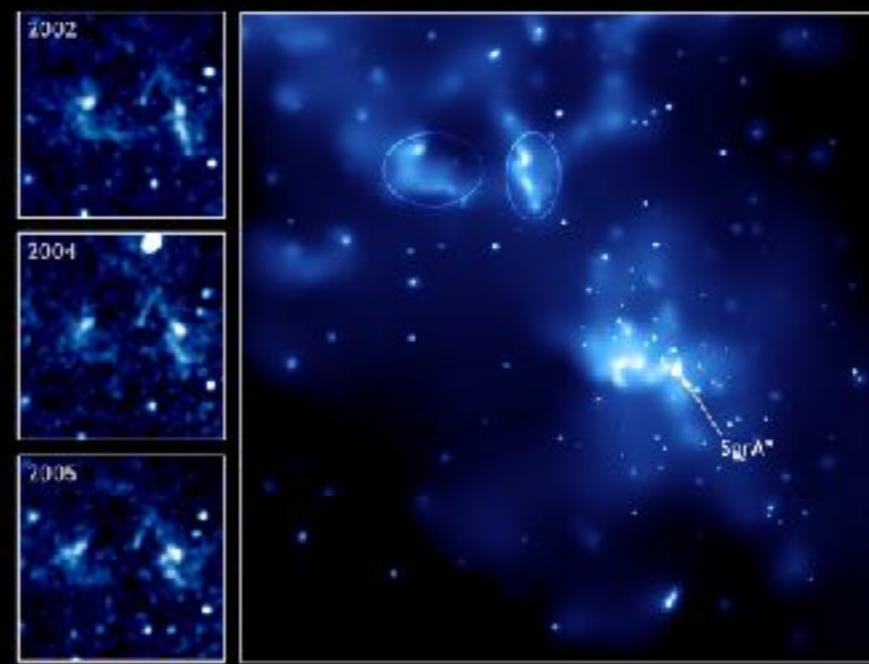
- apply to LAGEOS, LARES.
- Consider also the case of interplanetary probe as Cassini, JUNO or JUICE

Les tests en champ fort: expérience GRAVITY

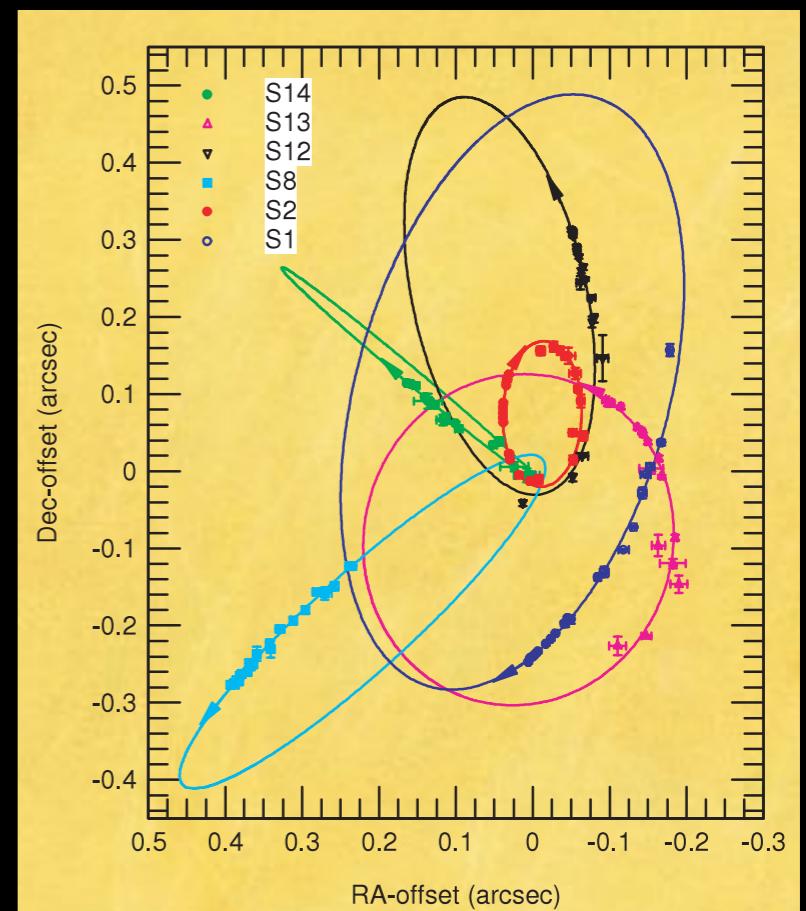
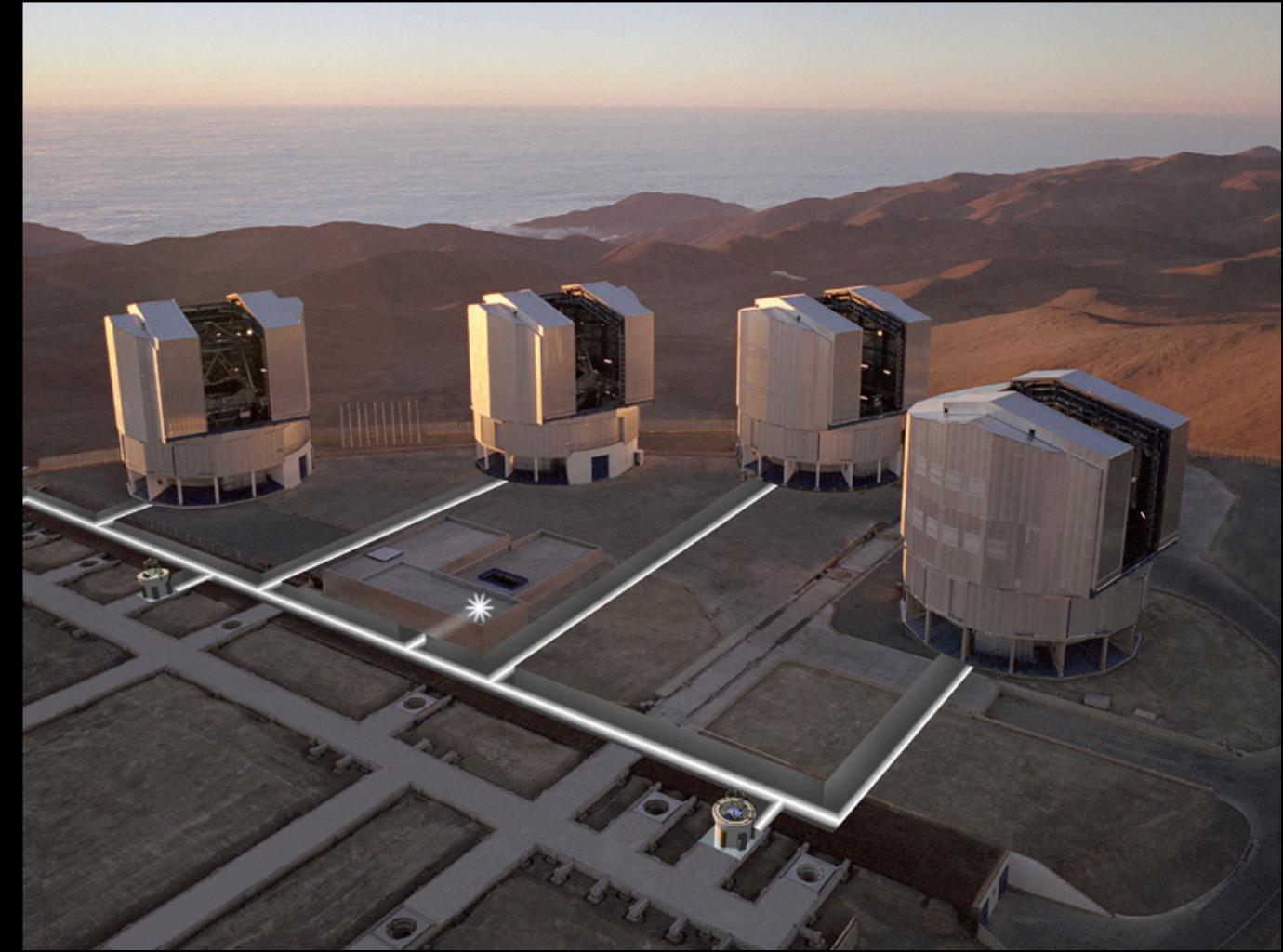
Mesure d'interférométrie
longueur d'onde infrarouge
Utilisation de l'optique adaptative



On observera
Sagittarius A (près du
centre galactique) près
du trou noir central.



observations de Sgr A en X du satellite Chandra



Eisenhauer et al. 2005

Mais alors... Einstein a toujours raison aujourd'hui?

Mais alors... Einstein a toujours raison aujourd'hui?

Deux petits exemples d'anomalies
qui font (ou "ont fait") jaser



L'anomalie Pioneer

Révélée par le JPL en 2002

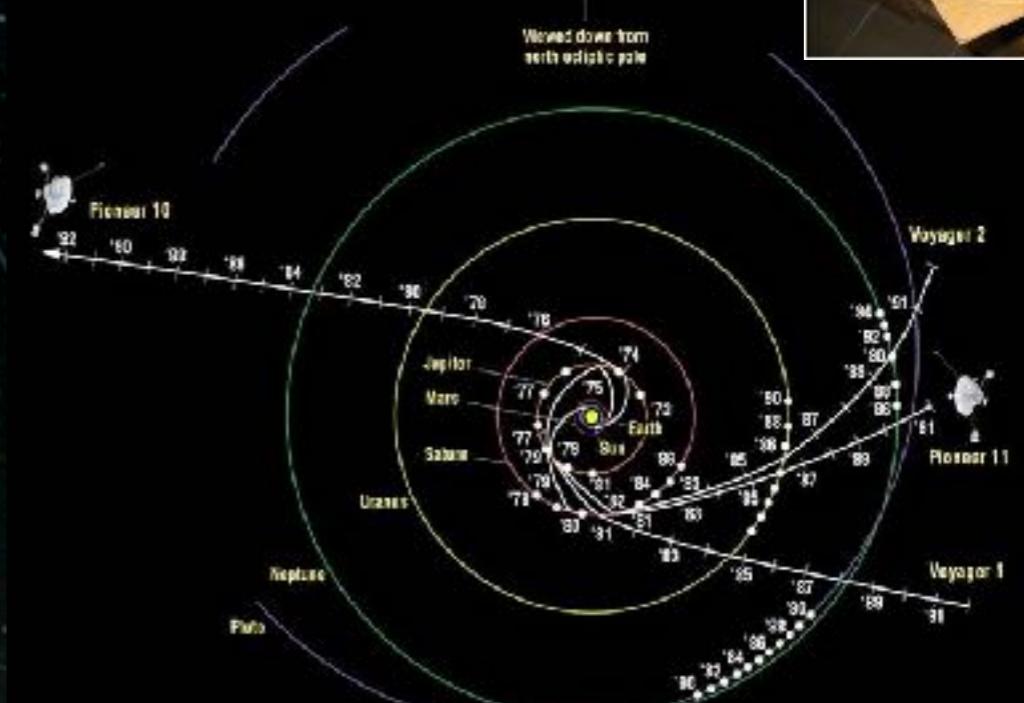
Les théoriciens se sont amusés à imaginer les théories les plus exotiques possible : des centaines de publications !

Officieusement a sombré *corps et biens* depuis quelques semaines.

A ce jour, on attend encore la publication de la part du JPL...

Ces sondes ne sortaient pas suffisamment vite du système solaire.

Une longue analyse a eu lieu pour déceler l'effet thermique manquant

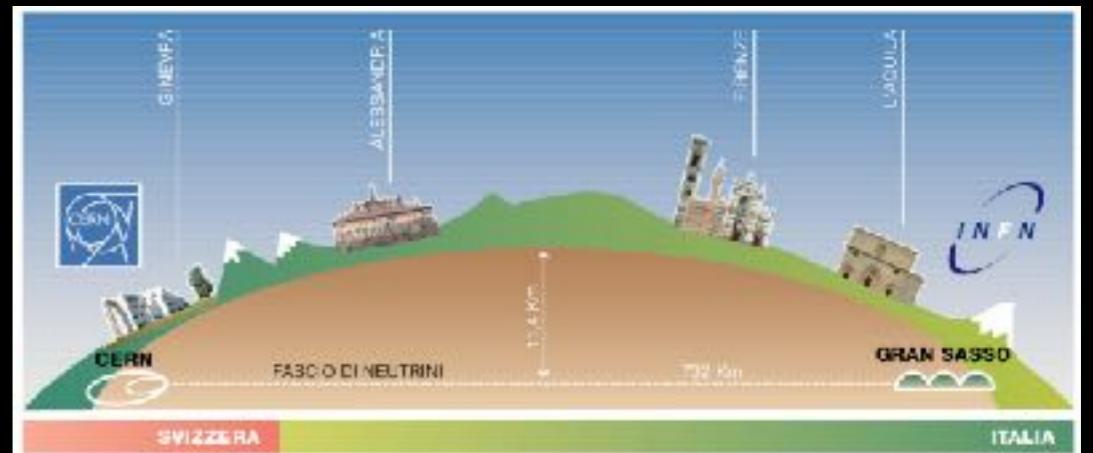


Un neutrino fou pris en excès de vitesse :-3 points

Sept. 2011, pour 60 ns de trop, un neutrino dépasse la limitation de vitesse. Le gendarme en charge de l'affaire : la collaboration OPERA.



Centre de "traitement des amendes" de Gran Sasso.



Labo. d'OPERA à Gran Sasso

Mars 2012 : une collaboration concurrente, ICARUS, démontre que le résultat n'est pas fiable.

Le parquet a décidé de classer l'affaire sans suite...

cause probable de l'erreur: un câble défectueux du récepteur GPS du "radar"

Conclusions

- At moment, GR is tested via PPN formalism and fifth force
- Existing VLBI, LLR, SLR and probe navigation data are existing, growing with time and with better accuracy
- New space missions are ongoing (Gaia, JUNO, Aces, JUICE) with unprecedented accuracy
- Since 5 years, people try to extend gravitational tests to more alternative theories
 - SME, since it happens even at Newtonian Level, is a good first candidate
 - But... we fit in the residuals.
- New generation of SME patch for real data analysis code is ongoing for Gaia and VLBI. Soon for LLR and in the future SLR.
- The resulting methodology will be next applied to other theories and objects (binary pulsars)