

The ATLAS High-Granularity Timing Detector

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on behalf of the HGTD group

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LAL Seminar
25th of September

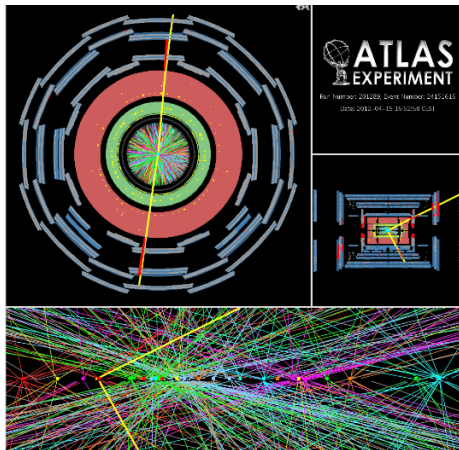


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The High-Luminosity LHC

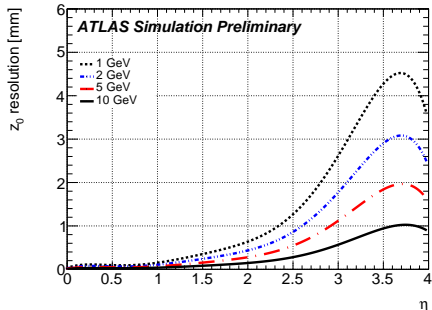
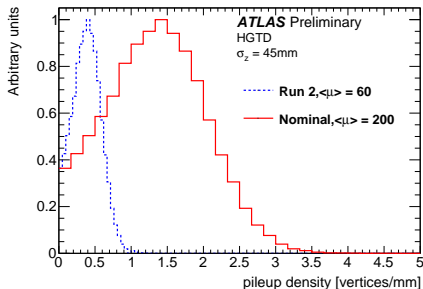
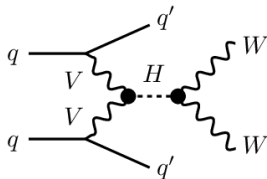
- ▶ The HL-LHC :
 - ▶ will start operation in 2026
 - ▶ instant luminosity $5 - 7 \times$ nominal
 - ▶ integrated luminosity $10 \times$ LHC
- ▶ Pileup is one of the most difficult challenges of the HL-LHC
- ▶ **ATLAS Upgrade** involving
 - ▶ new electronics in LAr and Tile
 - ▶ improved TDAQ
 - ▶ improved muon trigger/tagging
 - ▶ **ITk: tracking up to $|\eta| = 4.0$**
 - ▶ **HGTD**



Key aspect for ATLAS analysis: maintain the track-vertex association performance in spite of the harsh environment

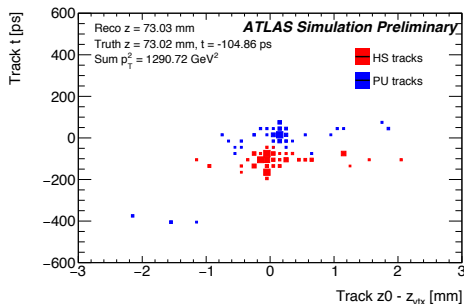
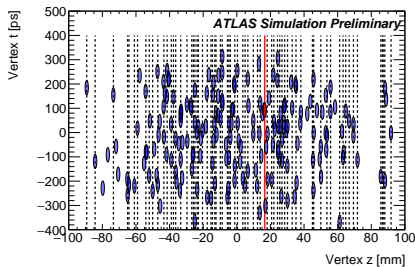
Motivation: beam conditions and z_0

- ▶ Increased luminosity at the HL-LHC:
 - ▶ expected $\langle\mu\rangle = 200$
 - ▶ average interaction density ~ 1.8 vtx/mm
- ▶ The z_0 resolution worsens with $|\eta|$:
 - ▶ several vertexes could be merged
 - ▶ degradation of performance in forward jet reconstruction (i.e. critical for VBF signals)



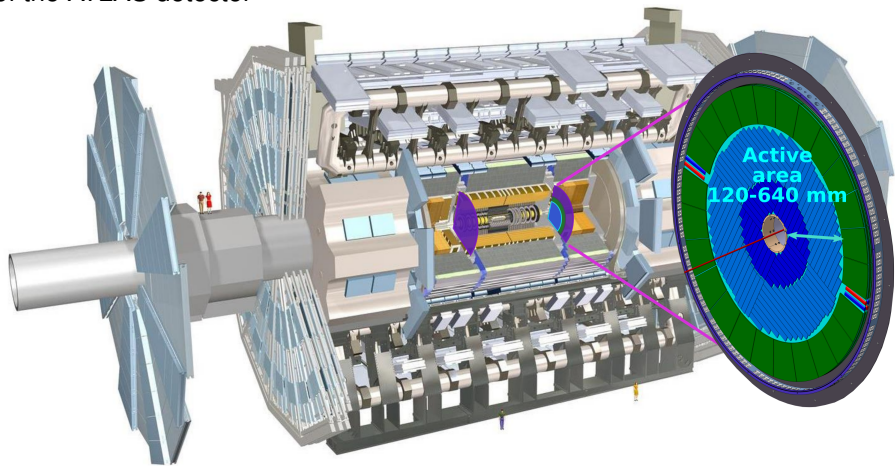
Motivation: precise timing measurements

- ▶ An additional dimension (4D) in existing detectors can provide a new handle on increased interactions per mm
- ▶ Expected nominal HL-LHC beam conditions: $\sigma_z = 45$ mm and $\sigma_t = 175$ ps
- ▶ Assigning a time to a track with a small enough time resolution would boost the discrimination power of ATLAS (~ 6 times for $\sigma_t = 30$ ps)



The High-Granularity Timing Detector

The HGTD will provide time measurements for objects in the forward regions of the ATLAS detector



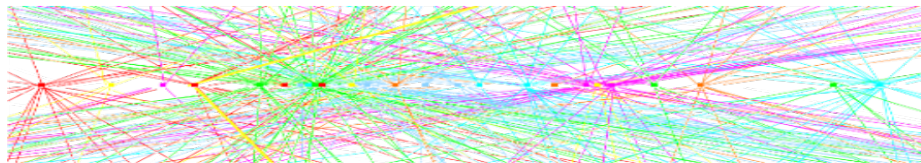
The HGTD: timing in ATLAS

General parameters:

- ▶ $2.4 < |\eta| < 4.0$
- ▶ Active area 6.3 m^2 (total)
- ▶ Design based on $1.3 \times 1.3 \text{ mm}^2$ silicon pixels ($2 \times 4 \text{ cm}^2$ sensors)
→ optimised for $< 10\%$ occupancy and small capacitance
- ▶ Radiation hardness up to $4.5 \cdot 10^{15} \text{ n}_{eq}/\text{cm}^2$ and 4.5 MGy
- ▶ Number of hits per track:
 - ▶ 2 in $2.4 < |\eta| < 3.1$
 - ▶ 3 in $3.1 < |\eta| < 4.0$

Goal:

- ▶ Resolve close-by vertices
 - ▶ **small timing resolution** (\sim few 10s of picoseconds).
- ▶ Provide minimum bias trigger
- ▶ Instantaneous and unbiased luminosity measurement

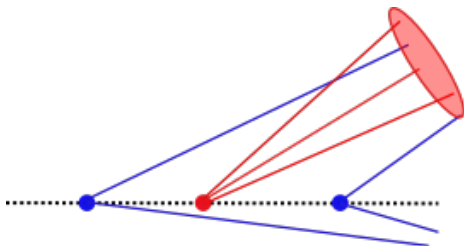


Performance Studies



Object Selection with Timing Information

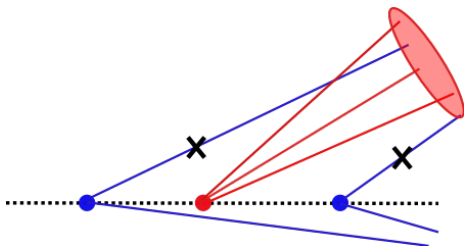
- ▶ $\langle \mu \rangle \sim 60$
- ▶ $\Delta Z > \sigma_{z_0}$



- ▶ Example:
pileup tracks in a forward jet

Object Selection with Timing Information

- ▶ $\langle \mu \rangle \sim 60$
- ▶ $\Delta Z > \sigma_{z_0}$

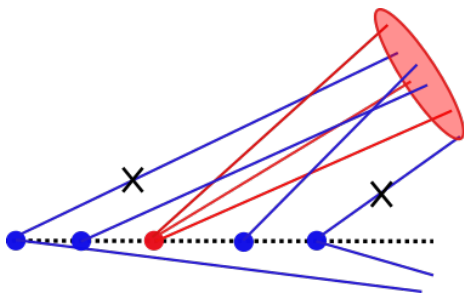


- ▶ Example:
pileup tracks in a forward jet
- ▶ Well separated vertices:

$$\frac{|z_0 - z_{vtx}|}{\sigma_{z_0}} < 2$$

Object Selection with Timing Information

- ▶ $\langle \mu \rangle \sim 200$
- ▶ $\Delta Z < \sigma_{z_0}$

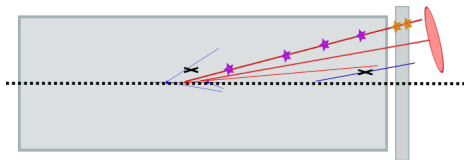


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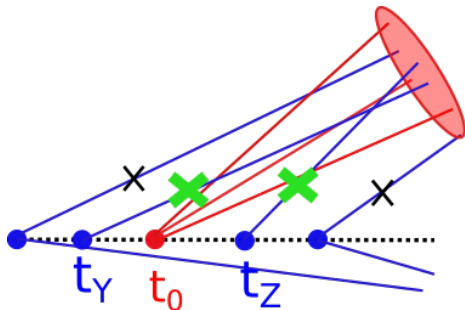


- ▶ Example:
pileup tracks in a forward jet
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Object Selection with Timing Information

- ▶ $\langle \mu \rangle \sim 200$
- ▶ $\Delta Z < \sigma_{z_0}$
- ▶ $\Delta t > \sigma_t$



- ▶ Example:
pileup tracks in a forward jet
- ▶ Well separated vertices:

$$\frac{|z_0 - z_{\text{vtx}}|}{\sigma_{z_0}} < 2$$

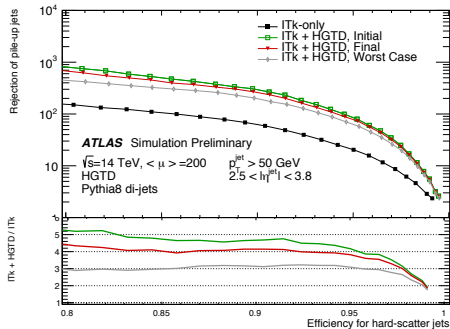
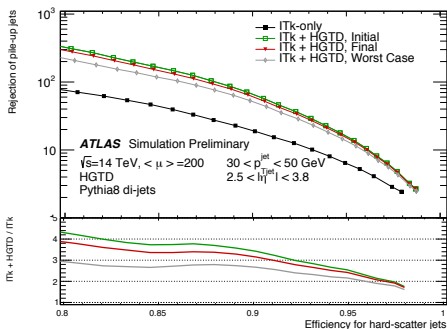
- ▶ Timing information:

$$\frac{|t - t_0|}{\sigma_t} < 2$$

Pileup jet rejection

- ▶ Tagging pileup jets
- ▶ Fraction of p_T of a jet coming from PV tracks:

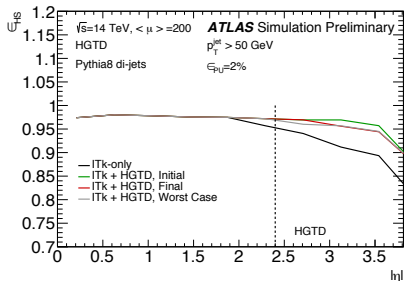
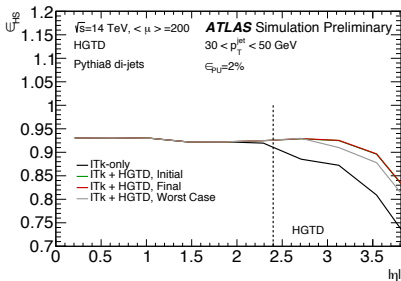
$$R_{p_T} = \frac{\sum p_T^{\text{trk}}(\text{PV}_0)}{p_T^{\text{jet}}}$$



- ▶ Improving id of PV0 tracks improves the discrimination power of R_{p_T}
- ▶ Up to a factor of 4 higher pu-jet rejection with the use of timing information
- ▶ More robust pileup rejection

Hard-scatter jet efficiency

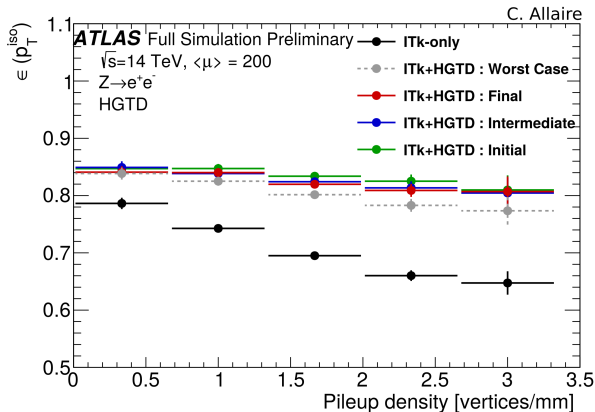
- ▶ Tagging of jets coming from the HS vertex
- ▶ Also using R_{p_T}
- ▶ Fixed pileup-jet efficiency of 2% (rejection factor of 50)



- ▶ The HGTD recovers the 10-30% drop in efficiency observed in the forward region.
- ▶ Allows to maintain similar pileup-jet suppression performance as in the central barrel.

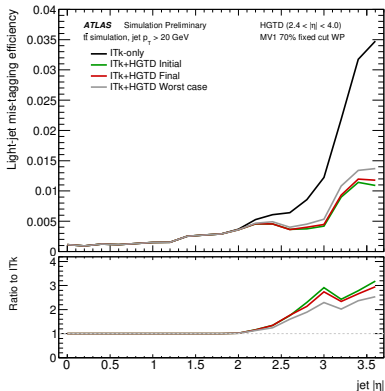
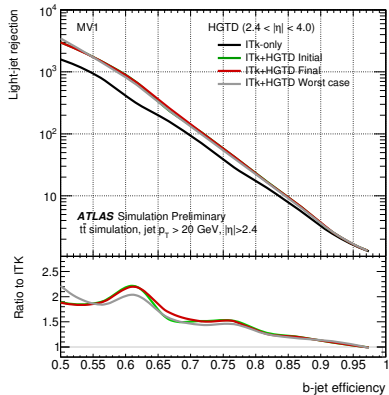
Lepton Isolation

- ▶ The HGTD can be used to assign a time to leptons in the forward region.
- ▶ **Isolation efficiency**: probability that no track with $p_T > 1$ GeV is reconstructed within $\Delta R < 0.2$ of the lepton track.



- ▶ Efficiency above 80% even at higher pileup density

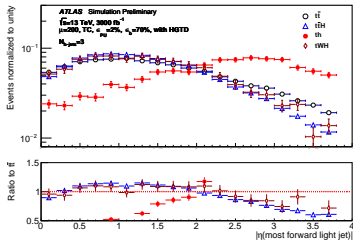
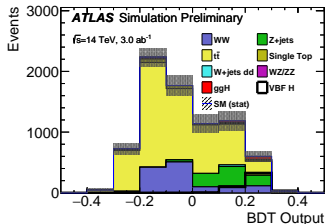
Heavy-flavour tagging



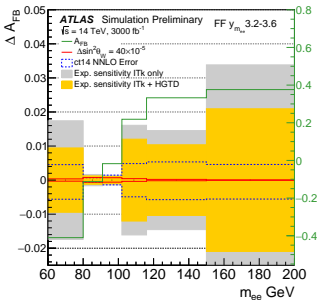
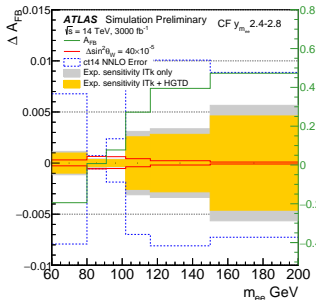
- ▶ Addition of the HGTD removes the majority of pileup tracks from the track selection.
- ▶ For a b-tagging efficiency of 70%(85%), the light-jet rejection for MV1 is increased by approximate factors 1.5 (1.2)
- ▶ The improvement could be higher in processes with more forward b-jets.

Impact in Analyses

VBF $H \rightarrow WW^*$ $\sim 8\%$ improvement



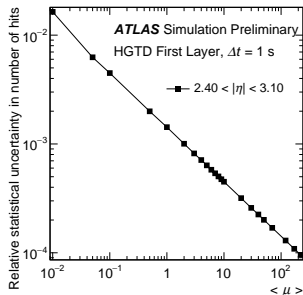
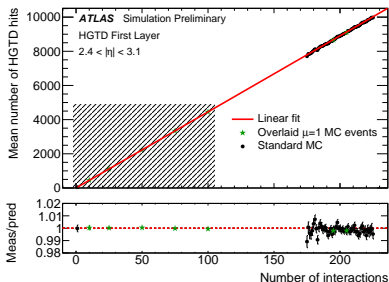
tH sensitivity:
 Improved b-tagging
 + PU rejection \rightarrow
 13% improvement

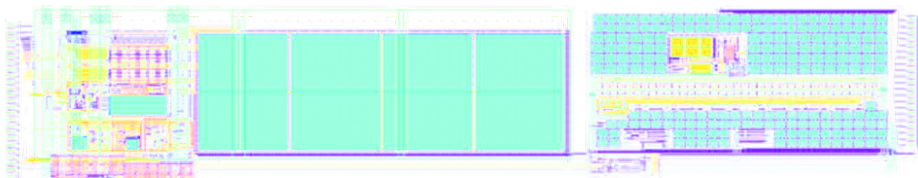


Weak mixing angle
 sensitivity:
 Improved lepton isolation \rightarrow
 13% improvement

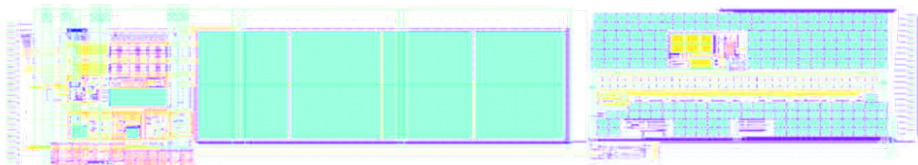
Luminosity measurement

- ▶ The luminosity uncertainty could limit the accuracy of some high precision measurements at the HL-LHC
- ▶ Need measurement as precise as in Runs I & II (currently 2.4%)
- ▶ Key characteristics of HGTD:
 - ▶ Fast signals $\rightarrow N_{hits}$ per bunch-crossing
 - ▶ High granularity \rightarrow low occupancy $\rightarrow \langle N_{hits} \rangle \propto \langle pp_{int} \rangle$
- ▶ Unbiased and high statistics per-BC measurement, available online and offline.





Detector Design



Time Resolution

Contributions to the timing resolution:

$$\sigma_T^2 = \sigma_S^2 + \sigma_{TW}^2 + \sigma_{jitter}^2 + \sigma_{clock}^2$$

▶ σ_S

- ▶ Landau fluctuations in the energy deposits of the particles
- ▶ non-uniformity of the energy deposit along the particle path; depends on the sensor thickness

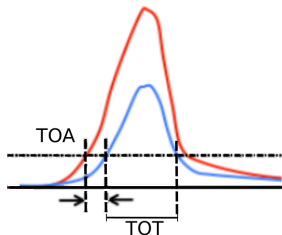
Time Resolution

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▶ σ_S

▶ $\sigma_{TW}^2 = \left[\frac{V_{th}}{S/t_{rise}} \right]_{RMS} \propto \left[\frac{N}{dV/dt} \right]_{RMS}$



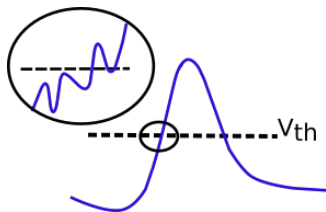
- ▶ Variations due to differences in the amplitude of the signal.
- ▶ Expected to be negligible after applying an offline correction based on measuring the TOT.

Time Resolution

Contributions to the timing resolution:

$$\sigma_T^2 = \sigma_S^2 + \sigma_{TW}^2 + \sigma_{jitter}^2 + \sigma_{clock}^2$$

- ▶ σ_S
- ▶ $\sigma_{TW}^2 = \left[\frac{V_{th}}{S/t_{rise}} \right]_{RMS} \propto \left[\frac{N}{dV/dt} \right]_{RMS}$
- ▶ $\sigma_{jitter}^2 = \frac{N}{dV/dt} \sim \frac{t_{rise}}{S/N}$



Variations due to noise in the signal

Time Resolution

Contributions to the timing resolution:

$$\sigma_T^2 = \sigma_S^2 + \sigma_{TW}^2 + \sigma_{jitter}^2 + \sigma_{clock}^2$$

- ▶ σ_S
- ▶ $\sigma_{TW}^2 = \left[\frac{V_{th}}{S/t_{rise}} \right]_{RMS} \propto \left[\frac{N}{dV/dt} \right]_{RMS}$
- ▶ $\sigma_{jitter}^2 = \frac{N}{dV/dt} \sim \frac{t_{rise}}{S/N}$
- ▶ σ_{clock}^2 contribution from the clock distribution
 - ▶ High Frequency: bunch to neighbouring bunch 'jitter'
 - ▶ Low frequency: drift over longer periods (~ 1 ms), can be corrected offline with calibration
 - ▶ Expected to be below 10 ps in total

Time Resolution

Contributions to the timing resolution:

$$\sigma_T^2 = \sigma_S^2 + \sigma_{TW}^2 + \sigma_{jitter}^2 + \sigma_{clock}^2$$

▶ σ_S

▶ $\sigma_{TW}^2 = \left[\frac{V_{th}}{S/t_{rise}} \right]_{RMS} \propto \left[\frac{N}{dV/dt} \right]_{RMS}$

▶ $\sigma_{jitter}^2 = \frac{N}{dV/dt} \sim \frac{t_{rise}}{S/N}$

▶ σ_{clock}^2 contribution from the clock distribution < 10 ps

Additional contributions from TDC expected to be negligible.

Time Resolution

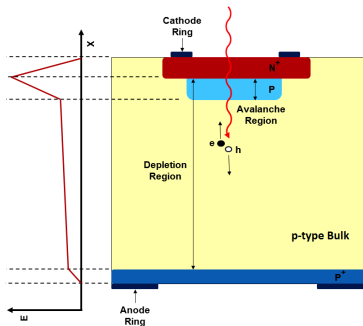
Contributions to the timing resolution:

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- ▶ σ_S
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- ▶ σ_{clock}^2 contribution from the clock distribution < 10 ps

Total time resolution per track = $\sigma(hit)/\sqrt{N_{hits}}$ goal < 30 ps

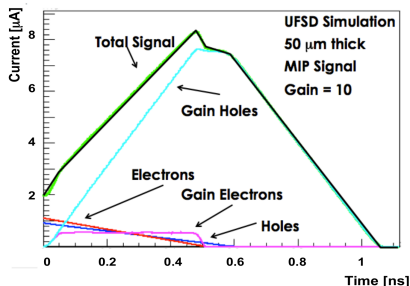
Low Gain Avalanche Diode (LGADs)



- ▶ n-on-p planar silicon detectors
- ▶ A thin highly-doped p-layer provides an internal gain (10-50)
- ▶ lower noise amplification improves S/N
- ▶ excellent timing resolution

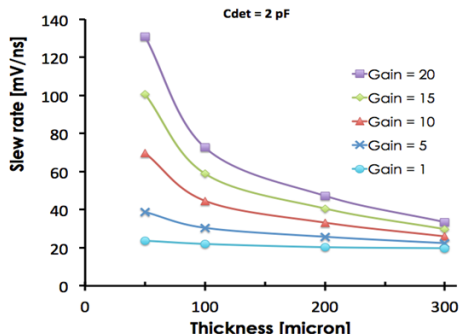
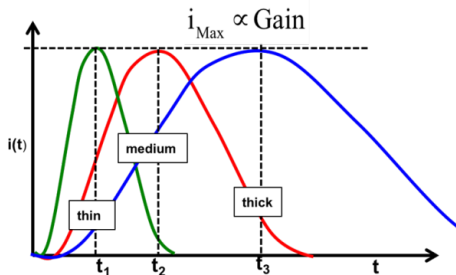
LGAD signal

- ▶ Key aspect: rise time (t_{rise})
- ▶ $t_{rise} \sim 0.5$ ns
- ▶ Smaller rise time from:
 - ▶ thinner pads
 - ▶ larger gain



LGAD Gain

Gain (g) = charge of LGAD wrt diode

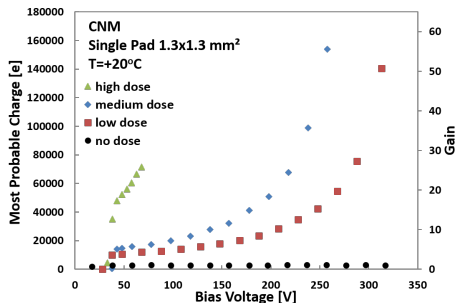


- ▶ Independent of the thickness
- ▶ $50 \mu\text{m}$ is baseline and $35 \mu\text{m}$ under study
- ▶ Depends on the characteristics of the additional p-layer

LGAD: gain vs bias voltage

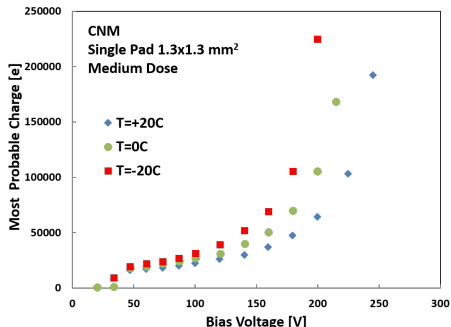
CNM (Barcelona) non-irradiated sensors

Various dopings



- ▶ The gain increases with doping
- ▶ Breakdown voltage is lower with higher dose
- ▶ Target gain $\sim 10 - 20$

Different temperatures



Operation at low temperature will allow:

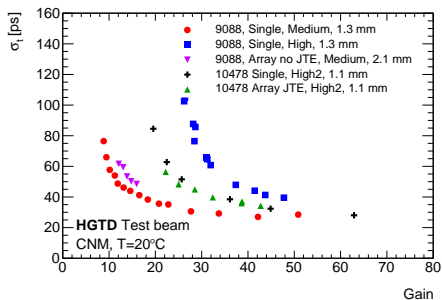
- ▶ higher gain
- ▶ at lower bias voltage
- ▶ reduced leakage current after irradiation

Target $\sim -30^\circ\text{C}$

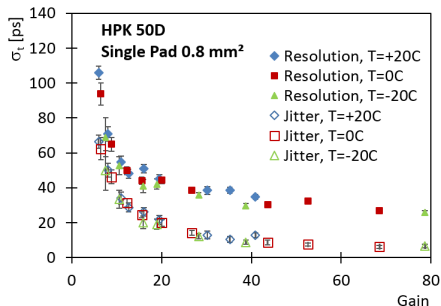
LGAD: time resolution vs gain

CNM (Barcelona) and HPK (Hamamatsu) non-irradiated sensors

Room temperature - CNM



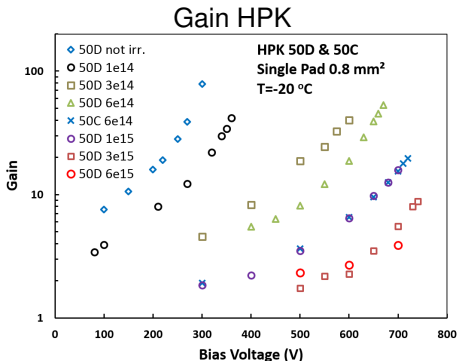
Temperature dependence - HPK



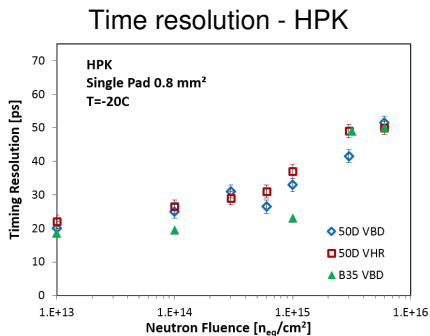
- ▶ Time resolution of 30 ps achieved for CNM and HPK sensors
- ▶ Jitter decreases with gain
- ▶ Limited by non-uniformity in energy deposits (σ_s)

LGAD performance after irradiation

- ▶ Loss of doping in the gain layer → degradation of gain
- ▶ faster signal
- ▶ increase of leakage current (up to a few μA)



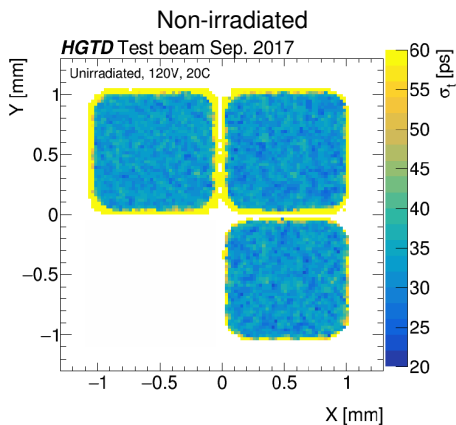
- ▶ Small gain (from bulk) after $10^{15} n_{eq}/cm^2$
- ▶ need to increasing the bias voltage



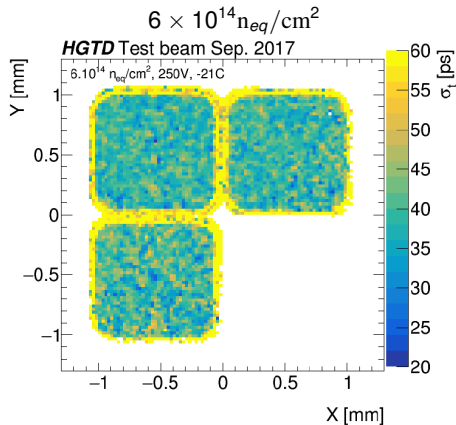
- ▶ $\sigma_t < 50$ ps up to $5 \times 10^{15} n_{eq}/cm^2$
- ▶ bias voltage at 10% below break down

Test-beam results: time resolution

- ▶ September 2017 test beam with 120 GeV pions at CERN-SPS
- ▶ CNM 2×2 arrays, each pad $1.063 \times 1.063 \text{ mm}^2$
- ▶ Test-beam 2016 paper available in [arxiv 1804.00622](https://arxiv.org/abs/1804.00622)



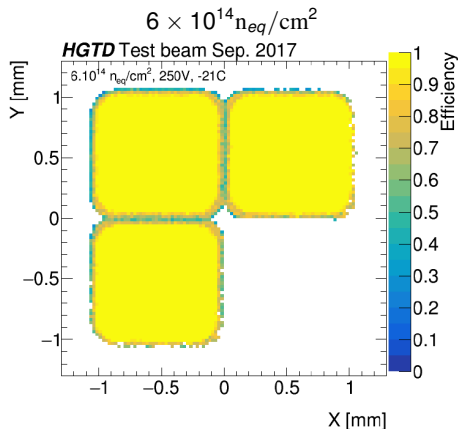
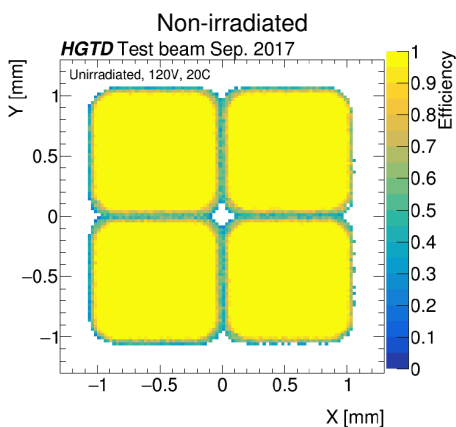
Average $\sigma_t \sim 30 \text{ ps}$



Average $\sigma_t \sim 40 \text{ ps}$

Test-beam results: efficiency

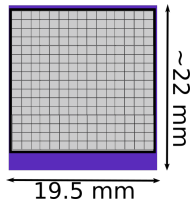
- ▶ CNM 2×2 arrays, each pad $1.063 \times 1.063 \text{ mm}^2$
- ▶ September 2017 test beam with 120 GeV pions at CERN-SPS



- ▶ Negligible inefficiency in the centre of the pads.
- ▶ Interpad area is not a dead region
- ▶ Also: cross-talk mostly negligible/ $\sim 5\%$ in irradiated sensors

ALTIROC ASIC

- ▶ The LGAD sensors will be read out by the ALTIROC
- ▶ specific ASIC designed for the HGTD
 - ▶ collaboration between Omega (design) and LAL (characterisation/test-beam)
- ▶ Bump-bonded to the sensor, it will read out 225 channels



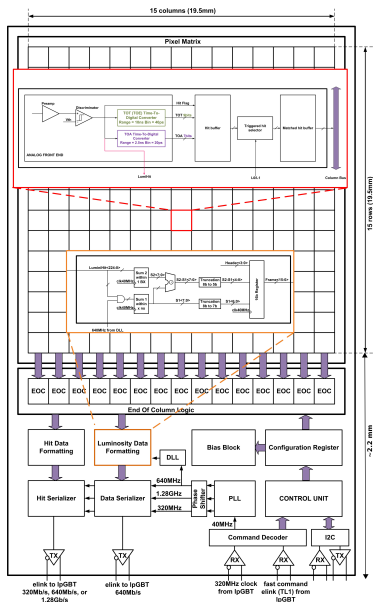
Requirements:

- ▶ Keep the excellent time resolution of the LGADs, $\sigma_{el} < 25$ ps
- ▶ Cope with a trigger latency of 10/35 μ s for L0/L1 trigger
- ▶ TDC conversion within 25 ns
- ▶ Power consumption constrained by cooling power (sensors at -30°C)
- ▶ radiation hard

Development:

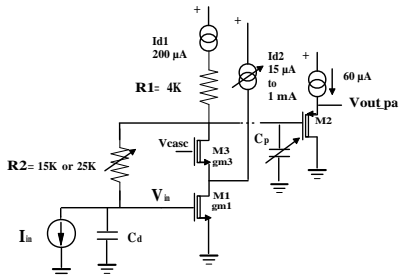
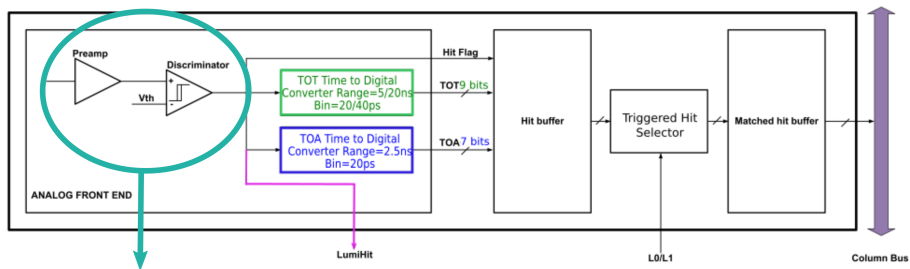
- ▶ ALTIROC0 single channel analog readout
- ▶ ALTIROC1 5×5 analog + digital channel readout

ASIC architecture



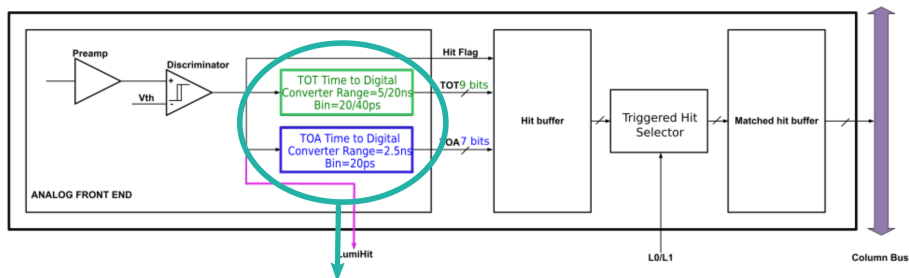
- ▶ single pixel readout (15×15)
- ▶ luminosity formatting block
- ▶ end-of-column logic
- ▶ off-pixel electronics:
 - ▶ Handling of input/output signals to peripheral electronics
 - ▶ clock distribution

Single-pixel architecture



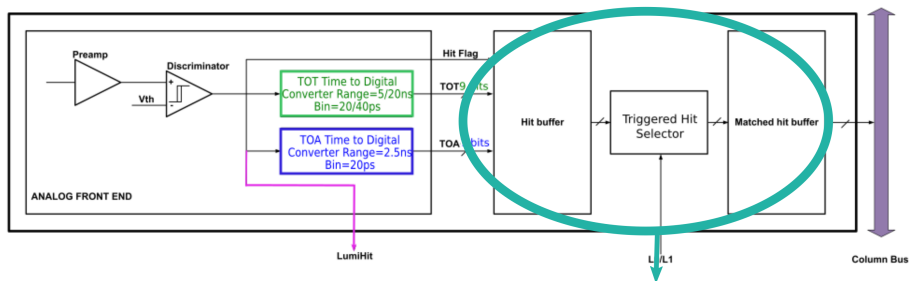
- ▶ Baseline: voltage sensitive preamplifier
- ▶ C_p to vary the signal speed
- ▶ Optimise t_{rise} to match the drift time of the sensor (0.5-1) ns to minimise jitter
- ▶ Fixed threshold discriminator
- ▶ Tested in ALTIROC0

Single-pixel architecture



- ▶ Time Of Arrival TDC (20 ps bin/2.5 ns range)
- ▶ Time Over Threshold TDC (40 ps bin/20 ns range)
- ▶ signal is also sent to the luminosity formatting unit
- ▶ To be tested in ALTIROC1

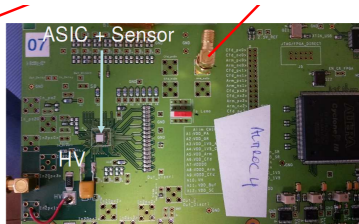
Single-pixel architecture



- ▶ store hit information until trigger
- ▶ select hit
- ▶ store until transfer

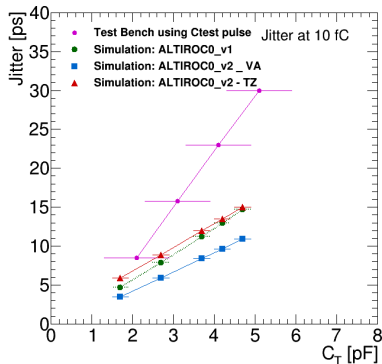
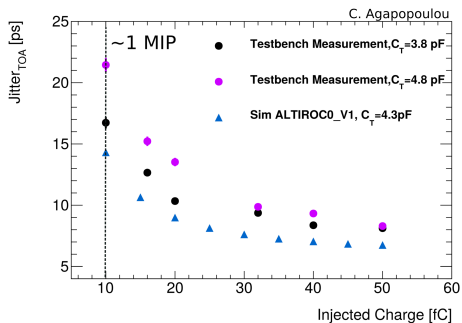
ALTIROC0

- ▶ single pixel readout:
 - ▶ preamplifier
 - ▶ discriminator
- ▶ 2×2 independent channels
- ▶ Voltage/*VPA* and transimpedance/*TZ* studied
- ▶ Alone / bump-bonded to sensor
- ▶ Full layout simulation test-bench/test-beam



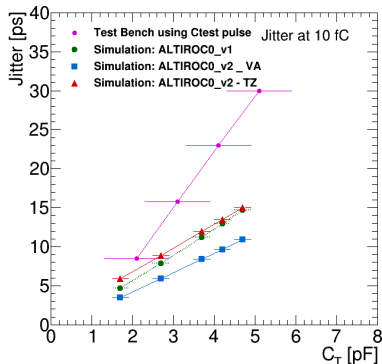
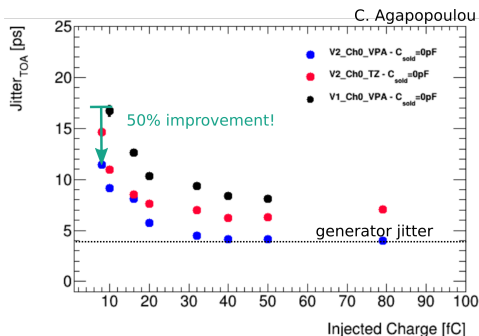
Preamplifier Jitter

- ▶ First design iteration: simulated/measured jitter in VPA below 15/25 ps for 1 MIP and $C_T < 5$ pF



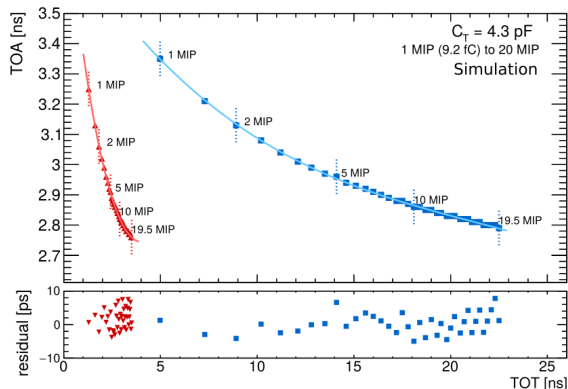
Preamplifier Jitter

- ▶ First design iteration: simulated/measured jitter in VPA below 15/25 ps for 1 MIP and $C_T < 5$ pF
- ▶ Second iteration with a faster preamplifier: achieved 8 ps jitter for $C_T \sim 2.8$ pF 50% lower than before!
- ▶ Should be below ~ 15 ps even for higher C_T according to simulation
- ▶ Higher jitter for TZ



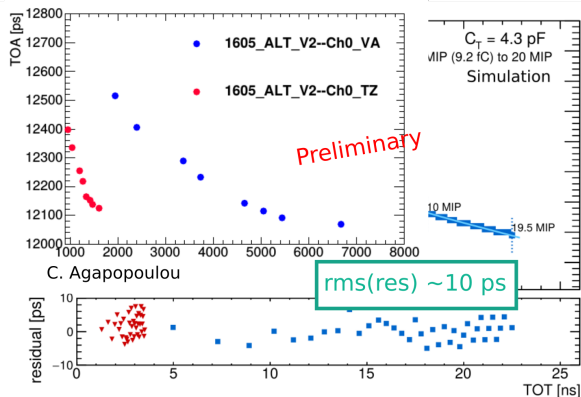
Time Walk correction

- ▶ Using measurement of the TOT (estimator of the pulse amplitude)
- ▶ Expected residual difference between simulation and measurement < 10 ps
- ▶ Voltage/VPA and transimpedance/TZ under study
- ▶ TOT excursion of the TZ is much shorter (as expected)



Time Walk correction

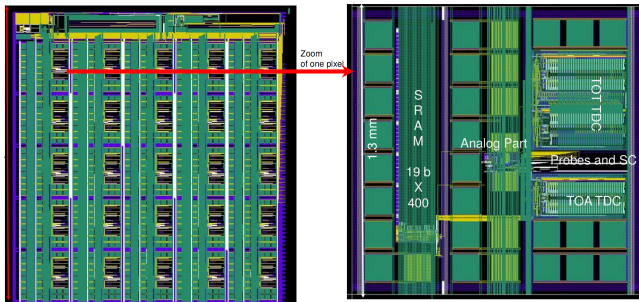
- ▶ Using measurement of the TOT (estimator of the pulse amplitude)
- ▶ Expected residual difference between simulation and measurement < 10 ps



- ▶ ALTIROC0 showed good performance by itself but suffered from coupling that affected the TOT measurement when connected to the sensor.
- ▶ studies ongoing

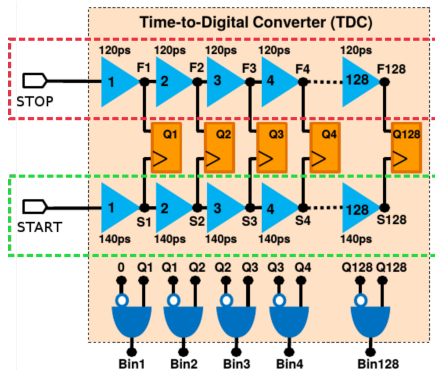
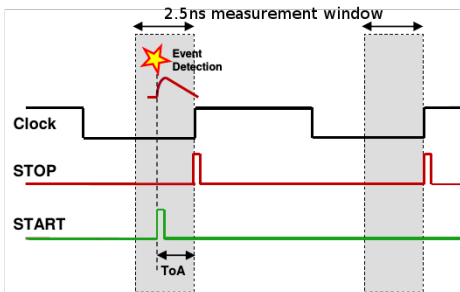
ALTIROC1

- ▶ 5×5 pixels
- ▶ Single-pixel readout:
 - ▶ TOA-TDC and TOT-TDC
 - ▶ simple memory (not final) and serializer
- ▶ Off-pixel:
 - ▶ phase shifter
- ▶ Testing to begin at the end of October 2018
- ▶ Irradiation testing



Time-to-Digital Converter

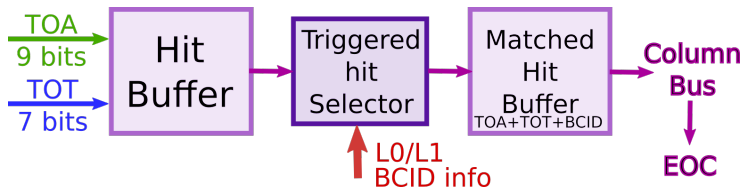
- ▶ Achieves a **20 ps resolution** by combining two lines of fast (120 ps) and slow (140 ps) cells
- ▶ Vernier delay line configuration with a **reverse START-STOP** scheme
- ▶ **Power saving**: no consumption if no hit
- ▶ Maximum conversion time of 25/28 ns for the TOA/TOT TDCs (preliminary sim.).



Count the number of cells it takes for the stop signal to surpass the start signal.

Single pixel memory

Temporarily store hit data and select hits associated to a trigger.

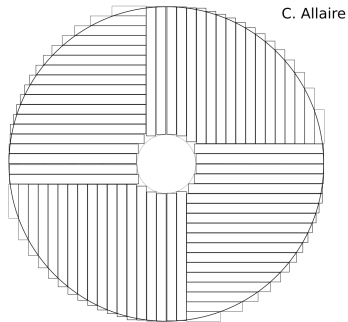
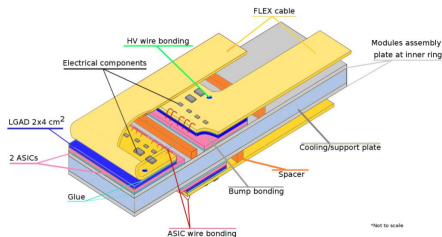


Baseline design is to use full buffering, storing TOA+TOT/hit flag:

- ▶ Handle 10/35 μ s latency for L0/L1 trigger
- ▶ Small space
- ▶ Limited power consumption
- ▶ SEU
- ▶ Alternative design: partial buffering

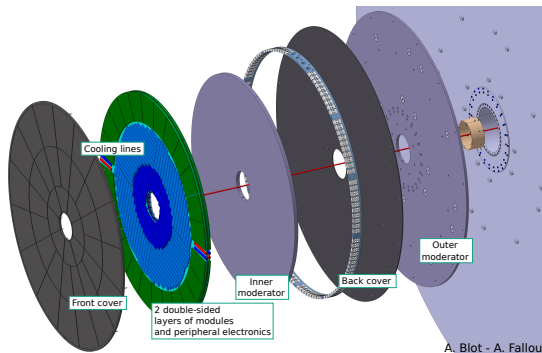
HGTD module

- ▶ sensor bump-bonded to 2 ASICs
- ▶ wire-bonded to a flex cable (input/output and power)
- ▶ placed on support stave



Highly optimised read-out row geometry

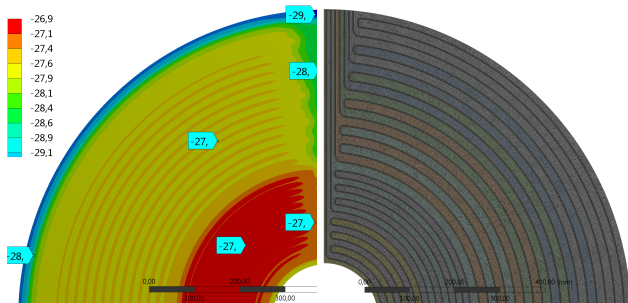
Mechanical support



Design challenges:

- ▶ Strict spatial constraints:
 - ▶ Thickness in Z within 75 mm
 - ▶ Allow space for ITk services at $R \sim 1$ m
 - ▶ Cooling services
- ▶ Thermal isolation: covers must be above condensation temperature (~ 17 °C)
- ▶ Weight ~ 350 kg per endcap

CO₂ cooling



J. Bonis-A. Fallou

Several challenges:

- ▶ LGAD sensors need to be kept at low temperature at all times ($-30\text{ }^{\circ}\text{C}$)
- ▶ CO₂ cooling will be used
- ▶ Finite element analysis: temperature distribution of $(27 \pm 1)\text{ }^{\circ}\text{C}$
- ▶ possible to have the vessel walls $> 18\text{ }^{\circ}\text{C}$ using heaters

Summary

- ▶ The HGTD is a Phase-II upgrade ATLAS project that will provide timing capability in the forward region.
- ▶ Compromise in the detector layout:
 - ▶ spatial/monetary constrains
 - ▶ goal to guarantee 3 hits per track for smaller radius (high η) and ~ 30 ps resolution per track
- ▶ Performance studies:
 - ▶ have shown potential of having timing information in the forward region to improve pileup rejection
 - ▶ more complex studies could show further impact in analyses
- ▶ Aspects of the detector design to be demonstrated:
 - ▶ LGAD's radiation hardness needs to be tested up to $4.5 \cdot 10^{15} \text{ n}_{eq}/\text{cm}^2$ ($1.5 \cdot 10^{15} \text{ n}_{eq}/\text{cm}^2$ tested so far)
 - ▶ validation of ASIC's demanding performance with a TDC, connected to a sensor (ALTIROC1)
 - ▶ optimisation of services given the small space available

- ▶ **Technical Proposal** successfully reviewed by LHCC in June 2018
- ▶ Next major step: submission of the Technical Design Report by April 2019, where the technical feasibility of the detector should be demonstrated

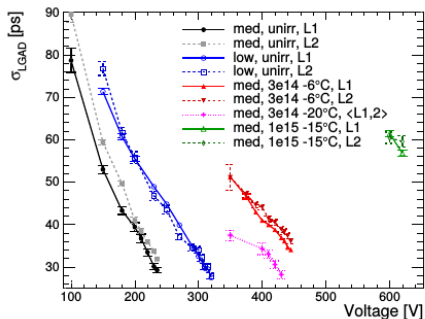
BACK UP

Overview of test beam results

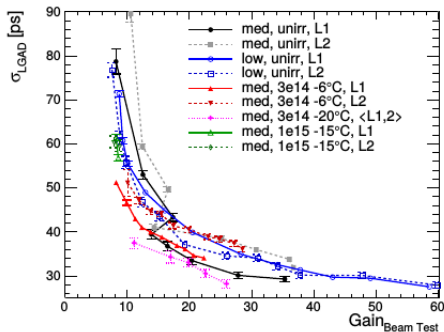
- ▶ Several test beam campaigns since 2016 (sensors from CNM and HPK).
- ▶ Achieved time resolution below 30 ps

CNM - 45 μm thick single pads¹

σ_t vs V_{bias}



σ_t vs gain



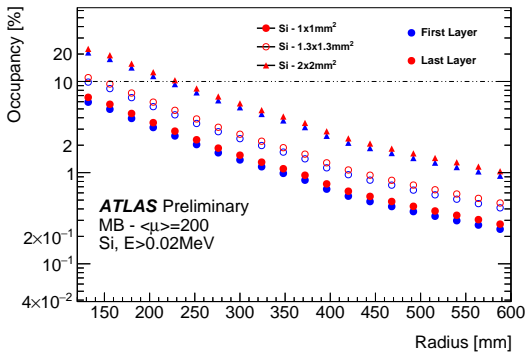
- ▶ Strong decrease of σ_t with V_{bias} ($\sigma_t < 30\text{ps}$ at 235/320 V in non-irrad. sensors)
- ▶ Irradiated sensors tested at different temperatures.
- ▶ Decrease of σ_t with gain. **Studies point to a safe gain of 10-20.**

¹results from J. Lange et al.; similar results in sensors from FBK

Pixel Size

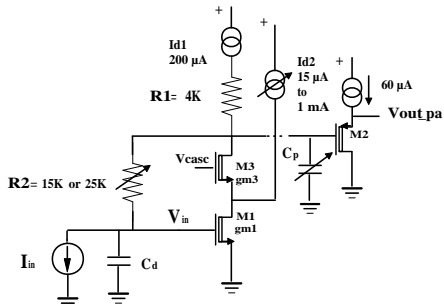
The definition of the size of the pixel is a result of several considerations, mainly:

- ▶ The need to keep occupancy low (below 10%)
- ▶ A small detector capacitance reduces noise, $C = \epsilon_r \epsilon_0 A/w$

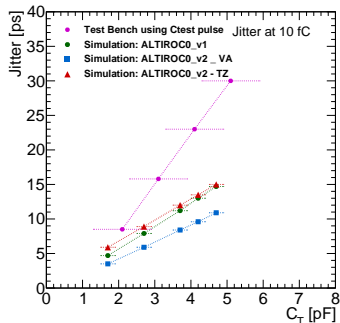
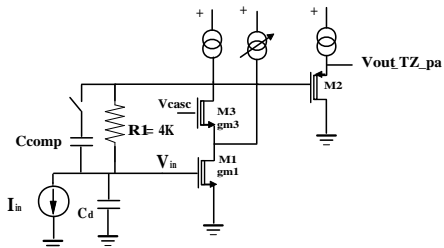


Voltage/Transimpedance preamplifier: schematics

Voltage Preamplifier

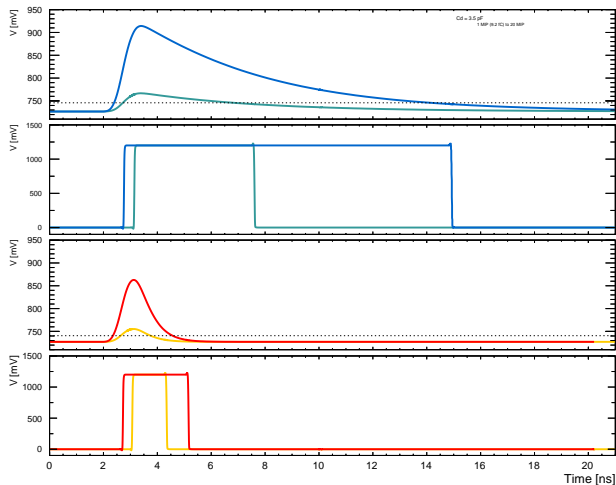


Transimpedance Preamplifier



- ▶ Difference btw measurement and simulated jitter attributed to different noise
- ▶ Lower jitter in v2
- ▶ Jitter in TZ larger than in VPA

Voltage/Transimpedance preamplifier: pulse simulation



- ▶ TZ preamplifier gives a faster, lower amplitude pulse than VPA.

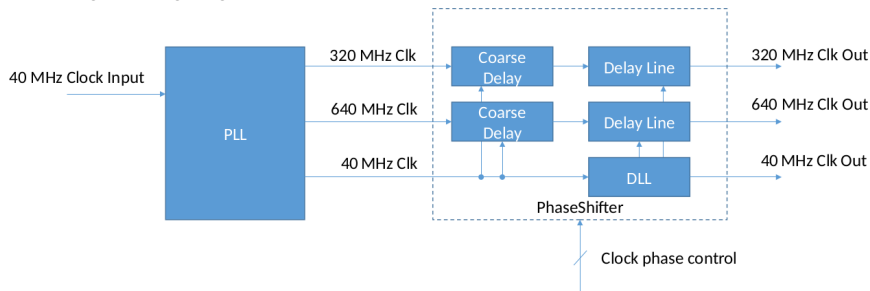
Off-pixel electronics - Phase shifter

The inner clocks of the ASIC have to be in phase, with an accuracy ~ 100 ps, in order to:

- ▶ ensure the correct time conversion of the TDC
- ▶ correctly adjust the time windows necessary to measure the luminosity

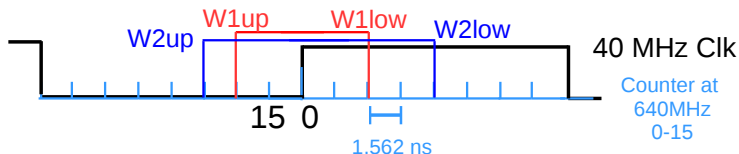
Characteristics:

- ▶ Receives clocks at 40, 320 and 640 MHz from the PLL
- ▶ Output phase adjusted to a step smaller than 100 ps
- ▶ Additional jitter below 5 ps
- ▶ Estimated power consumption around 10 mW
- ▶ Design is ongoing



Off-pixel electronics - Luminosity

- ▶ \mathcal{L} is linearly proportional to N_{hits}
- ▶ Non-linearities arise from:
 - ▶ double hits \rightarrow low occupancy
 - ▶ background noise (*afterglow*) \rightarrow compare N_{hits} in a smaller and wider time window around the BC



- ▶ Two time windows, $W2 > W1$
- ▶ Rising and falling edges of both windows are tunable
- ▶ Transmit the sum of hits per ASIC for each BC
- ▶ Only for ASICs at $R > 320$ mm
- ▶ The sum over ASICs is computed in 64 regions and saved.